



Technical Note

Emptying Operation of Water Supply Networks

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Abstract: Recently, emptying processes have been studied in experimental facilities in pipelines, but there is a lack regarding applications in actual pipelines, which permits establishing the risk of collapse because of sub-atmospheric pressure occurrence. This research presents a mathematical model to simulate the emptying process of water supply networks, and the application to a water emptying pipeline with nominal diameter of 1000 mm and 578 m long which is located on the southern of Cartagena, Bolívar Deparment, Colombia. In the application, both pipes and the air valve data manufacturer were considered. The behavior of all hydraulic and thermodynamic variables is considered. Results show that is crucial to know sub-atmospheric pressure values to prevent the collapse of the pipeline. The application of the mathematical model confirms that the hydraulic system is well designed depending on air valve sizes and maneuvering of drain valve.

Keywords: air-water; air valves; draining; emptying; transient flow; pipelines

1. Introduction

Trapped air can be introduced in water supply networks affecting the water behaviour during operational stages [1,2]. If trapped air is compressed, pressure surges occur [3,4]; in contrast, when it is expanded, then negative pressures are reached [5]. To avoid these situations, air valves should be installed along pipe systems since these devices relieve transient events through expelled/admitted air [6,7].

Researchers have analyzed the consequences of transient events in pipelines in the following situations: during the filling process [3,4,8,9], at pumping stations [10,11], analyzing the propagation of air pockets [12], in valve closures [11], and by using protection devices [13,14]. The authors have developed a mathematical model to analyze the emptying process using experimental facilities [5,15], which was validated for a single pipe at the Universitat Politècnica de València, Spain [15] and for a pipeline of irregular profile at the University of Lisbon, Portugal [5]. The main hydraulic and thermodynamic variables (absolute pressure, water velocity, and length of the emptying columns) were measured during the experiments. Figure 1 presents the used experimental facilities.

However, there is a lack regarding the application of the emptying process in actual pipelines that can be used for engineers to plan the process. In water supply networks, emptying maneuvers are required [5]. Knowing the behavior of transient flow, both water and air phase are important in order to simulate the emptying process; this is because the water flow will be replaced by the air flow. The emptying process starts when drain valves are opened, and trapped air pockets are immediately expanded and values of sub-atmospheric pressure are reached. Water velocities should be varied from 0.3 to 0.6 m/s to do an appropriate operation [7], and air valves for vacuum protection should be installed adequately along of pipelines [5,15]. Air valves should open to admit an adequate quantity of air flow into the installation with a similar ratio than water flow in order to prevent sub-atmospheric

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pressure conditions. A maximum differential pressure of 34 kPa (5 psi) is recommended during the transient event [6]. However, if air valves are not installed or failed during the process, then the hydraulic system can collapse depending on the values of the sub-atmospheric pressure, and the installation conditions (e.g., soil in natural conditions, type of backfill, and cover depth).



Figure 1. Experimental facilities to validate the emptying process: (**a**) single pipe (Universitat Politècnica de València, Spain). (**b**) pipeline of irregular profile (University of Lisbon, Portugal).

Pipe manufacturers suggest selecting the stiffness pipe as a function of the lowest value of sub-atmospheric pressure and others conditions of the pipe installations. Engineers select the stiffness class pipe based on their experiences. Another design feature is the selection of the air valve size for vacuum protection. The bigger the air valve size, the greater the protection of the system reached [6]. If air valves are improperly sized, the hydraulic event can damage not only the pipeline but also protection devices [1,16]. Drain valves maneuvers should be considered during the emptying process.

This research presents the mathematical model developed by the authors [5,15] to analyze the emptying process, which was applied to the Ciudad del Bicentenario pipeline located in Cartagena, Bolívar Department, Colombia, in order to show the behavior of hydraulic and thermodynamic variables. The mathematical model can be used for engineers to conduct a water emptying process in pipelines in the design and planning stages to avoid the collapse of pipe systems.

2. Pipeline Description

The Ciudad del Bicentenario pipeline is located in the southern of the city of Cartagena, Bolívar Department, Colombia (see Figure 2). The company Aguas de Cartagena (Cartagena, Colombia) provided the entire information regarding the pipeline [17].

Figure 3 shows the scheme of the analyzed pipeline, which is located between chainages from K2 + 360 m to K2 + 940 m. It is configured as a Glass-Reinforced Plastic (GRP) pipeline with nominal diameter of 1000 mm, 580 m long, pressure class of PN 10, and stiffness class of SN 5000 [18]. Slope branches vary in a range from 0% to 6.9%. The system presents the emptying column No. 1 (chainages from K2 + 360 m to K2 + 620 m), and the emptying column No. 2 (chainages from K2 + 940 m to K2 + 620 m).

Three air valves were installed along the pipeline with nominal diameter of 100 mm (Type 9000-Pam manufacurer). They are located at chainages K2 + 360 m, K2 + 700 m, and K2 + 940 m (see Figure 3). Air valves should work in subsonic flow (-0.3 bar $< \Delta P < 0$) during the emptying process [6,16]. Using the formulation presented by Wylie and Streeter [13], the inflow discharge coefficient (C_{adm}) was calibrated with a value of 0.68 to get similar values to the data provided by the Pam manufacturer (Derbyshire, UK) [19] as shown in Figure 4.

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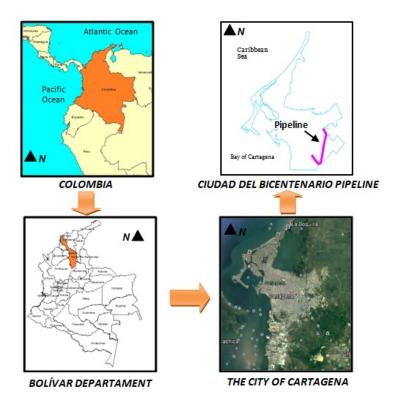


Figure 2. Location of the Ciudad del Bicentenario pipeline.

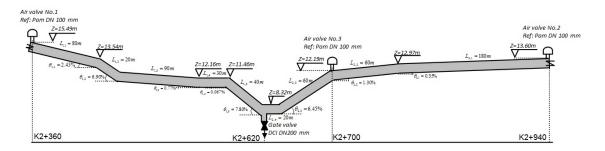
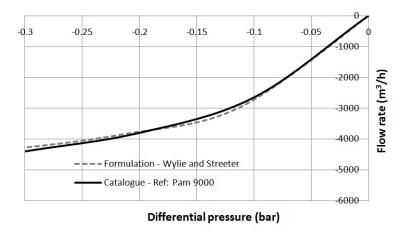


Figure 3. Profile—Ciudad del Bicentenario pipeline.



 $\textbf{Figure 4. Characteristics of the air valve} \\ - \text{Type 9000 Pam manufacturer.}$

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A Ductile Cast Iron (DCI) gate valve with a nominal diameter of 200 mm was installed at chainage K2 + 620 m to drain the hydraulic system, with a resistance coefficient (R_v) of 0.67 ms²/m⁶. A synthetic maneuver was considered with an opening time of 200 s.

3. Application of the Mathematical Model

The emptying process was modeled based on formulations developed by the authors considered as the most critical condition when the pipeline is completely filled since it produces the lowest value of the sub-atmospheric pressure [5,15]. The mathematical model uses the following formulations: (i) rigid model to represent the water phase behavior [3,5,15,20]; (ii) a piston flow to describe the air–water interface [3–5,21]; (iii) a polytropic equation to describe the air phase behavior [22–24]; (iv) the continuity equation of the air pocket [5,15]; and (v) the air valve characterization [13] to quantify the admitted air volume.

3.1. Equations

The corresponding equations of the hydraulic system are:

1. Mass oscillation equation applied to the emptying column 1

$$\frac{dv_{w,1}}{dt} = \frac{p_1^* - p_{atm}^*}{\rho_w L_{e,1}} + g \frac{\Delta z_{e,1}}{L_{e,1}} - f \frac{v_{w,1} |v_{w,1}|}{2D} - \frac{R_v g A^2 (v_{w,1} + v_{w,2}) |v_{w,1} + v_{w,2}|}{L_{e,1}}, \tag{1}$$

2. Emptying column 1 position

$$\frac{dL_{e,1}}{dt} = -v_{w,1} \to L_{e,1} = L_{e,1,0} - \int_0^t v_{w,1} dt, \tag{2}$$

3. Mass oscillation equation applied to the emptying column 2

$$\frac{dv_{w,2}}{dt} = \frac{p_2^* - p_{atm}^*}{\rho_w L_{e,2}} + g \frac{\Delta z_{e,2}}{L_{e,2}} - f \frac{v_{w,2} |v_{w,2}|}{2D} - \frac{R_v g A^2 (v_{w,1} + v_{w,2}) |v_{w,1} + v_{w,2}|}{L_{e,2}},$$
(3)

4. Emptying column 2 position

$$\frac{dL_{e,2}}{dt} = -v_{w,2} \to L_{e,2} = L_{e,2,0} - \int_0^t v_{w,2} dt, \tag{4}$$

5. Evolution of the air pocket 1

$$\frac{dp_1^*}{dt} = \frac{p_1^* k}{(L_1 - L_{e,1})} \left(\frac{\rho_{a,cn} Q_{a,cn,1}}{A \rho_{a,1}} - v_{w,1} \right), \tag{5}$$

Continuity equation of the air pocket 1

$$\frac{d\rho_{a,1}}{dt} = \frac{\rho_{a,nc}Q_{a,nc,1} - v_{w,1}A\rho_{a,1}}{A(L_1 - L_{e,1})},\tag{6}$$

7. Air valve 1 characterization

$$Q_{a,nc,1} = C_{adm} A_{adm} \sqrt{7 p_{atm}^* \rho_{a,nc} \left[\left(\frac{p_1^*}{p_{atm}^*} \right)^{1.4286} - \left(\frac{p_1^*}{p_{atm}^*} \right)^{1.714} \right]}, \tag{7}$$

8. Evolution of the air pocket 2

$$\frac{dp_2^*}{dt} = \frac{p_2^*k}{(L_2 - L_{e,2})} \left(\frac{\rho_{a,cn} Q_{a,cn,2} + \rho_{a,cn} Q_{a,cn,3}}{A \rho_{a,2}} - v_{w,2} \right), \tag{8}$$

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9. Continuity equation of the air pocket 2

$$\frac{d\rho_{a,2}}{dt} = \frac{\rho_{a,nc}Q_{a,nc,2} + \rho_{a,nc}Q_{a,nc,3} - v_{w,2}A\rho_{a,2}}{A(L_2 - L_{e,2})},$$
(9)

10. Air valve 2 characterization

$$Q_{a,nc,2} = C_{adm} A_{adm} \sqrt{7 p_{atm}^* \rho_{a,nc} \left[\left(\frac{p_2^*}{p_{atm}^*} \right)^{1.4286} - \left(\frac{p_2^*}{p_{atm}^*} \right)^{1.714} \right]}, \tag{10}$$

11. Air valve 3 characterization

$$Q_{a,nc,3} = C_{adm} A_{adm} \sqrt{7 p_{atm}^* \rho_{a,nc} \left[\left(\frac{p_2^*}{p_{atm}^*} \right)^{1.4286} - \left(\frac{p_2^*}{p_{atm}^*} \right)^{1.714} \right]}.$$
 (11)

It is very important to note that air valves 1 and 2 are working all the time because they are located at the ends of the pipeline. However, air valve 3 only is working when the air pocket passes through the position K2 + 700 m.

A summary at set of describes the hydraulic and thermodynamic behavior of the emptying process, which can solved for the 11 unknown variables: $v_{w,1}$, $v_{w,2}$, $L_{e,1}$, $L_{e,2}$, p_1^* , p_2^* , $\rho_{a,1}$, $\rho_{a,2}$, $v_{a,cn,1}$, $v_{a,cn,2}$ and $v_{a,cn,3}$.

3.2. Initial and Boundary Conditions

Considering the system is at rest (t=0), then initial conditions are: $v_{w,1}(0)=0$, $v_{w,2}(0)=0$, $L_{e,1}(0)=259$ m, $L_{e,2}(0)=319$ m, $p_1^*(0)=101,325$ Pa, $p_2^*(0)=101,325$ Pa, $\rho_{a,1}(0)=1.205$ kg/m³, $\rho_{a,2}(0)=1.205$ kg/m³, $v_{a,cn,1}(0)=0$, $v_{a,cn,2}(0)=0$, and $v_{a,cn,3}(0)=0$. The upstream boundary conditions are presented at chainages K2+360 m and K2+940, where the air pockets 1 and 2 are at atmospheric conditions (p_{atm}^*). The downstream boundary condition is given by the opening of the gate valve (located at chainage K2+620), where the atmospheric pressure (p_{atm}^*) is presented by the free discharge.

3.3. Gravity Term

The gravity term of the emptying column 1 is computed by:

If $L_{1,1} + L_{1,2} + L_{1,3} + L_{1,4} + L_{1,5} \ge L_{e,1} > L_{1,2} + L_{1,3} + L_{1,4} + L_{1,5}$, then:

$$\frac{\Delta z_{1}}{L_{e,1}} = \frac{L_{1,2} \sin \theta_{1,2} + L_{1,3} \sin \theta_{1,3} + L_{1,4} \sin \theta_{1,4} + L_{1,5} \sin \theta_{1,5}}{L_{e,1}} + \left(1 - \frac{L_{1,2} + L_{1,3} + L_{1,4} + L_{1,5}}{L_{e,1}}\right) \sin \theta_{1,1}, \tag{12}$$

If $L_{1,2} + L_{1,3} + L_{1,4} + L_{1,5} \ge L_{e,1} > L_{1,3} + L_{1,4} + L_{1,5}$, then:

$$\frac{\Delta z_1}{L_{e,1}} = \frac{L_{1,3} \sin \theta_{1,3} + L_{1,4} \sin \theta_{1,4} + L_{1,5} \sin \theta_{1,5}}{L_{e,1}} + \left(1 - \frac{L_{1,3} + L_{1,4} + L_{1,5}}{L_{e,1}}\right) \sin \theta_{1,2},\tag{13}$$

If $L_{1,3} + L_{1,4} + L_{1,5} \ge L_{e,1} > L_{1,4} + L_{1,5}$, then:

$$\frac{\Delta z_1}{L_{e,1}} = \frac{L_{1,4} \sin \theta_{1,4} + L_{1,5} \sin \theta_{1,5}}{L_{e,1}} + \left(1 - \frac{L_{1,4} + L_{1,5}}{L_{e,1}}\right) \sin \theta_{1,3},\tag{14}$$

If $L_{1,4} + L_{1,5} \ge L_{e,1} > L_{1,5}$, then:

$$\frac{\Delta z_1}{L_{e,1}} = \frac{L_{1,5} \sin \theta_{1,5}}{L_{e,1}} + \left(1 - \frac{L_{1,5}}{L_{e,1}}\right) \sin \theta_{1,4},\tag{15}$$

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If $L_{1.5} \ge L_{e.1} > 0$, then:

$$\frac{\Delta z_1}{L_{e,1}} = \sin \theta_{1,5}.\tag{16}$$

The gravity term of the emptying column 2 is computed by:

If $L_{2,1} + L_{2,2} + L_{2,3} + L_{2,4} \ge L_{e,2} > L_{2,2} + L_{2,3} + L_{2,4}$, then:

$$\frac{\Delta z_2}{L_{e,2}} = \frac{L_{2,2} \sin \theta_{2,2} + L_{2,3} \sin \theta_{2,3}}{L_{e,2}} + \left(1 - \frac{L_{2,2} + L_{2,3} + L_{2,4}}{L_{e,2}}\right) \sin \theta_{2,1},\tag{17}$$

If $L_{2,2} + L_{2,3} + L_{2,4} \ge L_{e,2} > L_{2,3} + L_{2,4}$, then:

$$\frac{\Delta z_2}{L_{e,2}} = \frac{L_{2,3} \sin \theta_{2,3}}{L_{e,2}} + \left(1 - \frac{L_{2,3} + L_{2,4}}{L_{e,2}}\right) \sin \theta_{2,2},\tag{18}$$

If $L_{2,3} + L_{2,4} \ge L_{e,2} > L_{2,4}$, then:

$$\frac{\Delta z_2}{L_{e,2}} = \left(1 - \frac{L_{2,4}}{L_{e,2}}\right) \sin \theta_{2,3},\tag{19}$$

If $L_{2,4} \ge L_{e,2} > 0$, then:

$$\frac{\Delta z_2}{L_{e,2}} = 0. {(20)}$$

4. Results and Discussion

The resolution of this set of differential-algebraic equations (Equations (1)–(11)) was conducted using Matlab (The MathWorks, Inc., Natick, MA, USA). In order to simulate the most critical situations, small air pocket sizes were considered. However, to avoid a numerical problem, a minimum air pocket length of 1 mm was established in water columns 1 and 2 [5]. A friction factor of 0.011 was used considering an absolute roughness k_s of 0.029 mm and a polytropic coefficient (k) of 1.2.

4.1. Absolute Pressure and Air Pocket Density

In the air pocket 1, the minimum sub-atmospheric pressure head occurs at 249.4 s with a value of 8.48 m (negative pressure of -1.85 m), which is reached after of the total opening of the gate valve (see Figure 5). On the other hand, in air pocket 2, the minimum value was 8.96 m (negative pressure of -1.37 m) at 125.1 s, which occurs because the quantity of admitted air by air valve 2 is not enough. However, when the air valve 3 starts to admit air into the system, then the absolute pressure pattern rises in the air pocket 2. At the end of the hydraulic event, emptying columns 1 and 2 reach the atmospheric conditions (p_{atm}^*). The minimum values of the sub-atmospheric pressure were checked by technical personnel during the emptying process of the pipeline.

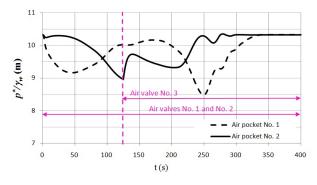


Figure 5. Evolution during the hydraulic event of the absolute pressure of the air pocket.

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The evolution of the air pocket density exhibits a parallel behaviour to the absolute pressure pattern as expected for the polytropic model (Equations (5) or (8)) and the formulation of ideal gas law [21] ($p^* = \rho_a R T_a$).

4.2. Length of the Emptying Columns

Transient phenomenon shows how the lengths of the emptying columns 1 and 2 are drained during the entire hydraulic event, as a consequence of admitted air by air valves into the system (see Figure 6). The emptying column 1 is drained completely at 338.9 s, whereas the emptying column 2 cannot drain completely due to horizontal branch of 20 m long located at the end, which drains more slowly, and part of the water column can remain inside of the installation.

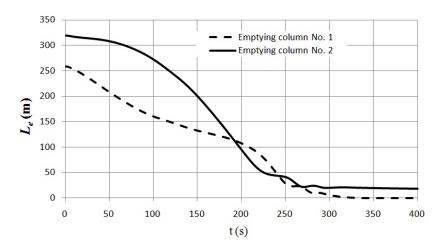


Figure 6. Evolution during the hydraulic event of the length of the emptying columns.

4.3. Water and Air Flow of Emptying Columns

Figure 7 presents the evolution of the water and air flow for the emptying column 1 where, during the first 157.2 s, the water volume drained is practically the same as the air volume admitted by the air valve 1. During this time, the sub-atmospheric pressure head values are higher than 9.17 m. The minimum value of 8.48 m (at 249.3 s) of the absolute pressure head is reached after the total opening of the gate valve ($T_m = 220$ s). The water flow surpasses the air flow generating the trough of the sub-atmospheric pressure aforementioned. At the end, some oscillations occur because the air flow is greater than water flow.

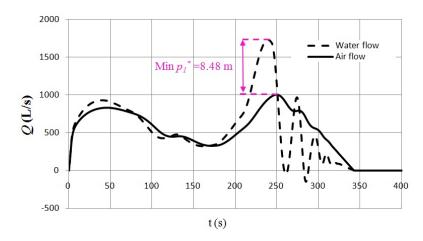


Figure 7. Evolution of the water and air flow in the emptying column 1.

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Figure 8 shows the behaviour of the water and air flow in the emptying column 2. At the beginning of the hydraulic event (from 0 s to 54 s), air valve 2 can introduce enough quantity of air volume adequately, where the water and air flow are similar with values of $325.6 \, \text{L/s}$ and $311.4 \, \text{L/s}$, respectively. Then, from $54 \, \text{s}$ to $125 \, \text{s}$, the water flow surpasses the air flow. The minimum value of $8.96 \, \text{m}$ of sub-atmospheric pressure head is reached at $125 \, \text{s}$, when air valve $3 \, \text{starts}$ to relieve the sub-amospheric pressure occurrence avoiding the risk of collapse of the installation at least until $132.7 \, \text{s}$. At $201.2 \, \text{s}$, air valves 2 and 3 cannot admit the required air volume generating another trough of sub-atmospheric pressure of $9.32 \, \text{m}$. At the end, some oscillations occur similarly to emptying column 1.

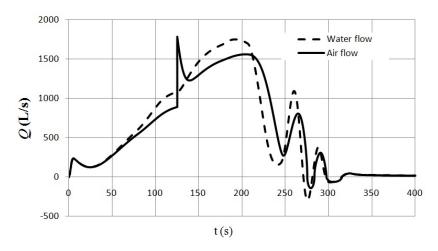


Figure 8. Evolution of the water and air flow in emptying column 2.

4.4. Risk of Pipeline Collapse

According to the pipe manufacturer, the stiffness class of a pipeline should be selected considering two parameters: (i) burial conditions, which include the soil in natural conditions, the type of backfill, and the cover depth; and (ii) the minimum value of the sub-atmospheric pressure. The analyzed GRP pipeline (Amiantit Pipe Systems, Dammam, Saudi Arabia) of nominal 1000 mm diameter and stiffness class of SN 5000 can support a sub-atmospheric pressure value of 7.78 m (negative pressure of -0.25 bar or -2.55 m) considering a cover depth of 10 m, and a typical type of backfill and a soil in natural conditions. During the emptying process, the minimum value of 8.48 m (or -0.18 bar) is reached at 249.3 s with a depth of 5.75 m according to construction drawing, which is lower than the values aforementioned. As a consequence, there is not a risk of collapse of the installation after checking that air valves and the operation of the gate valve are adequate.

Figure 9 presents the minimum values of sub-atmospheric pressure depending on the failure of air valves 1, 2, or 3. Four zones are identified. Zone *I* is presented when both the air valves are working or air valve No. 3 fails. Then, the hydraulic system is completely protected from the sub-atmospheric pressure occurrence and there is no risk of collapse. Zones *II* and *IV* are characterized for the failure of the air valves located at the ends. If air valve No. 1 fails, then air pocket 1 can cause the collapse of branch pipe 1 with a value of sub-atmospheric pressure head of 3.20 m; and if air valve No. 2 fails, then the minimum value of the sub-atmospheric pressure head is 4.90 m in branch pipe 2. The most critical condition is presented in Zone *III*, when the air valves fail. Branch pipes 1 and 2 can collapse with values of sub-atmospheric pressure head of 2.15 m and 4.18 m, respectively. Good maintenance of air valves is crucial in order to minimize risk of collapse of pipelines during the emptying process.

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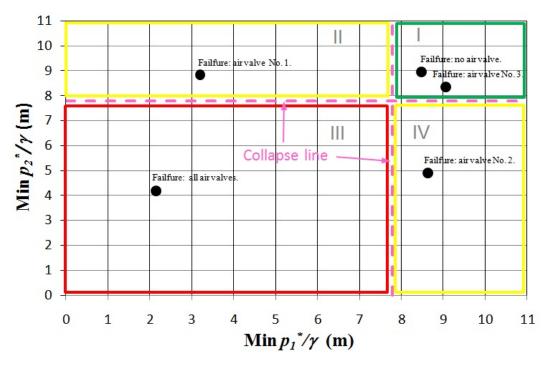


Figure 9. Sensitivity analysis regarding the failure of air valves.

5. Conclusions

This research presents both the mathematical model to simulate the emptying operation in water supply networks and the application to the Ciudad del Bicentenario pipeline located in Cartagena, Colombia. The analyzed pipeline has a nominal diameter of 1000 mm and 580 m long. The entire information about the pipeline was supplied by Aguas de Cartagena, which operates the water supply network in Cartagena, Colombia. The mathematical model gives important information regarding the main hydraulic and thermodynamic variables (water velocities, length of the water columns, air densities, absolute pressure of air pockets, and air flows).

Regarding to the application of the mathematical model, the following conclusions can be drawn:

- The mathematical model can be used for computing air valve sizes, maneuvering drain valves, and knowing the drainage time of pipelines to prevent the collapse of the hydraulic system.
- The minimum value of sub-atmospheric pressure is one of the most critical situations during the emptying process, which is adequately predicted by the mathematical model.
- Air valves should be selected appropriately along the pipe systems admitting the required air to avoid sub-atmospheric pressure conditions. If air valves have not been well sized, then extreme negative pressures are reached, which can cause the collapse of pipe systems. The mathematical model can be used to check the air valves behaviour during the emptying maneuvers in actual installations.
- The Ciudad del Bicentenario pipeline can resist the minimum value of sub-atmospheric pressure showing that there is no risk of collapse since the total volume of admitted air is similar to the volume of drained water. Both air valve sizes and the maneuver of the gate valve were adequately designed, so they can be used to empty the pipeline without risk of collapse. Annual maintenance is required for the air valves located at the ends of the installation since a failure of these devices can cause the collapse of branch pipes according to the sensitivity analysis.
- Horizontal branches in pipelines are not recommended because part of the water column can remain inside of the installation and free surface flow is presented, generating a slow drainage of the system.

This research only analyzed the risk of pipeline collapse during the emptying process. However, other sources of sub-atmospheric pressure occurrence should be analyzed (e.g., pumps' stoppages).

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Conflicts of Interest: The authors declare no conflict of interest.

Abbreviations

The following abbreviations are used in this manuscript:

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A
                                  cross-sectional area of pipe (m^2);
A_{adm}
                                  cross sectional area of the air valves (m<sup>2</sup>);
                                  inflow discharge coefficient of the air valves (-);
C_{adm}
D
                                  internal pipe diameter (m);
f
                                  friction factor (-);
                                  gravity acceleration (m/s^2);
g
                                  length of emptying columns 1 and 2, respectively (m);
L_{e,1} and L_{e,2}
L_1 and L_2
                                  total length of pipes 1 and 2, respectively (m);
L_{i,j}
                                 branch length i, j (m);
k
                                  polytropic coefficient (-);
                                  absolute pressure of air pockets 1 and 2, respectively (Pa);
p_1^* and p_2^*
                                  atmospheric pressure (Pa);
p_{atm}^*
R
                                  gas constant (J/kg/^{\circ}K);
R_{7}
                                 resistance coefficient of the gate valve (s^2/m^5);
ŧ
                                  time (s);
T_a
                                  absolute temperature of the air (°K)
                                 admitted air flow by air valves 1, 2, and 3, respectively (m^3/s);
Q_{a,nc,1}, Q_{a,nc,2}, and Q_{a,nc,3}
v_{w,1} and v_{w,2}
                                  water velocity of emptying columns 1 and 2, respectively (m/s);
\rho_{a,1} and \rho_{a,2}
                                  air density of air pockets 1 and 2, respectively (kg/m<sup>3</sup>);
                                  air density in normal conditions (kg/m^3);
\rho_{a,nc}
\rho_w
                                  water density (kg/m^3);
                                  difference elevation of water columns 1 and 2, respectively;
\Delta z_{e,1} and \Delta z_{e,2}
                                 branch slope i, j
\theta_{i,i}
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