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1 **Instrumentation and control of anaerobic digestion processes: A review and some research challenges**

2

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31 **Abstract**

32 To enhance energy production from methane or resource recovery from digestate, anaerobic digestion processes  
33 require advanced instrumentation and control tools. Over the years, research on these topics has evolved and  
34 followed the main fields of application of anaerobic digestion processes: from municipal sewage sludge to liquid  
35 – mainly industrial – then municipal organic fraction of solid waste and agricultural residues. Time constants of  
36 the processes have also changed with respect to the treated waste from minutes or hours to weeks or months.  
37 Since fast closed loop control is needed for short time constant processes, human operator is now included in the  
38 loop when taking decisions to optimize anaerobic digestion plants dealing with complex solid waste over a long  
39 retention time. Control objectives have also moved from the regulation of key variables – measured on-line – to  
40 the prediction of overall process performance – based on global off-line measurements – to optimize the feeding  
41 of the processes. Additionally, the need for more accurate prediction of methane production and organic matter  
42 biodegradation has impacted the complexity of instrumentation and should include a more detailed  
43 characterization of the waste (e.g., biochemical fractions like proteins, lipids and carbohydrates) and their  
44 bioaccessibility and biodegradability characteristics. However, even if in the literature several methodologies  
45 have been developed to determine biodegradability based on organic matter characterization, only a few papers  
46 deal with bioaccessibility assessment. In this review, we emphasize the high potential of some promising  
47 techniques, such as spectral analysis, and we discuss issues that could appear in the near future concerning  
48 control of AD processes.

49

50 **Key words:** Anaerobic digestion, organic matter, characterization, instrumentation, control, diagnosis.

51

52 **Nomenclature**

53	AD	Anaerobic Digestion
54	ADM1	Anaerobic Digestion Model N°1
55	AFM	Atomic Force Microscopy
56	BCA	Bicinchonic Acid
57	BD	Ultimate Anaerobic Biodegradability
58	BMP	Biochemical Methane Potential
59	BOD	Biochemical Oxygen Demand
60	CH <sub>4</sub>	Methane

61	CLSM	Confocal Laser-Scanning Microscopy
62	CO <sub>2</sub>	Carbon Dioxide
63	COD	Chemical Oxygen Demand
64	Da	Dalton
65	EPS	Extracellular Polymeric Substances
66	FOG	Fats, Oils, and Greases
67	FTIR	Fourier Transform Infrared spectroscopy
68	GASDM	General Activated Sludge and Digestion Model
69	GC/MS	Gas Chromatography coupled with Mass Spectroscopy
70	GISCOD	General Integrated Solid Waste Co-Digestion model
71	HA	Humic Acids
72	HPLC	High Performance Liquid Chromatography
73	HRT	Hydraulic Retention Time
74	ICA	Instrumentation, Control and Automation
75	IWA	International Water Association
76	LCFA	Long Chain Fatty Acids
77	MPR	Methane Production Rate
78	MSW	Municipal Solid Waste
79	NIRS	Near Infra-Red Spectroscopy
80	NMR	Nuclear Magnetic Resonance spectroscopy
81	OLR	Organic Load Rate
82	PLS	Partial Least Square
83	R <sup>2</sup>	Regression coefficient
84	RI <sub>4</sub>	Respiration Index 4 days
85	SEM	Scanning Electron Microscopy
86	STP	Standard conditions of Temperature and Pressure
87	S/X	Substrate to Biomass Ratio
88	TEM	Transmission Electron Microscopy
89	TKN	Total Kjeldahl Nitrogen
90	TOC	Total Organic Carbon

91	TS	Total Suspended Solids
92	VFA	Volatile Fatty Acids
93	VS	Volatile Solids
94	XPS	X-ray Photoelectron Spectroscopy
95	3D-EEM	3D Emission Excitation Matrix

96  
97

## 98 **1. Introduction**

99

100 One of the key issues for global sustainable development is the energy consumption, particularly as fossil fuels,  
101 which represents up to 80% of the global energy consumption. Moreover, fossil fuels are considered the main  
102 source of acidifying contaminants and greenhouse gasses, as well as the main factor contributing to global  
103 warming and climate change. Hence, one big challenge for this century is to develop new competitive sources of  
104 renewable energy, capable of replacing fossil fuels with a minimum impact on both the environment and society,  
105 while maintaining energy (electricity or gas) grid stability (Szarka *et al.* 2013). In this respect, alternative energy  
106 sources such as methane from organic residues must be considered.

107

108 Anaerobic Digestion (AD) is a biological process in which the organic carbon is converted through oxidation-  
109 reduction reactions to both its most oxidized state (CO<sub>2</sub>) and its most reduced form (CH<sub>4</sub>). The methane  
110 produced is an energy source that can be valorized as electricity, heat, biofuel or can be injected into the natural  
111 gas grid. In the context of a widely perceived energetic and climatic crisis, AD has become a very interesting  
112 alternative for organic waste disposal. For example, in France, wastewater treatment plant (WWTP) energy  
113 consumption is about 20 kWh per year per person equivalent, based on a 100,000 person equivalent plant. From  
114 these observations and the fact that wastewater sludge potentially contains a high amount of energy that can be  
115 recovered, it is clear that WWTPs of the future – or water resource reclamation facilities (WRRFs) as they are  
116 now called - should aim at a positive energy balance (Cao and Pawlowski 2012).

117

118

## 119 1.1 From Municipal Wastewater Solids to Industrial and Agricultural Wastes

120

121 AD has been used to stabilize municipal wastewater solids for over 80 years, probably with the first heated,  
122 mixed system being employed in Germany in 1927 (Imhoff 1938). During the last 30 years, the total number of  
123 papers on AD and industrial applications increased rapidly, mainly due to a favorable environmental policy: the  
124 Kyoto protocol (2005), national or international legislation promoting AD, special rates for selling electricity  
125 produced from biogas. The evolution of the market also led to a higher complexity of the substrates considered  
126 for AD valorization.

127

128 In the eighties, industrial wastewater treated by AD began to grow and worldwide, the overall number of  
129 anaerobic reactors treating industrial wastewater reached 2266 references in 2007 (van Lier 2008) and kept on  
130 increasing since then. The main focus of AD optimization has been about kinetics of soluble substrates,  
131 considering acetogenesis and methanogenesis as the limiting steps (Mata-Alvarez *et al.* 2000).

132

133 At the end of the eighties, AD applications focused on the conversion of solid waste began to increase. Solid  
134 wastes then included mainly municipal solid waste (MSW) and green wastes. The increasing production of solid  
135 waste combined with waste management policies aiming at reducing long-term environmental impacts of landfill  
136 disposal have created a need for alternative treatment. The use of AD to treat the organic fraction of municipal  
137 solid waste became a reality (De Baere 2000; 2008): from 3 plants in 1990 to 55 plants referenced in 2010 in  
138 Europe and at least 4 in North America today, for example. From a process control standpoint, the  
139 disintegration/hydrolysis step received considerable attention for solid waste since it is the rate-limiting step for  
140 substrates containing mainly particulates (Mata-Alvarez *et al.* 2000; Lauwers *et al.* 2013).

141

142 Concomitantly, farmers have become increasingly interested in the AD process, both as an additional source of  
143 revenue and as an alternative energy source without greenhouse gas emission to the atmosphere. AD is indeed  
144 one of the technologies that fulfil European criteria for second generation biofuel production (fuels manufactured  
145 from various types of complex organic carbon sources such as lignocellulose biomass or agricultural residues,  
146 *e.g.* manure). The case of Germany where more than 7,850 plants generate over 3.5 GW of electricity is an  
147 example or in China where more than 35 million household digesters and 25,000 digesters for agricultural  
148 residues have been deployed (Fang 2012).

149

## 150 1.2 Biodegradability, Bioavailability and Bioaccessibility

151

152 Hydrolysis rate of complex substrates has been identified for a long time as an important factor for AD  
153 modelling and process optimization (Vavilin *et al.* 1997), especially considering substrate characterization and  
154 hydrolysis kinetics. Modern dynamical models of AD are very useful for optimization of biogas production. For  
155 example, the IWA Anaerobic Digestion Model N°1 ADM1 (Batstone *et al.* 2002) has a detailed pathway  
156 description, but the model's main drawback is that it also needs detailed input variables and data that may not be  
157 available for a specific application (Astals *et al.* 2013a). Indeed, a key-point for the successful description of a  
158 bioprocess is appropriate influent characterization data (Huete *et al.* 2006; Buffiere *et al.* 2006; Kleerebezem and  
159 van Loosdrecht 2006).

160

161 Lately, three major concepts have been shown to be of prime importance to characterize organic matter  
162 biodegradation: biodegradability, bioavailability and bioaccessibility (Jimenez *et al.* 2014). Biodegradability is  
163 the ability of a substrate to be broken down by a microorganism into simpler compounds but this biodegradation  
164 is limited by molecule's bioavailability, complexity and/or toxicity. Bioavailability is defined as the direct access  
165 to the molecule to be degraded while Aquino *et al.* (2008) defined bioaccessibility as the possible access to the  
166 molecule depending on several factors such as the contact time between the substrate and the microorganism, the  
167 efficiency of hydrolytic activity or ultimately any pre-treatment applied to the waste. There is thus a notion of  
168 physical accessibility as in the case of the cellulose protection by lignin or vegetal walls acting as a barrier and  
169 needing chemical or physical break-up to make cellulose accessible to microorganisms (Motte *et al.* 2014, Reilly  
170 *et al.* 2015). Consequently, the bioavailable organic matter is included in the bioaccessible fraction such as the  
171 organic fraction able to be degraded by secreted exo-cellular enzymes (Jimenez *et al.* 2014).

172

173 In parallel, the control problem associated with anaerobic biological waste or wastewater treatment processes  
174 must involve – like in any aerobic processes – process configurations that remain robust against unpredicted  
175 perturbations (e.g., physicochemical, mechanical, etc.) and uncertainties in relation to: (a) initial conditions, (b)  
176 kinetic and hydrodynamic parameters, (c) yield coefficients, and (d) input concentrations. All these aspects  
177 strongly influence the overall objectives of instrumentation and control and are currently profoundly impacting  
178 the technical challenges and optimization criteria applied to AD processes.

179

## 180 2. Instrumentation of Anaerobic Digestion Processes

181

182 The following section first focuses on classical instrumentation that is very often encountered in practice. On-  
183 line instruments that can be used in fast closed-loop control scheme and have proven to be very useful for  
184 monitoring any type of digester will be presented first (See also Spanjers and van Lier 2006 for additional  
185 information). Next, because of the development of the solid AD process – with long residence time – some  
186 techniques that are not yet available in an on-line context will be discussed. They can indeed provide very  
187 informative measurements that can help to optimize AD plants with long solid retention time, such as those  
188 dealing with municipal or agricultural waste. Sensor dynamics are likely to be less important than static  
189 characteristics and other cost benefit considerations in most cases, as the process dynamics are seldom  
190 challenging to the sensor technologies used.

191

### 192 2.1 – On-Line Instrumentation

193

#### 194 2.1.1 Flow, Temperature, pH and ORP

195

196 Instruments to monitor gas and liquid flows are ubiquitous in wastewater treatment. For example, Harremoës *et*  
197 *al.* (1993) provided an extensive overview of liquid flow measurement techniques and pointed out the  
198 importance of proper installation for guaranteed accuracy. Measurements are based on pressure differentials  
199 resulting from restrictions (venturi, orifice plates, and meshes) placed in the flow path. In addition,  
200 electromagnetic and ultrasonic sensors can also be applied.

201

202 Temperature is a rather important variable for anaerobic digesters and temperature control is often implemented.

203 Three commonly used types of process measuring instruments are available for measuring temperature:

204 resistance thermometer, thermo-element, and thermistor.

205

206 It is normal practice to install pH electrodes in a treatment plant. Immersion of these probes in ‘sticky’ sludge  
207 has encouraged the development of different cleaning strategies: hydraulic (water spray), mechanical (brush),  
208 chemical (rinsing with cleaning agent) or ultrasonic cleaning. With these techniques, longer periods without

209 maintenance can be attained. Poor or no automatic cleaning may indeed cause problems and self-diagnosis has  
210 been integrated in advanced systems. More sophisticated set-ups include automated checks of the impedance of  
211 the diaphragm and the glass electrode, while tests performed during (automatic) calibration may be used to  
212 indicate other sensor deficiencies. Although pH is a variable that is important in all biological processes, its  
213 value is especially critical in anaerobic digestion, eventually leading to acidification and process failure. Hence,  
214 its measurement and control are important. However, in the case of wastewaters with high buffering capacity, pH  
215 measurements may be rather insensitive to indicate process changes and are therefore not advisable for process  
216 supervision and control. In such cases, they may be replaced with bicarbonate and/or alkalinity measuring  
217 systems (Di Pinto *et al.* 1990; Hawkes *et al.* 1993 and Guwy *et al.* 1997 – see also section 2.1.3).

218  
219 Oxidation-reduction potential (ORP) sensors are also sometimes installed since an increase in ORP indicates a  
220 possible presence of oxygen in the process. In this respect, it is recommended to maintain an ORP potential  
221 below -300 mV relative to a standard hydrogen electrode (depending on the wastewater characteristics) in order  
222 to not adversely affect anaerobic methanogenic archaea activity. ORP is also sometimes used to monitor sulfate  
223 reduction in digesters and H<sub>2</sub>S in the biogas through micro-aeration (Nghiem *et al.* 2014).

224  
225 As biogas formation rate is one of the most commonly monitored variables in anaerobic digestion processes, gas  
226 flow sensors are very often part of digester instrumentation. Pressure measurements can be found in AD plants  
227 as well, especially for alarm functions.

## 228 229 2.1.2 Biogas Composition

230  
231 Gas composition measurements are also required in lab processes and full-scale plants. Typically, specific gas  
232 analyzers monitor the content of a component directly and infrared absorption measurements are used to  
233 determine carbon dioxide and methane concentrations. There are several of such sensors available today in the  
234 market. It has to be kept in mind that, although not always straightforward to predict from measurements in the  
235 gas phase, the corresponding concentrations of gasses in the liquid phase are important as they represent the  
236 environment the microorganisms operate in. It is possible to use Henry's law to calculate equilibrium aqueous  
237 concentration, however it is necessary to know the gas composition and the Henry's constant for each

238 component at the required temperature and in aqueous solutions of variable ionic strength. Also, gas-liquid  
239 partitioning in digesters is very dynamic and equilibrium conditions may not be present.

240 The presence of hydrogen sulphide in the gas and the explosive character of biogas also require careful  
241 precautions. Hydrogen sulphide measurement in the gas phase may be performed by monitoring the reaction of  
242 sulphide with a Pb-strip. Subsequently, the black PbS that is produced is quantified by colorimetry. No direct on-  
243 line measurement of hydrogen sulphide in the liquid phase has been reported though. Membrane inlet mass  
244 spectrometry (Ryhiner *et al.* 1992) is another method to directly measure a large number of dissolved gasses and  
245 volatile compounds. The MS membrane probe response is often linear over very large concentration ranges. For  
246 application of thin membranes – that are required for sufficiently fast response and high sensitivity – the analyzer  
247 should be protected because of the rather high risk of membrane rupture. A fast safety shut-off system including  
248 fast pressure measurement is thus advised to be installed.

249

250 Specific hydrogen (H<sub>2</sub>) analyzers have been developed – mainly in laboratories – based for example on  
251 electrochemical cells (Mathiot *et al.* 1992). Immersible sensors have been developed to measure dissolved  
252 hydrogen concentrations directly in the liquid phase down to partial pressures of 1 Pa (10<sup>-5</sup> atm). Their reliability  
253 and long-term stability have been reported (Pauss and Nyns 1993). An inexpensive amperometric dissolved  
254 hydrogen probe has been used to determine the onset of digester failure by substrate overloading (Cord-Ruwisch  
255 *et al.* 1997). The measuring principle is based on the oxidation of hydrogen at a platinum black electrode at an  
256 adjusted potential. The current flowing to the electrode is directly related to the hydrogen concentration in the  
257 bulk liquid but H<sub>2</sub>S has to be trapped and removed before the biogas flows into the hydrogen monitor. Björnsson  
258 *et al.* (2001a) applied a hydrogen-sensitive palladium–metal oxide semiconductor (Pd-MOS) sensor in  
259 combination with a Teflon membrane for liquid-to-gas transfer for the detection of dissolved hydrogen and the  
260 monitoring of a laboratory-scale anaerobic digestion process, employing mixed sludge containing mainly  
261 food/industrial waste. The sensor gave valuable information about approaching process overload, and can serve  
262 as a good alternative for volatile fatty acids (VFA) monitoring. The sensor was stable and robust during 3  
263 months of operation, and therefore it was concluded that hydrogen sulfide, which is known to poison the Pd-  
264 MOS sensor, could not penetrate the Teflon membrane.

265

266

### 267 2.1.3 Alkalinity

268

269 The incentive to measure the bicarbonate content of the mixed liquor indeed originates from the fact that  
270 imbalance in anaerobic digestion (due to the accumulation of volatile fatty acids, VFA) cannot easily be detected  
271 on the basis of pH measurements, especially when the alkalinity of the mixed liquor is high (Hawkes *et al.*  
272 1993). Because the alkalinity is often mainly due to the bicarbonate buffer, it has been proposed since the early  
273 sixties that its measurement can be used in control strategies for anaerobic digesters (McCarty 1964). One way to  
274 do so is by titration. Such methods involve titrating the sample down to pH 3.5 to determine the bicarbonate  
275 content with a correction for the volatile fatty acids present (see for example Ripley *et al.* (1985) or Anderson  
276 and Yang (1992)). The method is based on quantifying the gaseous carbon dioxide evolved from the sample as it  
277 is acidified. The volume of gas may be measured in two different ways. The overpressure in a closed constant  
278 volume vessel can be measured, or the gas volume produced can be measured with a sensitive gas flow meter in  
279 a constant pressure system. During titration, interferences from other weak acid/base constituents cannot be  
280 excluded and overestimation of VFA may sometimes occur (Purser *et al.* 2014).

281

### 282 2.1.4 Volatile Fatty Acids

283

284 Total VFA concentrations have been monitored for a long time as process performance indicators. It gives fast  
285 and reliable information of process status compared to other common indicators such as pH, alkalinity, gas  
286 production, and gas composition (Ahring *et al.* 1992; Björnsson *et al.* 2001b; Boe *et al.* 2007). Automated  
287 bicarbonate and total VFA instruments based on titrimetry have been developed and applied in practice for some  
288 years – see for example Feitkenhauer *et al.* (2002) or Ruiz *et al.* (2005).

289

290 Compared to total VFA concentration, individual VFA (acetate, propionate, butyrate etc.) can provide more  
291 information of the process status. Several studies have highlighted the importance of individual VFA as an early  
292 warning of process imbalance (Boe *et al.* 2010; Pind *et al.* 2003; Pratt *et al.* 2003; Pratt *et al.* 2012; Van Ginkel  
293 and Logan 2005). Ahring *et al.* (1992) suggested the overall level of n-butyric and iso-butyric was the best  
294 indicator of process stress. Boe *et al.* (2010) advised propionate as the most persistent parameter which was  
295 effective indicator of stress status of the process. Individual VFA are easily measured off-line using GC or  
296 HPLC, provided that all particulate matter has been removed from the sample.

297 However, only a few studies reported the development of an on-line individual VFA monitoring system because  
298 when dealing with anaerobic waste treatment, the presence of particulate matter is often high. Ryhiner *et al.*  
299 (1993) used GC for on-line analysis of acetic, propionic, butyric, valeric, and iso-valeric in a UASB reactor  
300 treating whey powder solution. The sample was purified by membrane filtration, acidified by phosphoric acid,  
301 and injected into the GC column by an auto-sampler with a specially constructed flow-through vial. However, no  
302 performance data was shown for this system. Zumbusch *et al.* (1994) used a HPLC for VFA monitoring in a  
303 UASB reactor treating baker's yeast wastewater using an ultra-filtration module for sample purification. The  
304 main problem of this process was membrane fouling requiring a high level of maintenance of the filtration  
305 system. Pind *et al.* (2003) used a GC for on-line analysis of VFA in a CSTR reactor treating manure and sample  
306 purification employed a three step filtration; pre-filtration by a rotating filter inside the reactor, ultra-filtration by  
307 a membrane cartridge, and a mini-filter for final purification. The system showed good correlation with the off-  
308 line measurement. However, membrane fouling was still the crucial problem and the membrane needed to be  
309 cleaned every 15–18 h to obtain sufficient flow. Boe *et al.* (2007) developed a new method to measure individual  
310 VFA based on headspace gas chromatography (HSGC). The method applies *ex situ* VFA stripping with variable  
311 headspace volume and gas analysis by gas chromatography-flame ionization detection (GC-FID). In each  
312 extraction, digester sample was acidified with H<sub>3</sub>PO<sub>4</sub> and NaHSO<sub>4</sub>, and then heated to strip the VFA into the gas  
313 phase. The system has been tested for on-line monitoring of a lab-scale CSTR reactor treating manure for more  
314 than 6 months and has shown good agreement with off-line analysis.

315

#### 316 2.1.5 Spectral sensors

317 Spectral techniques – UV/visible spectroscopy (UV/vis), Mid InfraRed spectroscopy (MIR), Near InfraRed  
318 spectroscopy (NIRS) – are beginning to provide very useful information about the complexity of organic matter.  
319 UV/vis spectroscopic probes in the range of 190 to 750 nm are often used in wastewater treatment plants to  
320 measure COD, TOC and NO<sub>3</sub>-N (Sarraguça *et al.* 2009). Wolf *et al.* (2013) developed a UV/vis spectroscopic  
321 system for VFA measurement (1.1 g.L<sup>-1</sup> – 3 g.L<sup>-1</sup>) in AD plants. An UV/vis probe from S::CAN was used in  
322 combination with a custom-built dilution system to monitor the absorption of fully fermented sludge. To validate  
323 the approach, on-line measurements have been taken at a full-scale 1.3 MW industrial biogas plant. Results  
324 showed that VFA concentrations can be predicted with an accuracy of 87%. Nevertheless, the necessary dilution  
325 system is a disadvantage compared to NIR and MIR spectroscopic systems.

326 NIRS presents great potential for monitoring the AD process. Holm-Nielsen *et al.* (2008) evaluated the use of  
327 NIRS technology on-line (Transflexive Embedded Near Infra-Red Sensor or TENIRS) to monitor a thermophilic  
328 digester treating manure and organic food industrial waste. Good correlation was obtained between on-line NIRS  
329 measurement of glycerol and VFA content in the anaerobic digester. Further works documented the potential to  
330 monitor VFA as well as VS in on-line installations at lab-scale and full-scale plants (Krapf *et al.* 2013, Jacobi *et*  
331 *al.* 2009).

332 Mid InfraRed (MIR) spectroscopy is another interesting technique to characterize waste organic matter. One  
333 major advantage against existing NIR sensors is that process variables such as VFA, total alkalinity (TA), NH<sub>4</sub>-  
334 N and TS show distinctive peaks in the MIR spectrum between 1,800 and 800 cm<sup>-1</sup>, which makes it easier to  
335 correlate peak intensity to actual concentrations. Provenzano *et al.* (2014) used Fourier Transform InfraRed  
336 (FTIR) and fluorescence spectroscopy to characterize the organic matter evolution during AD and composting of  
337 pig slurry. Steyer *et al.* (2002) also used for several years a FTIR spectrometer for on-line measurements of  
338 COD, TOC, VFA, total and partial alkalinity of an AD fixed bed treating industrial wine distillery wastewater.  
339 Spanjers *et al.* (2006) applied the same technique at a full scale plant for the on-line monitoring of VFA, COD,  
340 alkalinity, sulphate, and, since aerobic post-treatment was considered, total nitrogen, ammonia and nitrate  
341 concentrations. Based on these studies, Wolf *et al.* (2014) developed an on-line MIR system with an FTIR probe  
342 using Polychristalline-Infrared (PIR) fibres that allow for higher signal to noise ratio (S/N) ratios as well as  
343 longer fibres. Furthermore, a fully automated process interface for cleaning and recalibration was used in order  
344 to reduce maintenance to a minimum. Good calibration results were obtained for VFA (R<sup>2</sup>=0.97, RMSE  
345 0.372 g.L<sup>-1</sup>), TA (R<sup>2</sup>=0.99, RMSE=0.259 g.L<sup>-1</sup>) and NH<sub>4</sub>-N (R<sup>2</sup>=0.99, RMSE=0.11 g.L<sup>-1</sup>). In spite of all  
346 advantages and advances in infrared spectroscopic on-line measurement systems, two main challenges remain:  
347 (1) despite the great interest in infrared spectroscopy on organic matter characterization, this technique is not  
348 sensitive enough for structural interpretation of complex molecules and does not account for the bioaccessibility  
349 of organic constituents; (2) prices for infrared spectroscopic measurement systems, NIR and MIR, are still far  
350 too expensive to be widely used in AD plants, so that financial feasibility is mostly not provided.

351

#### 352 2.1.6 Other On-line Instrumentation

353 Other examples of advanced instrumentation can be seen in electronic tongues and noses and microwave or  
354 acoustic chemometrics (Madsen *et al.* 2011). A gas chromatograph or mass spectrometer coupled to a sample  
355 preparation unit can also be used, but so far no full-scale applications for these methods have been reported.

356

357 Liquid phase electrical conductivity is defined as the ability of a solution to conduct electrical current and is  
358 directly proportional to ion concentrations. Moreover, it can be easily monitored on-line: a cell formed by two  
359 electrodes is placed in the sample and the current between both electrodes is measured by means of the  
360 application of a potential difference (Colombié *et al.* 2007). Conductivity measurements could bring very  
361 informative measurements for monitoring and control of AD processes since ion concentrations are mainly  
362 affected by both VFA and bicarbonate concentrations (Hawkes *et al.* 1994), two of the most reliable indicators of  
363 AD process performance. Several studies have been published on the feasibility of electrical conductivity sensors  
364 for bioprocess monitoring (see, for instance, Hoffmann *et al.* 2000; Varley *et al.* 2004; Aguado *et al.* 2006;  
365 Ellison *et al.* 2007). However, there is still a lack of knowledge regarding its applicability to AD processes,  
366 despite some applications in dark fermentation processes for H<sub>2</sub> production (Aceves-Lara *et al.* 2010).

367

## 368 2.2 – Off-Line Instrumentation

369

370 With long HRTs or SRTs, off-line characterization of the waste and biomass can be considered as a way to  
371 provide operators with useful information to optimize AD plants, even though the data are yet not on-line.  
372 Several techniques exist and they are presented below.

373

### 374 2.2.1 Global characterization methodologies

375 From an analytical point of view, the performance of AD in wastewater or waste treatment is traditionally  
376 evaluated using parameters such as chemical oxygen demand (COD), total organic carbon (TOC) and  
377 biochemical oxygen demand (BOD). In order to optimize plant design and operation, Raunkjær *et al.* (1994)  
378 proposed to link COD fractions and biodegradability. Kayhanian (1995) showed that the content of  
379 biodegradable volatile solids (VS) impacted the prediction of biogas production rate and the computation of the  
380 organic loading rate and the carbon/nitrogen (C/N) ratio. Since the seventies, the most widely used indicator to  
381 assess the performance of digesters has been the amount of methane produced per unit of total solid (TS) or  
382 volatile solids (VS) of any given substrate (Chynoweth *et al.* 1993).

383

### 384 2.2.2 Biodegradability and organic matter characterization

385 One of the key issues in operating and optimizing AD plants is to assess the quantity of methane that can be  
386 produced from an organic residue. To this end, the most commonly used method to measure anaerobic  
387 biodegradability is the biochemical methane potential (BMP) test (ISO EN 11734 1995).

388

#### 389 *BMP Data and Use for Process Modeling*

390 The BMP assay is a procedure developed to determine the methane yield of an organic material during its  
391 anaerobic decomposition by a mixed microbial community in a defined medium. The procedure was developed  
392 for a serum-bottle technique by Owen *et al.* (1979). Angelidaki and Sanders (2004) described the procedure and  
393 the calculations. The test ends when the cumulative biogas curve closely approaches an asymptote, usually after  
394 30 days of incubation but it may be much longer for non-easily degradable material such as fibers. Therefore, the  
395 main inconvenience of the test is the long time required in its execution. Other negative points are the variability  
396 of the results obtained through the BMP tests and their ability to predict continuous digester performances.  
397 Concerning the first point, several studies made inter-laboratory assays to compare the BMP test results. Kinetic  
398 rates were widely different among different participating laboratories, standard deviations ranged from 57% to  
399 68% (Jensen *et al.* 2009). The relative standard deviation of BMP values ranged from 15% to 24% and decreased  
400 to 10% when outliers were not considered (Raposo *et al.* 2011). Currently, only one inter-laboratory (French  
401 Inter-laboratory assay 2013-2014) proposes new guidelines and protocol after 2 test rounds achieved on solid  
402 substrates. This last study has shown good intra-laboratory repeatability (equal to 4%), reproducibility (between  
403 5 and 7%) and reproducibility (between 13 and 21%) – see Cresson *et al.* (2014).

404 Concerning the second drawback, according to Jensen *et al.* (2009), the biodegradability and the bioaccessibility  
405 of hydrolysis-limited substrates could be defined by the parameters  $B_0$  and  $k$  calculated from the Gompertz  
406 equation applied to a BMP curve (cumulative methane production versus time),  $B = B_0 \times (1 - e^{-kt})$ , where  $B$   
407 is the cumulative methane production,  $B_0$  is the maximal methane production and  $k$  is the hydrolysis rate  
408 constant. However, the authors discuss the conservative feature of these parameters measured in a BMP test.  
409 Several opinions are found in the literature concerning the use of  $B_0$  and  $k$  parameters obtained in batch tests in  
410 order to model continuous digesters (see, for example, Val del Rio *et al.* 2011; Nielfa *et al.* 2015; Strömberg *et*  
411 *al.* 2015). Batstone *et al.* (2009) found that the BMP test's parameters should not be used for dynamic modelling  
412 of continuous digesters. While the final value of BMP was found to be consistent with continuous data, these  
413 authors found that the hydrolysis rate parameter value was lower in a BMP test than in a continuous digester  
414 treating thermally a waste activated sludge (*i.e.* 0.15-0.25 d<sup>-1</sup> versus > 5d<sup>-1</sup>). According to Labatut *et al.* (2011),

415 the BMP test is not suitable for predicting methane production kinetics for continuous digesters because it is  
416 conducted under diluted conditions, so preventing any inhibition response from being observed. Nevertheless,  
417 Jensen *et al.* (2009) found that the batch test was slightly conservative in terms of estimating degradability and  
418 rate, when applied to slowly degradable substrates such as waste activated sludge. Fannin *et al.* (1987) concluded  
419 that the maximum theoretical methane yield determination was useful to evaluate digester performance and to  
420 provide basis for experimental work. On the other hand, biodegradation tests performed sequentially in batch  
421 reactors using a slightly different protocol than the one used in BMP tests (Ganesh *et al.* 2013) were shown to be  
422 very informative in assessing the biodegradation kinetics of a broad spectrum of biowaste (García-Gen *et al.*  
423 2015).

424

#### 425 *More Rapid Prediction of Methane Potential*

426 Over the years, several authors developed relationships between the organic matter composition and the methane  
427 production or the anaerobic biodegradability. Static models are correlations (obtained by linear regression or  
428 partial least square (PLS) regression) where the parameters of interest are expressed as a function of one or more  
429 variables based on some analytical composition of the given substrate. Static implies neither kinetic equation nor  
430 variation over time. Three kinds of static models appeared in the literature to predict biodegradability of solid  
431 organic waste. Table 1 summarizes the comparative analysis, including benefits and drawbacks, of the different  
432 characterization methodologies involved in the integrative tools.

433

#### 434 • Initial biogas production modelling

435 Some authors used the initial rate of biogas production modelling in order to predict the final value of BMP  
436 (Donoso-Bravo *et al.* 2011; Strömberg *et al.* 2015). For example, based on a database, Strömberg *et al.* (2015)  
437 proposed an algorithm to predict the BMP value from incubation experimental data operated during 6 days with  
438 an error less than 10%. Donoso-Bravo *et al.* (2011) used similar technique with incubation during 3-4 days.  
439 However, the modelled methane production of a continuous digester was underestimated by 20% with these  
440 parameters.

#### 441 • Organic matter characterization

442 Over the last two decades, several authors also tried to build other static integrative tools based on organic matter  
443 characterization but they were mainly applied to municipal solid waste (Buffiere *et al.* 2006), kitchen, fruits and  
444 vegetables wastes (Gunaseelan 2007; 2009). Few studies dealt with municipal sludge although the

445 methodologies used on solid waste can be transposed to sludge. The most recent publications have been  
446 presented by Mottet *et al.* (2010), Appels *et al.* (2011) and Jimenez *et al.* (2014).

447 First, the theoretical BMP obtained from the empirical formula has been calculated since 1930 using the Buswell  
448 equation (Neave and Buswell 1930). This stoichiometric equation is based on the elemental composition  
449 ( $C_nH_aO_b$ ) where organic matter is reduced to methane and oxidized into carbon dioxide, with the assumption of a  
450 total conversion. However, these relationships remain theoretical and they assume that organic matter is fully  
451 converted. They did not consider (i) the fraction of substrate used for bacterial growth, (ii) the refractory organic  
452 matter (such as lignin) contained in the substrate, (iii) the fraction of the organic matter remains inaccessible due  
453 to binding within particles and (iv) the limitation of nutrients (Angelidaki and Sanders 2004). Several authors  
454 showed that biodegradability was overestimated using this technique (Shanmugam and Horan 2009, Labatut *et*  
455 *al.* 2011). Additionally, when applied to municipal solid waste, Davidsson *et al.* (2007) showed that theoretical  
456 methane potential is more realistic when the calculation is based on biochemical composition (lipids,  
457 carbohydrates, proteins) rather than on elemental composition analysis.

458 From Table 1, correlations obtained depend on the nature of different waste molecules. For example, fiber  
459 characterization would be more suitable for lignocellulose-like substrates such as green wastes, fruits and  
460 vegetables wastes (Buffiere *et al.* 2006) than for sewage sludge. Indeed, Mottet *et al.* (2010) applied the Van  
461 Soest fractionation (Van Soest 1963) to characterize organic matter from municipal sludge in order to build a  
462 biodegradability indicator. The error for the validation of the Partial Least Square (PLS) model was about 35%.  
463 Van Soest fractionation targets fibers and carbohydrates (i.e. cellulose, hemicellulose, lignin) but sewage sludge  
464 are also composed of proteins, humic acids and lipids (Jimenez *et al.* 2013). In the second part of their work, the  
465 authors found a better correlation between anaerobic biodegradability and the specific biochemical fractions of  
466 organic matter, such as proteins, carbohydrates, lipids and the degree of oxidation of organic molecules. Only  
467 Gunaseelan (2007; 2009) considered fibers, carbohydrates, lipids and proteins.

468 Concerning biomolecules characterization, several methods exist and are summarized in the Table 2. Initially  
469 conceived to analyze proteins, lipids and carbohydrates in serum samples, colorimetric methods have been  
470 applied in environmental engineering to characterize organic fractions. They are now coupled with analytical  
471 improvements such as organic matter extraction techniques (Park and Novak 2007; Ras *et al.* 2008). Table 2  
472 summarizes some of the available methods used to determine the main components of organic matter.  
473 Depending on the nature of the substrate (total sludge or EPS solubilized in an extracting agent) the methods are  
474 more or less adequate (Jimenez *et al.* 2013). Recently, several reported works used a more advanced

475 methodology: gas chromatography with mass spectroscopy (GC/MS) was used in order to determine the detailed  
476 composition of carbohydrates, proteins and lipids present in the sample. Huang *et al.* (2010) used this technology  
477 for wastewater characterization.

478

479 • Aerobic tests

480 Indirect correlations between aerobic activity tests and anaerobic tests such as BMP are also often proposed.  
481 Aerobic tests are less time consuming than anaerobic tests and they can be easier from a practical point of view  
482 (e.g. no need for anaerobic conditions and precautions working in an air environment). Although the  
483 respirometric test takes less time than the BMP test, there are some limitations in using it to determine the BMP.  
484 First, only the readily biodegradable organic matter is considered (the more complex organic matter, such as  
485 cellulose, are degraded more slowly and are not measured in the short-term test) (Lesteur *et al.* 2010). The  
486 second limitation is the assumption that the organic matter in sludge presents the same biodegradability under  
487 aerobic and anaerobic conditions (Ekama *et al.* 2007). Buendía *et al.* (2008) used long anaerobic and aerobic  
488 batch tests in order to estimate readily and slowly biodegradable fractions and found a good correlation between  
489 the anaerobic and the aerobic readily biodegradable fraction. However, the slowly biodegradable fraction was  
490 underestimated by the aerobic batch testing. In the same way, Park *et al.* (2008) showed some proteins bound to  
491 divalent cations were bioaccessible only under aerobic conditions but were not bioaccessible under anaerobic  
492 conditions. Higher volatile solids removal was observed under aerobic conditions (48%) compared to AD (39%).

493

494 *Emerging Techniques for Organic Matter Characterization*

495 Progress in analytical chemistry has led to the development of new instruments and techniques to characterize  
496 organic matter. Among them, NIRS and 3D fluorescence spectroscopy are the most promising for  
497 instrumentation and biodegradability measurement.

498 Recently, NIRS is used for BMP assessment following two different approaches. The first approach is to  
499 determine the composition of the input material using NIRS and to calculate the BMP value by regression using  
500 static models. The second approach to predict the biodegradability uses directly the spectra through a dedicated  
501 calibration. Jacobi *et al.* (2012) used both approaches for the determination of the biogas production from maize,  
502 which is commonly used in Germany. The calibration allowed errors for volatile solids of 0.74 % fresh matter  
503 and for biogas production of 5.26-11.14 l/kg fresh matter. Application of the technique for off-line prediction of  
504 continuously gathered data allowed, together with first order degradation kinetics, the prediction of the biogas

505 production of a full-scale biogas plant over several months. Zhang *et al.* (2009) succeeded in building PLS  
506 models between NIRS results and ethanol, acetate, propionate and butyrate concentrations in a H<sub>2</sub> producing  
507 reactor fed on synthetic wastewater. Lignin concentration has also been correlated to NIRS measurement by  
508 Brinkmann *et al.* (2002). However, so far NIRS has not yet found its way into practical implementation at biogas  
509 plants. One obstacle seems to be the transfer of calibrations of a given sample set to new samples and the  
510 reliability of the predicted values.

511 Lesteur *et al.* (2011), Doublet *et al.* (2013) and Triolo *et al.* (2011) have successfully developed PLS models for  
512 BMP prediction of different waste organic matter BMP values using Near InfraRed Spectroscopy (NIRS).  
513 Lesteur *et al.* (2011) and Doublet *et al.* (2013) found a direct correlation between the NIRS analysis and the  
514 biodegradability provided by the BMP tests for municipal solid waste. The prediction demonstrated good  
515 accuracy (standard deviation of 28 mLCH<sub>4</sub>/gVS and relative error of 13% respectively). However, NIRS  
516 measurement for biodegradability assessment is still performed on dried-frozen samples and does not consider  
517 accessibility of the organic matter.

518 Another promising technique is the fluorescence spectroscopy. Fluorescence allows the characterization of the  
519 analyzed organic material in both liquid and solid phases. The technique gives a topographic map of the organic  
520 matter complexity. Identification of molecular-like groups is possible based on the excitation and emission  
521 wavelength coordinates (Jimenez *et al.* 2014). It is indeed a selective and sensitive method since fluorescence  
522 characteristics are related to the structure and the functional groups in the molecules. Some studies have revealed  
523 the potential of fluorescence spectroscopy to link to the complexity of a substrate and its biodegradability  
524 (Tartakovsky *et al.* 1996; Reynolds *et al.* 1997) and results on establishing a link between complexity, sludge  
525 stabilization degree and accessibility, were encouraging (He *et al.* 2011; Wan *et al.* 2012). Recently, Jimenez *et*  
526 *al.* (2014) proposed a sewage sludge characterization methodology to assess both biodegradability and  
527 bioaccessibility needed for modified ADM1 input variables and thus for further optimization of AD plants.  
528 These authors combined basic chemical extractions with 3D fluorescence spectroscopy in a 5 days long  
529 methodology and predicted successfully both parameters using a PLS regression model. A wide range of  
530 biodegradability (0-60%) and of readily/slowly biodegradable fractions (0-46%), representing bioaccessibility,  
531 were predicted with errors of 6% for both. However, this technique was specific to sewage sludge, as far as  
532 proteins compose the main part of the organic matter in this organic waste.

### 533 2.3 - Dynamical Models and Software Sensors

534

535 As previously presented, static models have been proposed as an alternative solution to predict biodegradability  
536 with several kind of organic matter characterization as explicative variables. However, all the static models were  
537 not able to predict simultaneously the bioaccessibility and the biodegradability as the digester dynamics.

538

539 Dynamical models accounts for evolution in kinetic equation and biomasses. This leads to more complex models  
540 generally based on ordinary differential equations representing mass balance within the process. The first  
541 dynamical AD digestion models were proposed in the mid-sixties by Andrews and Pearson (1965) and Andrews  
542 and Graef (1971). Only a single stage was considered gathering acidogenesis and methanogenesis. A Haldane  
543 kinetic equation was proposed to account for acetoclastic methanogenesis inhibition at high concentration of  
544 acetate. Mosey (1983) and Hobson (1985) extended the model with hydrogenotrophic methanogenesis. The  
545 models were then extended depending on the different substrates (wastewater, sludge or manure). More than 10  
546 years ago, the IWA Task Group on Mathematical Modelling of Anaerobic Digestion Processes proposed the  
547 Anaerobic Digestion Model No1 (ADM1), as a consensual modelling of anaerobic digestion (Batstone *et al.*  
548 2002). The biochemical reactions represented in the model describe: (i) an extracellular disintegration step  
549 converting composite particulate matter into carbohydrates, lipids, proteins and inert compounds, (ii) an  
550 extracellular enzymatic hydrolysis step that converts the degradation products into their chemical building  
551 blocks, *i.e.* LCFA, monosaccharides and amino acids, (iii) acidogenesis or fermentation into hydrogen, acetate  
552 and VFA, (iv) acetogenesis of VFA into acetate and (v) acetoclastic and hydrogenotrophic methanogenesis. The  
553 extracellular reactions are assumed to be of first-order, while the intracellular biochemical reactions use Monod-  
554 type kinetics for substrate uptake and biomass growth. Variants to the ADM1 model given by Batstone *et al.*  
555 (2002) are available for plant wide modelling (Rosén and Jeppsson 2006; Grau *et al.* 2007; De Gracia *et al.*  
556 2009; Barat *et al.* 2012). Many applications of the ADM1 model have been published for a wide variety of  
557 substrates (see e.g. Batstone *et al.* 2009; Lauwers *et al.* 2013) and some models account for both the  
558 biodegradability and the bioaccessibility of the waste (Mottet *et al.* 2013, García-Gen *et al.* 2015). On the other  
559 hand, simpler models have been developed, more suitable to support monitoring or control strategies. For  
560 example, the model of Bernard *et al.* (2001a) includes two reactions and turns out to approximate efficiently the  
561 ADM1 model (Bernard *et al.* 2005b) for modeling AD processes treating industrial wastewater.

562

563 In many occasions, on-line or off-line measurements are not enough to evaluate and to assess the operating  
564 conditions of AD plants but, when combined with dynamical models, these measurements can lead to very

565 useful additional information about non measured variables. This methodology leads to the so-called “software  
566 sensors”. It is possible to distinguish the approaches based on data sets, those founded on expert knowledge (in  
567 the broad sense of the term) and those founded upon an analytical – mathematical – description of the system. In  
568 this section, we focus particularly on the estimation for the efficient development and implementation of state  
569 estimation schemes. These estimation schemes are called estimators, state observers, software sensors, or simply  
570 observers, and they can be used for design or optimization strategies in a wide class of biochemical processes.  
571 As underlined, these algorithms are able to estimate both state variables, that are normally not measured, and  
572 unknown parameters from the available measurements. In biological processes, observers are mainly useful in  
573 on-line estimations for control purposes. The most popular approaches used in the past have been the well-  
574 known classical extended Kalman filters (EKF) and extended Luenberger observers (ELO). One of the reasons  
575 for the popularity of EKF/ELO is that they are easy to implement since the algorithms can be directly derived  
576 from the state space model. However, since these estimators are based on a linearized model of the process, the  
577 stability and convergence properties are essentially local; it is difficult to guarantee its stability over a wide  
578 operating range. As a matter of fact, very few works deal with the observability of nonlinear biochemical  
579 processes (e.g., Gauthier and Kupka 1994) and they are usually concerned with particular process applications.  
580 Another problem is that the theory for EKF/ELO is developed assuming a perfect knowledge of the system  
581 model and parameters, in particular of the process kinetics, and as a consequence, it is difficult to develop error  
582 bounds to take into account the large uncertainty of these parameters.

583

584 In order to overcome these drawbacks, several other approaches have been proposed from the early seventies  
585 (Misawa and Hedrick 1989; Perrier *et al.* 2000; Dochain 2003; Alcaraz-González and González-Álvarez 2007).  
586 For example, adaptive observers (Bastin and Dochain 1990, Dochain 2003) belong to the class of observers  
587 allowing the estimation of both kinetic parameters and states. As in the EKF, the poorly known (or unknown)  
588 parameters are considered to be extra states with no dynamics. One of the original features of the adaptive  
589 observer is to consider a nominal process model, *i.e.* a model with nominal values of the poorly known  
590 parameters (Chen 1990). The design of nonlinear observers in general has been a very active research area. Most  
591 of the nonlinear approaches are placed in the category of “high gain” observers (HGO) since they tend to split  
592 the dynamics into a linear part and a nonlinear part and to choose the gain of the observer so that the linear part  
593 dominates the nonlinear one (Gauthier *et al.* 1992; Gauthier and Kupka 1994; Dochain 2003).

594

595 Several linearization methods also have been proposed (Baumann and Rugh 1986). Nevertheless, like EFK/ELO,  
596 only local behavior can be guaranteed as they miss practical results on performance and stability. Other  
597 approaches are sliding observers based on the theory of variable structure systems (Xiong and Saif 2003) but  
598 their design involve conditions that must be assumed *a priori* or that are usually hard to verify (Misawa and  
599 Hedrick 1989). All these approaches solve some of the problems described above but in most of the cases, the  
600 complexity of the resulting estimating algorithms is a limitation for real time computation. Indeed, monitoring  
601 algorithms can prove to be efficient if they are able to incorporate the important well-known information on the  
602 process while being able to deal with the missing information in a robust way. They include the lack of on-line  
603 measurements and the uncertainty on the process dynamics.

604

605 Two relatively new robust nonlinear observers have found a wide acceptance in biological process, including of  
606 course anaerobic digestion. Such robust observers are capable of coping simultaneously with the aforementioned  
607 problems while remaining easy to implement with a minimum number of straightforward conditions to verify.  
608 The first one, the asymptotic observer (Bastin and Dochain 1990; Alcaraz-González and González-Álvarez  
609 2007), although requiring the knowledge of the process inputs, has the main advantage that it permits the exact  
610 cancellation of the nonlinear terms of the systems, and so facilitates its design, stability analysis and  
611 implementation. The second one, the interval observer, allows for the reconstruction of a guaranteed interval on  
612 the unmeasured states instead of reconstructing their precise numerical values assuming that only guaranteed  
613 lower and upper limits on the process inputs and model parameters are available (Gouzé *et al.* 2000; Alcaraz-  
614 González *et al.* 2005a; Rapaport and Dochain 2005; Moisan *et al.* 2009).

615

616 The main disadvantage of the aforementioned asymptotic observer is that the process operational conditions  
617 (mainly the hydraulic retention time) establish its convergence properties and it is not possible to modify the  
618 convergence rate by choosing a gain like in the classical observers or the HGO. However, adapting the design  
619 features of the HGO and adaptive observers, a Tunable Asymptotic Observer (TAO) has been proposed for AD  
620 processes (Bernard and Gouzé 2004, Alcaraz-González *et al.* 2005b). Furthermore, in a more diverse sense,  
621 super-twisting observers have also been demonstrated recently to be very useful in achieving a very fast  
622 convergence without loss of robustness, (Sbarciog *et al.* 2012).

623

624 Concerning the drawback of influent uncertainty – very common in AD plants –, the general problem of  
625 simultaneous estimation of unmeasured state variables and inputs for nonlinear systems has been addressed from  
626 a number of different robust approaches. With respect to AD processes, Theilliol *et al.* (2003) proposed a  
627 simultaneous input-and-state concentrations observer that required the full knowledge of the process kinetics.  
628 Also, Aceves-Lara *et al.* (2010) simultaneously estimated state space variables and the input concentrations in a  
629 biohydrogen production process in which input and state estimations were performed using a state  
630 transformation and an asymptotic observer. More recently, Jaúregui-Medina *et al.* (2009) proposed an observer-  
631 based estimator, named the “Virtually Controlled Observer” (VCO) because one of the observer's inputs (the  
632 hypothetical -unmeasured- influent substrate concentration) is updated by a feedback control that regulates the  
633 estimation error of a measured output. In a fixed bed configuration, several of these approaches have also been  
634 applied to distributed parameter systems (see e.g., Delattre *et al.* 2004; Aguilar-Garnica *et al.* 2009).

635

### 636 **3. Control of Anaerobic Digestion Processes**

637

638 Because of the inherent complexity and necessity for safety in biotechnological processes, efficient monitoring  
639 and decision support systems are required in order to optimize their operation. Indeed, even in normal  
640 operational conditions, several types of disturbances may occur with serious consequences in the performance of  
641 the process. Fluctuations in the influent to be treated is an illustration and a typical example would be an  
642 integrated dairy producing 100 different products that, over the course of a week, result in a wastewater stream  
643 with flow/total COD/TSS/FOG/temperature variations of 20x/10x/5x/3x/1.5x, some of these changes taking  
644 place in a matter of hours. Hence, the last two decades have seen an increasing interest to improve the operation  
645 of AD processes by applying advanced control schemes. Optimized and stable performances are indeed required  
646 to be guaranteed consistently and this has major consequences for instrumentation, control and automation  
647 (Huntington 1998; Olsson and Newell 1998). Two main factors (which can be interpreted as both, incentives and  
648 constraints) have contributed to this new paradigm: (1) the need for optimally controlled plants due to  
649 environmental regulatory norms and (2) the need to reduce cost. In order to fulfill these requirements, the  
650 optimal control of AD processes faces important uncertainties arising from the intrinsic complexity of plant  
651 design. Among others, the main disturbances that can be observed are the following: acidification, inhibition and  
652 toxicant exposure (McCartney and Oleszkiewicz 1991; 1993; O’Flaherty *et al.* 1998; Hao 2003; Appels *et al.*  
653 2008; Chen *et al.* 2008; Cirne *et al.* 2008), overload (Waewsak *et al.* 2010; Wijekoon *et al.* 2011), alkalinity,

654 variability of inputs, water content and rheology, foaming, stirring and mixing problems (McMahon 2001;  
655 Dalmau *et al.* 2010) and lack of macro- and micro-nutrients (Speece 2008).

656

657 By far, the most developed control laws in the literature use the dilution rate as manipulated variable (see Figure  
658 1) but it is mainly in simulation and only few full-scale applications are available. Manipulating the dilution rate  
659 is indeed difficult in practice and AD processes are facing the problem of the lack of actuators. Examples for  
660 other manipulated variables are liquid recirculation rates and the addition of bases to stabilize the process. In  
661 case of a co-digestion plant, only one substrate or a constant substrate mix is usually controlled using the dilution  
662 rate as manipulated variable. The other substrates then must be calculated based on boundary conditions such as  
663 hydraulic retention time, organic loading rate or restrictions defined by funding schemes (Zhou *et al.* 2012).

664

665 Whilst experimentation is required for the tuning of regulators, either on the plant itself or within a simulation  
666 environment, design techniques have been developed that allow devising the optimal controller for a particular  
667 process model and performance index. Certain constraints imposed on the control action, such as a minimization  
668 of the control effort, can be accommodated during the design.

669

### 670 3.1 – Classical control in AD

671

672 PID and on/off controllers belong to classical control methods. Table ESM.1 and ESM.2 in Online Resource 1  
673 illustrates some examples of application of these control methodologies in AD.

674

675 The first application of on/off control in AD was reported in the 70s (see Table ESM.1 in Online Resource 1),  
676 which aimed at setting the manipulated variable to a binary value depending on predefined threshold values.  
677 They were followed by PID controls including P, PI, and PID controls. For instance, Marsili-Libelli and Beni  
678 (1996) applied PID control for stabilising alkalinity and pH by manipulating the addition of bicarbonate. On the  
679 other hand, von Sachs *et al.* (2003) proposed a PI structure for controlling biogas flow rate by modifying the  
680 dilution rate in a two-phase AD system.

681

682 PID cascade controls (see Table ESM.2 in Online Resource 1) are a simple but effective approach for feed  
683 control. Their advantages are that two possibly conflictive set-points can be simultaneously controlled whilst the

684 set-point of the master loop can be set by an expert system. Approaches such as Liu *et al.* (2004a; 2004b),  
685 Alferes *et al.* (2008), and Alferes and Irizar (2010) are dedicated to control biogas production at a given set-point  
686 or to operate the digester at high organic load. Therefore, these approaches try to maximize the economical  
687 benefit of the digester, whereas the set-point is established in order to avoid digester overloads.

688

689 As regards adaptive control, Zhou *et al.* (2012), for instance, proposed a PID aimed at controlling the methane  
690 flow rate based on measurements of VFA and VFA/TA.

691

692 Another control strategy lies on minimizing the COD or VFA content in the effluent (see e.g. Alvarez-Ramirez *et*  
693 *al.* 2002; Mu *et al.* 2007). The key goal of control strategies of this type is to stabilize digester performance  
694 whilst maximizing COD degradation. On the other hand, García-Diéguez *et al.* (2011) proposed an approach  
695 capable to maximize methane flow rate whilst tracking a set-point for effluent VFAs.

696

### 697 3.2 - Advanced control in AD

698

699 Since classical PID controllers are usually limited to single-input-single-output control loops and to linear,  
700 simple cases, different advanced control approaches have been theoretically analyzed and experimentally  
701 validated in order to control AD processes.

702

#### 703 3.2.1. Expert systems

704

705 Expert systems can be classified in rule-based and fuzzy systems (Tables ESM.3 and ESM.4 in Online Resource  
706 1) and systems extended with a surrogate model such as an artificial neural network or special fuzzy systems  
707 (Table ESM.5 in Online Resource 1).

708

709 Applying nonlinear control methods comes quite natural since biogas plants are nonlinear processes. Such expert  
710 systems are quite popular for AD control because of: 1) their intuitive design based on rules, and 2) their non-  
711 linearity coping with the non-linearity of the plant. The first approach is performed by rule-based systems such  
712 as the well-known fuzzy control, whilst the latter one is performed by the use of neural networks. Furthermore,

713 expert systems can easily incorporate all measured variables and are easily extensible if an additional process  
714 value is measured in the future.

715

716 Fuzzy logic is a problem-solving tool that can achieve a definite conclusion from imprecise information,  
717 allowing intermediate values rather than simple yes/no evaluations (García-Gen 2015). The main benefit of this  
718 approach is that it can be used to control non-linear systems. A fuzzy-logic controller (Zadeh *et al.* 1965) is  
719 indeed capable of optimizing different kinds of processes under dynamic operating and loading conditions by  
720 applying valuable expert knowledge (Verbruggen *et al.* 1997). Moreover, fuzzy-logic control does not require a  
721 large amount of data and/or a rigorous mathematical model, and allows for the development of multiple-input-  
722 multiple-output control schemes. Hence, fuzzy logic is a powerful tool for AD control (Olsson *et al.* 2005).

723

724 Different examples of rule-based and fuzzy-logic-based systems for AD control can be found in literature (see  
725 Tables ESM.3 and ESM.4). For instance, Pullammanappallil *et al.* (1991; 1998) developed an expert system  
726 aimed to control methane production by switching between different control strategies (set-point control,  
727 constant yield control, batch operation and constant dilution rate) based on a t-test. Puñal *et al.* (2003) proposed a  
728 PI-based fuzzy logic system for monitoring the effluent VFA concentration in anaerobic wastewater treatment  
729 plants, using the dilution rate as manipulated variable. Murnleitner *et al.* (2002) and Grepmeier (2002) proposed  
730 expert systems based on fuzzy theory for overload avoidance in AD process. Different inputs were used for such  
731 purpose: H<sub>2</sub> concentration, CH<sub>4</sub> concentration, biogas flow rate, pH, and filling level of the buffer tank.

732

733 Table ESM.5 in Online Resource 1 summarises different examples of expert systems for AD control consisting  
734 of neural networks and special fuzzy systems. For instance, Steyer *et al.* (1997) proposed a hierarchical fuzzy  
735 control for VFA concentration which used the control error of pH, temperature and biogas flow rate as input  
736 variables. Holubar *et al.* (2002; 2003) used a neural network to maximize methane production and COD  
737 degradation by modifying OLR on the basis of different inputs: pH, VFA, and biogas production and  
738 composition. Carlos-Hernandez *et al.* (2007) developed a fuzzy supervisory controller to optimise process  
739 performance by regulating the addition of base and the dilution rate; whilst this control system was later  
740 modified (Carlos-Hernandez *et al.* 2010) following a neural fuzzy structure for estimating methanogenic biomass  
741 performance.

742

### 743 3.2.2. Model-based and linearizing control

744

745 Linearizing approach is popular for feed control purposes in AD (see Table ESM.6 in Online Resource 1).  
746 Moreover, much effort has been applied to develop new model-based control laws that will achieve suitable  
747 process performances (Méndez-Acosta *et al.* 2010). In this context, simple models like AM2 (Bernard *et al.*  
748 2001b) are preferred to more complex ones like ADM1 (Batstone *et al.* 2002).

749

750 Linearizing control is based on a non-linear controller, which is precisely designed to achieve linear closed-loop  
751 dynamics (Isidori *et al.* 1989; Ignatova *et al.* 2008). The main aim of linearizing control is to take advantage of  
752 available mathematical models. They allow controlling very efficiently the functioning of a plant and may allow  
753 the achievement of finer actions than those controllers that decide only upon the difference between  
754 measurements and set points (Olsson *et al.* 2005). Linearizing controllers are designed by a two-step procedure  
755 (Kurtz *et al.* 1997). First, a non-linear process model is used in order to synthesize the non-linear state feed-back  
756 controller that linearizes the map between a “new” manipulated input and the controlled output. In the second  
757 step, a linear pole placement controller is designed for the feed-back linearized system. However, due to the  
758 strongly non-linear relationships existing between both inlet and outlet of an anaerobic process, linearizing  
759 controllers only attain proper results when the process dynamics are bounded by a defined linear zone  
760 (Simeonov and Queinnec 2006).

761

762 Applications of adaptive linearizing control have been presented for anaerobic digestion (Renard *et al.* 1988).  
763 However, an important problem with adaptive control systems is the necessity for on-line identification of the  
764 process model while the plant is in closed-loop operation. An approach to deal with the identification problem  
765 consists of considering that the process model belongs to a bounded class of possible models with fixed  
766 parameters. The identification is then reduced to the choice of the correct model, or, as in the Model Weighting  
767 Adaptive Control (MWAC) approach (Gendron *et al.* 1993), by weighting the different models into a composite  
768 process model.

769

770 Another method in this category is the interval-based approach. Concerning Interval Observers, a recent control  
771 approach that uses the partial information provided by this kind of observers has been designed to exponentially  
772 stabilize a regulated variable in a neighborhood of a predetermined set-point (Rapaport and Harmand 2002). As

773 for observers, these approaches have been also applied to distributed parameter systems applied to fixed-bed  
774 bioreactors (e.g., Dochain *et al.* 1997; Babary *et al.* 1999; Antoniadis and Christofides 2001; Aguilar-Garnica *et*  
775 *al.* 2009).

776

777 Some other recent approaches for control of this kind of processes have been derived from the theory based on  
778 differential geometry (Isidori 1989; Henson and Seborg 1997). Control approaches based on differential  
779 geometry allow for the transformation of a nonlinear system into a partially or totally linear one, by means of a  
780 nonlinear state transformation, which is obtained from directional derivatives of the output. It is important to  
781 remark that geometric control differs totally from the linear approximation of dynamics by calculation of the  
782 Jacobian. Either state-space (Hunt and Su 1983) or input-output linearization (Méndez-Acosta *et al.* 2004; 2005;  
783 2008) have been employed.

784

785 More recently, sliding mode approaches have been also used mainly to control Anaerobic Sequential Batch  
786 Reactors (ASBR), (Vargas *et al.* 2008), as well as in continuous bioreactors (Lara-Cisneros *et al.* 2015). In  
787 general, the sliding mode approaches are widely used due to robustness with respect to uncertainties.

788

789 3.2.3. Other advanced controllers

790

791 Table ESM.7 in Online Resource 1 summarizes other advanced control approaches, including, for instance,  
792 disturbance monitoring, non-linear, adaptive, and robust control.

793

794 A nonlinear adaptive control law for bioreactors which is robust in the face of unknown kinetics has been  
795 proposed recently for the global stabilization of bioreactors and then applied to the regulation of anaerobic  
796 digestion processes (Mailleret *et al.* 2004). Similar to linearizing control, different interval-based approaches  
797 have been used to exponentially stabilize a regulated variable in a neighborhood of a predetermined set-point  
798 (Alcaraz-González *et al.* 2005a).

799 On the other hand, most of the controllers reviewed before were developed to regulate known set-points or to  
800 track well defined trajectories. However, in AD operation, the control objective could be to optimize a criterion  
801 that is dependent of unknown parameters in order to keep a performance criterion at its optimal value. Also, it is  
802 well known that the explicit form of the performance function in AD processes is highly uncertain (e.g., the

803 growth rate of methanogenesis or growth rate of acidogenesis) (Lara-Cisneros *et al.* 2015). Extremum-Seeking-  
804 Control (ESC) and probing control are two techniques to handle these kinds of dynamic optimization problems  
805 (Dochain *et al.* 2011; Guay *et al.* 2004; Liu *et al.* 2006; Marcos *et al.* 2004a; 2004b; Steyer *et al.* 1999). The  
806 goals of ESC schemes and probing control is to find the operating setpoints, *a priori* unknown, such that a  
807 performance function reaches its extremum value. Steyer *et al.* (1999) developed a probing control approach  
808 based on the analysis of disturbances added on purpose to the influent flow rate. By increasing the influent flow  
809 rate for a short period of time, the increased biogas yield was compared to the expected one. Overloading or  
810 inhibition could be interpreted as a negative effect of the disturbance (i.e. an unsatisfactory gas yield). Liu *et al.*  
811 (2006) developed a cascade controller system that is embedded into a rule-based supervisory system based on  
812 ESC. This controller was applied to intensify biogas production in an anaerobic up-flow fixed bed reactor at  
813 laboratory scale and achieved good performance, especially during the early startup and during rejection of  
814 disturbances. In particular, the process was operated at maximum productivity and had safety margins adequate  
815 to ensure reliable operation, react fast on disturbances and avoid unstable process conditions. Lara-Cisneros *et*  
816 *al.* (2015) proposed an ESC scheme with sliding mode to achieve the dynamic optimization of methane outflow  
817 rate in anaerobic processes. The control law was designed to regulate VFA concentration at the optimal value  
818 whilst maximizing methane production. However, only numerical experiments illustrated the performance and  
819 robustness of the proposed control approach.

820  
821 Concerning the need of sensors for control purposes, even if there now exists a large variety of devices for  
822 measuring almost all key variables, they still remain relatively expensive for medium and small enterprises,  
823 mainly in developing countries. In this sense, the challenge to control AD processes is to do it with a minimum  
824 of information, even if it is obtained off-line. In this context, discrete control approaches are beginning to be  
825 used (Méndez-Acosta *et al.* 2011).

826

### 827 3.2 - Control in Anaerobic co-Digestion (AcoD)

828

829 Anaerobic co-digestion (AcoD) presents higher potential energy recovery than conventional single substrate AD.  
830 Therefore, high effort has been focussed on AcoD in order to: 1) enhance process performance thus maximising  
831 biogas production; 2) navigate into the use of new co-substrates; and 3) increase process feasibility by the  
832 application of digestates for agricultural purposes (Mata-Alvarez *et al.* 2014).

833

834 For instance, biogas production has been classically improved by co-digesting manure and organic waste (see,  
835 for instance, Ahring *et al.* 1992; Tafdrup 1994). Since manures are often associated with poor methane yields,  
836 AcoD of manure with other organic wastes has been identified as a cost-effective alternative for improving  
837 process efficiency (Mata-Alvarez *et al.* 2011; Frigon *et al.* 2012; Astals *et al.* 2013b)). This co-digestion process  
838 is usually optimised when biogas yield is above 30 m<sup>3</sup> biogas per m<sup>3</sup> biomass treated, which normally requires a  
839 25% organic waste ratio (Boe 2006). Nevertheless, lower ratios may be enough when treating concentrated  
840 wastes (Gregersen 2003).

841

842 Other classical AcoD process is the co-digestion of sewage sludge with the organic fraction of municipal solid  
843 waste (OFMSW). Besides the biowaste composition (food waste, market waste, etc.), biogas production during  
844 the co-digestion of sewage sludge and biowaste highly depends on several factors such as sewage sludge  
845 composition (primary, secondary or mixed), OLR, reactor configuration, operating temperature or mixing  
846 conditions (Mata-Alvarez *et al.* 2011). For instance, Silvestre *et al.* (2015) assessed the effect of OFMSW  
847 loading rate and particulate size on sewage sludge mesophilic anaerobic co-digestion in a CSTR operating at 20  
848 days of SRT. This study revealed that sewage-sludge–OFMSW mixture composed by 54% of inlet volatile solids  
849 (OLR of 3.1 kg COD m<sup>-3</sup> d<sup>-1</sup>; 1.9 kg VS m<sup>-3</sup> d<sup>-1</sup>) resulted in an increased in volumetric methane production and  
850 methane yield of up to 200 and 59%, respectively.

851

852 Recent literature has reported increasing interest by the scientific community on the applicability of AcoD to  
853 new biowastes. For instance, co-digesting sewage sludge and microalgae is considered one promising technology  
854 for energy production, whilst representing a key step for recycling nutrients for algal cultivation (Ward *et al.*  
855 2014). Recent research has shown that AcoD can increase anaerobic degradability of algae by improving  
856 substrate composition. Nevertheless, further research is needed since the quantity and quality of the produced  
857 biogas vary considerably depending on anaerobic inocula, waste composition and operating conditions (Ajeej *et*  
858 *al.* 2015).

859 The control of AcoD processes can be addressed following the same strategies used for classical AD processes.  
860 However, it is crucial to characterise comprehensively the co-substrates and to choose adequately the blend of  
861 substrates to be treated (García-Gen 2015).

862

863 Alvarez *et al.* (2010) developed a methodology for optimising feed composition in AcoD of agro-industrial  
864 wastes. This optimisation protocol was based on a linear programming method aimed to set up different blends  
865 for maximising the total substrate biodegradation potential ( $L_{CH_4} \cdot \text{kg}^{-1} \text{ substrate}$ ) or the biokinetic potential ( $L_{CH_4}$   
866  $\cdot \text{kg}^{-1} \text{ substrate} \cdot \text{d}^{-1}$ ). To this aim, the controller defined restrictions on several characteristics of the mixture,  
867 such as  $\text{NH}_4^+$ , lipids or C/N ratio. The methodology was validated using three types of agro-industrial biowaste:  
868 pig manure, fish waste and biodiesel waste. Validation results were related to the mixture of biowaste to be feed  
869 to the AcoD process in order to maximise biodegradation potential and methane production. Linear  
870 programming was proved to be a powerful, useful and easy-to-use tool to estimate methane production in co-  
871 digestion units where different substrates can be fed (Alvarez *et al.* 2010).

872

873 Wang *et al.* (2012) proposed optimizing the feeding composition and the carbon/nitrogen (C/N) ratio for  
874 improving methane yield during AcoD of multi-component substrates (dairy, chicken manure and wheat straw).  
875 The results showed that co-digestion performed better than individual digestion in terms of methane potential.  
876 Maximum methane productions were achieved with a dairy/chicken manure ratio of 40:60 and a C/N ratio of  
877 27:1 (after optimization using response surface methodology). The results suggested therefore that better  
878 performance of AcoD can be fulfilled by optimizing feeding composition and C/N ratio.

879

880 Wang *et al.* (2013a) evaluated two statistical methods for optimizing feeding composition in AcoD systems. To  
881 this aim, a simplex-centroid mixture design (SCMD) and central composite design (CCD) were evaluated using  
882 methane potential as response variable. Each co-substrate (dairy manure, chicken manure, swine manure and rice  
883 straw) served as an independent variable in SCMD and CCD, involving two factors: the manure and C/N ratios  
884 together with the C/N ratio of the blend. Experiments demonstrated that co-digestion of three-component  
885 substrates resulted in higher methane potentials, as well as on better fitted models to predict the response based  
886 on selected variables. In response surface plots, SCMD showed the interactions among each component in the  
887 co-substrates and CCD presented the interaction between the ratio of manures and the C/N ratio. SCMD and  
888 CCD were both suitable methods for optimizing feeding composition during anaerobic co-digestion.

889 Jiménez *et al.* (2014) optimised methanogenic activity using the response surface methodology during the AcoD  
890 of agriculture and industrial wastes. This optimisation accounted for microbial community performance, taking  
891 into account the effect of each substrate concentration and their interactive effects on specific methanogenic  
892 activity and microbial community diversity. The results showed a significant interaction among the substrates

893 and an enhancement of the methane production and specific methanogenic activity. The optimization allowed  
894 identifying substrate interaction effects in a concentration range with a reduced number of experiments. The  
895 model validation proved to be useful for defining optimal combination of wastes in AcoD systems.

896  
897 García-Gen *et al.* (2015) proposed a control strategy for optimising AcoD in terms of methane productivity,  
898 digestate quality and process stability. To this aim, a linear programming approach was adopted to calculate the  
899 feeding of multiple substrates for maximum methane productivity, taking into account restrictions based on  
900 experimental and heuristic knowledge. Alkalinity ratio measurements against reference values were used for  
901 quantitatively assessing process stability by using an empirical diagnosis function. A second empirical diagnosis  
902 function was defined to compare methane flow rate measurements against a reference value of maximum  
903 capacity. The quantitative change applied to the most active constraint of the substrate blend optimisation  
904 problem (leading to a new set-point of feeding substrates blend) was calculated by a variable-gain control  
905 function derived from the previously commented diagnosis functions. This closed-loop control architecture was  
906 successfully validated in a 1 m<sup>3</sup> hybrid Upflow Anaerobic Sludge Blanket – Anaerobic Filter (UASB-AF)  
907 reactor, treating blends of substrates (gelatine, glycerine and pig manure supernatant) at OLR values between  
908 0.71 and 6.33 gCOD·L<sup>-1</sup>·d<sup>-1</sup>. The proposed controller was capable to increase methane productivity whilst  
909 recovering the system from transient acidifications.

910

### 911 3.3 - Sulphide Control

912

913 Different control strategies can be applied to minimize problems related to sulphide in the system (Cirne *et al.*  
914 2008). The monitoring of sulphate in the influent cannot be considered as a realistic option since sulphate  
915 concentration in the influent cannot be predicted nor monitored. Final removal of sulphide (e.g. desulphuration  
916 of biogas) is based on the application of different physico-chemical or biological techniques sometimes requiring  
917 additional treatment units:

- 918 - selective inhibition of SRB using compounds such as nitrite, antibiotics, or molybdate. However, these  
919 actions are not very effective when operating continuous AD processes and they also present a negative  
920 effect on MA.
- 921 - pH increase in order to move the H<sub>2</sub>S/HS<sup>-</sup> equilibrium towards less toxic HS<sup>-</sup>.

- 922 - sulphur precipitation using organic or inorganic compounds (mainly iron salts). The main drawbacks of  
923 this technique are the reagent cost, the increase in sludge production and possible pipes obstructions  
924 from precipitates.
- 925 - H<sub>2</sub>S stripping by high stirring in the reactor, recycling the produced biogas after scrubber or other H<sub>2</sub>S  
926 removal technologies.
- 927 - oxidation of sulphide with oxygen or nitrate using chemical or biological processes. This process  
928 consists of introducing small amounts of these compounds without affecting process performance (van  
929 der Zee *et al.* 2007; Cirne *et al.* 2008; Fdz-Polanco *et al.* 2009a; 2009b).

930

### 931 3.4 - Control of Anaerobic Membrane Bioreactors (AnMBR)

932

933 Several operating strategies to control membrane fouling in anaerobic or aerobic membrane reactors have been  
934 experimentally validated. For example, Jeison and van Lier (2006) developed an on-line cake-layer management  
935 protocol that monitored critical flux constantly and prevented excessive cake-layer from building up on the  
936 membrane surface; Smith *et al.* (2006) developed a control system to optimize back-flushing which reduced the  
937 water needed for back-flushing by up to 40%; Vargas *et al.* (2008) established a control algorithm for fouling  
938 prevention which regulated back-flushing and Park *et al.* (2010) studied how membrane fouling could be  
939 reduced by successively increasing and decreasing membrane gas sparging intensities, and recorded the  
940 effectiveness in reducing membrane fouling.

941

942 Anaerobic membrane bioreactors (AnMBR) can be very efficiently used to treat urban wastewater but they  
943 require more sophisticated process control systems than for aerobic MBR systems or other conventional  
944 anaerobic systems – such as up-flow anaerobic sludge blanket (UASB); expanded granular sludge blanket  
945 (EGSB); or anaerobic filters (AF). For example, Robles *et al.* (2014) implemented a model-based supervisory  
946 controller to optimize filtration in an AnMBR demonstration plant. Energy savings of up to 25% were achieved  
947 when using gas sparging to scour membranes and the downtime for physical cleaning was about 2.4% of  
948 operating time. The operating cost of the AnMBR system after implementing the proposed supervisory controller  
949 was about €0.045/m<sup>3</sup>, 53.3% of which were energy costs. In another application, Robles *et al.* (2013; 2015)  
950 obtained similar results using a 2-layer control system measuring the treatment flow rate (controlling the HRT),  
951 the sludge wasting volume (controlling the SRT), the temperature, and the gas sparging intensity in the anaerobic

952 reactor and controlling the permeate flow rate, the trans-membrane pressure (TMP), the sludge flow-rate  
953 recycled through the membrane tanks, and the gas sparging intensity in the membrane tanks.

954

955

#### 956 **4 – What is next?**

957

958 Many ideas and many perspectives arise from all the above details about current scientific and technical  
959 achievements.

##### 960 *Instrumentation*

961 With respect to instrumentation, it is indeed believed that (1) more and more advanced sensors will be soon  
962 available (2) confidence index associated to the measurements will provide human operators with the ability to  
963 decide on the best actions based on the quality of the measurements (3) sensors network will allow the human  
964 operator to anticipate future problems, (4) software sensors and (5) use of large data base and all of this will  
965 improve by far the information content currently retrieved from AD plants. The simultaneous use of a sensor  
966 network (Steyer *et al.* 2004) and of numerical models will clearly help in extending and qualifying the available  
967 measurements.

968 As pointed out earlier in the paper, the analysis of individual VFA species has often been proposed as an  
969 important measurement parameter for the diagnosis, optimisation and control of anaerobic processes. Most of  
970 this information is today collected off-line and are mainly based on either GC or HPLC analysis and have been  
971 benchmarked comprehensively in Raposo *et al.* (2013). As off-line monitoring of VFAs is likely to have a  
972 significant lag in measuring VFA and inputting the data into a feedback control loop would have significant  
973 draw backs due to the time delay in analysis and inputting the data. There is a significant challenge to overcome  
974 in producing an instrument for on-line or at-line species specific VFA analysis that is relatively easy to operate at  
975 low capital and operational cost. There has been a significant amount of activity directed automating off-line  
976 techniques in particular GC headspace techniques (Boe *et al.* 2007 and Boe *et al.* 2008) but there has been  
977 limited uptake for this method beyond the initial publications. An alternative approach has been the use of Near  
978 Infra Red Spectroscopy (NIRS) for acetate, propionate and TVFA analysis but the NIR analyser despite  
979 requiring relatively little maintenance was found to have a too high error of prediction for accurate quantification  
980 (Ward *et al.* 2011). An alternative approach to the traditional analytical techniques of GC, HPLC or IR  
981 spectroscopy may be to use biosensors as the measurement system. This offers the potential of a relatively low

982 cost sensor system, with high specificity and sensitivity and no requirement for continuous supply of a chemical  
983 or gaseous mobile phase as required by GC or HPLC techniques. An approach based on microbial fuel cells  
984 (Kaur *et al.* 2013; 2014) and genetically engineered light emitting bacteria (Li and Yu 2015) have been proposed  
985 as possible solutions to develop a more effective on-line VFA instrument. A microbial fuel cell based biosensor  
986 was able to discriminate between acetate, propionate and butyrate, with a response time of 1-2 minutes with a  
987 sensitivity of 5 mg.L<sup>-1</sup> when cyclic voltammetry analysis was utilised (Kaur *et al.* 2013). The sensor linearity  
988 was limited to 5-40 mg.L<sup>-1</sup> but this could be addressed with appropriate sample dilution. An alternate biosensor  
989 approach using a genetically engineered *E. coli* based biosensor with light emitting response to propionate has  
990 been demonstrated with a linear response of 1-10 mM (Li and Yu 2015), however other VFAs such as acetate  
991 and butyrate are important species in anaerobic digestion require measurement. Despite a number of innovative  
992 approaches taken to measuring individual VFA species, an effective and low cost instrument for the on-line or at  
993 line measurement has yet to be identified.

994

995 In the first section dedicated to the instrumentation, the lack of “sensors” for monitoring biodegradability and  
996 bioaccessibility has been highlighted. As pointed out by the substrate evolution, agricultural and municipal solid  
997 wastes are more and more used. This kind of complex substrates need long HRT and the off-line option can be  
998 acceptable in order to drive their digestion or co-digestion.

999 Despite the fact that several tools are promising like NIRS for biodegradability prediction, this technique is, until  
1000 now, applied on dried-frozen samples and the impact of drying samples on the BMP values obtain with not  
1001 prepared sample has not been studied. As previously mentioned, NIRS technology has a great potential as  
1002 sensor, and work has to be followed to develop a probe able to predict BMP value on raw samples. However,  
1003 this technique does not give bioaccessibility or biodegradation rate parameters. In the case of co-digestion for  
1004 example, these parameters are crucial. Other study does it in a faster way than BMP test (for example, Jimenez *et*  
1005 *al.* 2014) but it needs advanced knowledge of the methodology used and advanced and expensive material (i.e.  
1006 3D fluorescence spectroscopy). Therefore, more efforts have to be done on how to transpose these promising but  
1007 complex techniques into a cheap and practical “sensors”. For example, research on multi-excitation wavelength  
1008 fluorescence probes would be done, and, associated with an optimized chemical extraction protocol would be  
1009 able to predict both biodegradability and bioaccessibility. These kinds of information would be very valuable in  
1010 order to predict the optimal mixture to do during co-digestion for example.

1011

1012 As previously mentioned, spectroscopic on-line sensors are of particular interest to the AD industry and research  
1013 as they allow the on-line monitoring of crucial process variables. Nevertheless, high prices and complex  
1014 calibration routines hinder commercial success. Newly developed tunable Micro-Electronic-Mechanical-System  
1015 (MEMS) based Fabry-Pérot interferometers for the UV/vis, NIR and MIR wavelength ranges provide a very  
1016 promising solution. Not only are these spectrometers on a chip very small 5 x 10 cm but also relatively cheap, if  
1017 manufactured in big numbers. Currently, two different system designs exist. Neumann *et al.* (2010) introduced a  
1018 tunable MEMS interferometer for the middle- and long-infrared range using a pyro-detector. The different  
1019 wavelengths can be generated by two bragg reflectors whose distance can be changed by a spring suspension.  
1020 Although, the presented performance results are good, the spring suspension is considered to be a weakness as it  
1021 makes the spectrometer sensitive to vibration and wear. Therefore, the Technical Research Centre of Finland  
1022 (VTT) developed an interferometer design with piezo-effect based tuning of the gap between the reflectors  
1023 (Antila *et al.* 2014, Mäkynen *et al.* 2014). In general, these MEMS systems allow for completely new probe  
1024 designs where the spectrometer is directly integrated into the probe so that the fibre length can be reduced  
1025 significantly, increasing the S/N ratio. Thus, not only the sensitivity of a sensor is increased but also the size of  
1026 the whole sensor system is reduced. This particularly important for MIR sensors where a short fibre length is  
1027 crucial to guarantee a high S/N ratio. Malinen *et al.* (2014) gives a broad overview of the possibilities in various  
1028 applications. In high quantities, prices for MEMS spectrometers are expected to drop to 70-100€ per piece,  
1029 which makes spectroscopic sensors attractive for the use in AD plants.

1030

1031 Confidence indexes are information about the way measurements are obtained. One important lesson from  
1032 applying ICA in AD plants is that some sensor technologies are more useful than other ones. Indeed, if all on-  
1033 line sensors provide numerical values of the measured variables, some (e.g. spectrometer or titrimeter) also  
1034 provide information on how the measurements have been obtained (Steyer *et al.* 2006). This information can  
1035 then be used as a confidence index on the measurement and is of great help to decide – in a closed loop context –  
1036 if a control law can rely or not on the obtained measurements. In order to guarantee a safe operation of the plant,  
1037 the controller can indeed be turned off in case of sensor fouling or any other dysfunctionning in the instrument.  
1038 However, this increase in complexity in the management of the sensor data and the automation of the process  
1039 may involve dedicated highly qualified operators for permanently recalibrating and adapting the complex  
1040 implemented algorithms. Indeed, most of the monitoring, diagnosis or control advanced strategies which are  
1041 described on Table 4 have been tested (when they have been experimented) on short time periods (generally less

1042 than a few weeks), with a precalibrated set of parameters and initial conditions. These additional degrees of  
1043 freedom, which are rarely clearly stated, must be managed on the long term for operational perspectives. Better  
1044 accounting for such degrees of freedom, automating these aspects to reach robust autoadaptive algorithms, or  
1045 allowing a remote expert to manage them (Bernard *et al.* 2005a; 2005b) is thus a challenge for the future years.

1046

#### 1047 *Models and virtual sensors*

1048 Even if modeling AD has been an active research topic these last two decades, improving the models supporting  
1049 monitoring and control strategies is also very challenging. Due to the increasing complexity of the substrates,  
1050 hydrolysis was considered as the limiting step introducing the notion of bioaccessibility. Based on the  
1051 degradation kinetics of the sludge, new variables appeared by taking into account the bioaccessibility of the  
1052 substrate. A better knowledge of the sludge composition indeed leads to more realistic although more complex  
1053 models. However, despite the techniques described the literature until now, input variables of ADM1 are still  
1054 difficult to characterize. Advanced analytical techniques could provide a higher degree of information on the  
1055 composition of any given substrate. Promising new tools can be used for direct measurement, such as NIRS, 3D-  
1056 EEM SPF and LIF probes in order to describe the biodegradability of a waste. However, with the  
1057 biodegradability, the bioaccessibility is a key concept of the model input variables characterization. Some studies  
1058 proposed bioaccessibility assessment specific to sewage sludge. Further investigations need to be performed in  
1059 order to find a relevant and rapid tool for organic matter characterization of more solid wastes in order to obtain  
1060 reliable parameters for the biological processes models. ADM1 is sensitive to the substrate composition, and a  
1061 methodology providing characterization rules based on substrate type using either upstream knowledge,  
1062 chemical analysis (for simple substrates), or biochemical testing would greatly improve the predictability  
1063 potential of the models (Batstone 2013), and then their further efficiency in monitoring and control strategies.

1064

1065 A more accurate description of the physicochemical models, and especially of the precipitation related to  
1066 calcium and phosphorus (Batstone *et al.* 2012) is a difficult yet necessary step to better understand the cycle of  
1067 phosphorous. Even if it may strongly increase the model complexity, considering sulfur reduction and oxidation  
1068 processes are also challenges for the future. Also, the spatial distribution of the chemicals and biomasses within  
1069 the reactor should now be accounted for and integrated in the models. These points should be seen in a larger  
1070 context than AD, and a plant wide approach (see e.g., Olsson *et al.* 2014) must prevail. For example,

1071 physicochemical models must describe phosphate speciation and release under aerobic and anaerobic conditions,  
1072 while micropollutants must be tracked along the full treatment plant.

1073

1074 Soft sensing or virtual sensing is the use of models to predict process parameters that are expensive or difficult to  
1075 measure from more accessible process measurements. They are an effective method of providing in-line  
1076 estimates of quantities that are difficult to measure on-line, and as such offer the possibility of providing  
1077 enhanced monitoring of processes, both in terms of providing additional process information and acting as a  
1078 reference for sensor fault detection. They have previously been demonstrated for estimating parameters such  
1079 alkalinity, chemical oxygen demand, inorganic carbon, and volatile fatty acids in waste water treatment plants  
1080 (Bernard 2011) and more recently for total alkalinity in biogas plants (Ward *et al.* 2011). However, development  
1081 and updating of soft sensor models requires expert knowledge due to the complex modeling techniques required  
1082 and the need for tailored training data, putting them beyond the research of most small scale biogas plant  
1083 operators. Newly developed powerful Machine Learning methods facilitate soft sensor development because of  
1084 their ability to learn vastly complex and nonlinear relationships (Gaida *et al.* 2012). Further research in this area  
1085 is necessary to tap the full potential of the existing methods with regard to AD processes.

1086

1087 *Control*

1088 With respect to both observer and control design, one may also expect the development of high power  
1089 computation capacity will fundamentally change our way of thinking. Modern control techniques usually  
1090 necessitate the use of a limited order model to be able to guarantee stability and performance robustness.  
1091 Techniques based on particulate filters (Cf. for instance Goffaux and Van de Wouwer (2005) and Benyahia *et al.*  
1092 (2012) for applications to chemostat models) coupled with the use of nonlinear optimal controllers present the  
1093 advantage of being able to use complex model while dealing with uncertainty. Of course, the price to pay is a  
1094 relatively less degree of guarantee but the higher the on-line computer capabilities, the higher the state space to  
1095 be investigated and the lower the probability to push the process towards a dangerous functioning zone. Another  
1096 promising route concerns the use of innovative passive control approaches in which control objectives are  
1097 considered at the initial conception step of the process. In terms of performances, it is for instance well known  
1098 that series of reactors perform better than single processes. However, this design may penalize both investment  
1099 costs and the stability of the process since reducing the size of the first reactor. The introduction of alternative  
1100 configurations of the different reactors and the judicious choice for their respective volumes may lead to a more

1101 robust global system with respect to specific uncertainty and disturbances (if compared to a single tank reactor),  
1102 cf. for instance the work by Rapaport *et al.* (2014) on the stabilization of chemostats with substrate-inhibited  
1103 kinetics.

1104  
1105 It is usually expected that a controller using a more complex model would lead to better performances.  
1106 Assuming the on-line computation capability is available, it may be true. But the use of very simple models from  
1107 which a control may "really" be optimal with respect to a given performance index, from a mathematical  
1108 viewpoint, may be helpful to think of new control strategies. For instance, the work by Sbarciog *et al.* (2010)  
1109 allowed us to propose a new control strategy able to guarantee sub-optimal performances while preserving the  
1110 stability of the whole process (Rodriguez *et al.* 2013).

1111  
1112 Microbial management of bioprocesses is another emerging topic with a great potential. This is particularly true  
1113 for AD which involves a huge biodiversity (Carballa *et al.* 2015). Thanks to the development of molecular  
1114 analytical tools (denaturing gradient gel electrophoresis, single-strand conformation polymorphism...), the  
1115 anaerobic microbiome has been more and more characterized (Vanwonterghem *et al.* 2014, Sundberg *et al.*  
1116 2013). Considering the biodiversity can give raise to a new paradigm for the control and optimization of AD.  
1117 Until now, the principal objective of control was to stabilize the digester. Nonetheless, a stable process tends to  
1118 reduce the biodiversity through the selection of the fittest species in the imposed environment. Although this  
1119 selection process could increase the steady-state performance, it could seriously alter the resilience of the process  
1120 (Ramirez *et al.* 2009). Dynamical feeding has been proposed in order to select a microbiome with a high ability  
1121 to adapt to disturbances (De Vrieze *et al.* 2013). Bioaugmentation have been also applied, in particular in  
1122 response to stress (e.g. Schauer-Gimenez *et al.* 2010; Tale *et al.* 2011). Concerning the model-based control  
1123 laws, most of them are designed assuming one population for one function. Recently, Mairet and Bernard (2014)  
1124 have proposed to evaluate the performances of such control laws when several species are present. Using the  
1125 control law proposed by Mailleret *et al.* (2004) as an example, they have shown that a slow-growing species can  
1126 lead to reactor shutdown. This framework can be used to design robust control laws which better tame  
1127 biodiversity. Rapaport and Harmand (2002) also proposed a "biocontrol" strategy using biotic microbial  
1128 ecosystem capabilities to select certain species. Although attractive, these approaches remain studied in  
1129 simulations only. The control of the microbiome involved in AD is an exciting challenge for the future, but the  
1130 lack of on-line instrumentation for biodiversity monitoring can limit process implementation. Recently, on-line

1131 flow cytometers have been proposed for AD (Koch *et al.* 2014) and can open new directions for closed-loop  
1132 microbial control strategies.

1133 Recently, novel potential actuators emerged to control methanogenic pathways (Liu *et al.* 2013; Lin *et al.* 2013).  
1134 Indeed, methanogenic pathways (i.e. acetoclastic or hydrogenotrophic) have been analyzed using stable carbon  
1135 isotope signature. This analysis is made on the biogas phase and thanks to an isoprime mass spectrometer linked  
1136 with a gas chromatography, a carbon fractionation can be performed. This information is very valuable because  
1137 it points out the contribution of the different methanogenic pathways producing methane and carbon dioxide. For  
1138 example, Liu *et al.* (2013) made cartography of the methanogens type depending on ammonium and acetate high  
1139 concentrations. In the same way, Lin *et al.* (2013) showed the impact of the addition of bicarbonate on the  
1140 methanogenic biodiversity. This kind of information would be very valuable in order to drive a digester in case  
1141 of acid or/and ammonia inhibition, without loose energetic performance.

1142 The balance between the synergistic production and consumption of VFA intermediates in the AD with respect  
1143 to process stability is important and has been outlines in section 3.1. Disagregation of the trophic groups in the  
1144 AD process by physically separating them into an acidogenic stage reactor and a methanogenic stage reactor is  
1145 not a new idea. Two stage AD, often with the intention of improving hydrolytic processes, has been studied by  
1146 many researcher over the last 40 years e.g. Ghosh *et al.* (1975). However, increased scope for control actuation  
1147 may be available by such stage separation especially with the ability to monitor and manage microbial  
1148 populations more effectively in recent years. Furthermore, the stages can be integrated with each other and other  
1149 processes to improve gas yields as reported by Massanet-Nicolau *et al.* (2013). Guwy *et al.* (2011) described  
1150 how the integration of multi stage bioprocesses can be used to extract or utilize the products. The extraction of  
1151 VFAs for example may simultaneously deliver valuable chemicals and controlled supply of substrate for  
1152 methanogenesis to a subsequent stage. This VFA extraction may be achieved by conventional electro dialysis, as  
1153 proposed by Jones *et al.* (2015) in an acidogenic stage also generating hydrogen. VFAs are also an appropriate  
1154 substrate for bioelectrochemical systems as has been demonstrated by many researchers and reviewed by Pant *et*  
1155 *al.* (2010). The application of multivariable control strategies as described in this paper may deliver optimal  
1156 system performance, although control of each of the stages or sub-processes may be independently controllable  
1157 under a system level supervisory regime.

1158 The capacity of ADs to utilize additional CO<sub>2</sub> was demonstrated by several authors, which could provide a  
1159 potential solution for on-site sequestration of CO<sub>2</sub> streams while enhancing methane production by CO<sub>2</sub>  
1160 sparging. CO<sub>2</sub> could then become an efficient actuator to improve AD performances. Few studies have indeed

1161 considered the potential of CO<sub>2</sub> biological conversion in anaerobic processes, reporting benefits both in terms of  
1162 carbon uptake and renewable energy production (Salomoni and Petazzoni 2006; Salomoni *et al.* 2011).  
1163 Interestingly, microorganisms operating under CO<sub>2</sub> saturated conditions continue to synthesize CH<sub>4</sub>.  
1164 Alimahmoodi and Mulligan (2008) stated a 69–86% CO<sub>2</sub> uptake when dissolving this gas in the influent of an  
1165 upflow anaerobic sludge blanket (UASB) reactor. Francioso *et al.* (2010) and Salomoni *et al.* (2011) further  
1166 confirmed the potential of CO<sub>2</sub> biological conversion in two phase anaerobic digestion (TPAD), and observed  
1167 25% methane (CH<sub>4</sub>) yield enhancement when sparging CO<sub>2</sub> into the first stage. Moreover, the net production of  
1168 CO<sub>2</sub> in CO<sub>2</sub>-recirculating AD units can be reduced by a factor of 4. Fernández *et al.* (2014) addressed the  
1169 reduction of CO<sub>2</sub> emissions and enhancement of biogas production associated with CO<sub>2</sub> enrichment of anaerobic  
1170 digesters (ADs). The benefits of CO<sub>2</sub> enrichment were examined by injecting CO<sub>2</sub> at 0, 0.3, 0.6 and 0.9 M  
1171 fractions into batch ADs treating food waste or sewage sludge. Daily specific methane (CH<sub>4</sub>) production  
1172 increased 11–16% for food waste and 96–138% for sewage sludge. Potential CO<sub>2</sub> reductions of 8–34% for  
1173 sewage sludge and 3–11% for food waste were estimated. Mohd Yasin *et al.* (2015) used CO<sub>2</sub> as the substrate to  
1174 generate methane by enriched methanogens after anaerobic enrichment of waste activated sludge (WAS) and  
1175 they demonstrated that methanogens from WAS have significant potential for converting the greenhouse gas  
1176 CO<sub>2</sub> into the fuel methane. Moreover, methane production was increased 70 fold by active methanogens in the  
1177 enriched methanogens culture after 3 days in the presence of H<sub>2</sub> and CO<sub>2</sub>.  
1178 Indeed, the addition of H<sub>2</sub> into an anaerobic digestion has been performed in several studies (Luo *et al.* 2012;  
1179 Luo and Angelidaki 2013; Wang *et al.* 2013b; Díaz *et al.* 2015) in order to remove CO<sub>2</sub> from biogas while  
1180 methane production increased, through the hydrogenotrophic pathway. For example, Luo *et al.* (2012) showed  
1181 that increasing both hydrogen partial pressure and mixing intensity would give 22% of methane production. One  
1182 main barrier highlighted was the gas-liquid mass transfer of H<sub>2</sub> because of the low solubility of this gas.

1183

## 1184 **Conclusions and perspectives**

1185

1186 Over the years, knowledge on anaerobic digestion has increased and several instruments are now available to  
1187 monitor efficiently the AD processes. Global parameters for organic matter characterization can indeed be used  
1188 and biodegradability, bioavailability and bioaccessibility of complex solid substrates can be assessed. Modelling,  
1189 especially through the development and consolidation of the ADM1 model, has successfully proven its ability to  
1190 translate the biological steps occurring in the AD. Since its creation, many improvements have been carried out,

1191 and ADM1 has been tailored to a broad variety of substrates. But there are still progresses to be accomplished to  
1192 better manage the influent composition, and further represent physicochemical processes such as precipitation.  
1193 There is still a gap between these more and more accurate models, but also involving higher degrees of  
1194 freedoms, and simpler models which support most of the monitoring, diagnosis and control algorithms. Bridging  
1195 this gap, combining these theoretical approaches with information provided by innovative sensors, and reducing  
1196 expert needs to run these algorithms will probably significantly improve the attractiveness of the approach  
1197 together with its efficiency.

1198  
1199 These developments will also contribute to improve emerging processes such as thermophilic and ultra-high rate  
1200 processes (Ge *et al.* 2011), or supporting co-digestion strategies (Mata-Alvarez *et al.* 2011). Modelling,  
1201 monitoring and control are also expected in the objective of recovering nutrients (Mehta and Batstone 2013) and  
1202 for tracking micropollutants, trace organics, pathogens and recalcitrant (Fountoulakis *et al.* 2008).

1203

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1208

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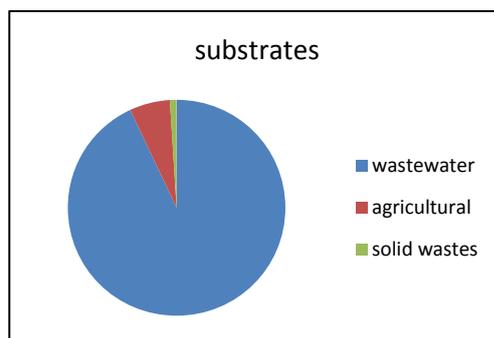
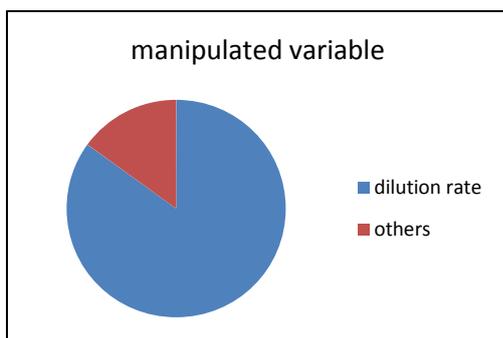
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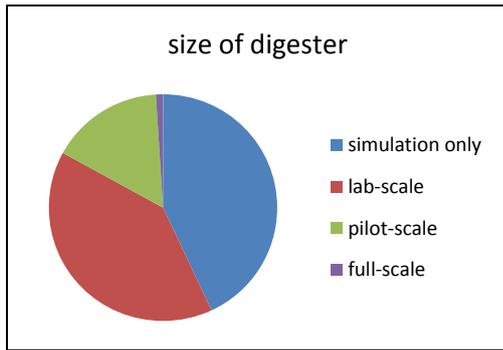
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 1868 **Figure 1:** Percentage distribution of manipulated variable (121 publications), size of digester (134 publications)  
 1869 and substrates (109 publications) of the reviewed publications.

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**Table 1:** Summary of the different methodologies used in integrative tools found in the literature

Integrative tools	Characterization methods	Benefits	Drawbacks	References
Static model PLS, correlations, Stoichiometric reaction	Biochemical characterization Proteins, carbohydrates, lipids, COD/TOC, TOC soluble	Analytical simple and rapid methods	Model validation not yet achieved Based on one type of sludge (secondary) Care to be taken of the accuracy of methods used Not take into account complexity and accessibility	<i>Mottet et al. (2010)</i>
	CHNOS elemental analysis	Fast and practical method	Consideration of the whole organic matter degradation: the biodegradable fraction is not used Over-estimation of BMP tests	<i>Shanmugam and Horan (2009)</i>
	Van Soest and fibers analysis	Faster and practical method Validation on several solids wastes Accessibility taking into account with growing extraction power	Not suitable for sewage sludge in terms of protocol (porosity) Model validation not conclusive	<i>Chandler et al. (1980)</i> <i>Gunaseelan (2007)</i> <i>Mottet et al. (2010)</i>
	Aerobic respiration rate	Faster than a BMP test (4 days instead of 21-30 days) Promising on solid wastes	Only readily substrate taken into account No accessibility taken into account Assumption on the same biodegradability under aerobic and AD	<i>Cossu and Raga (2008)</i> <i>Scaglia et al. (2010)</i>
	Initial rate technique	Faster method than BMP Maximum production rate and affinity constant determined	Extrapolation in continuous digester underestimate methane production Not information on substrate bioaccessibility	<i>Donoso-Bravo et al. (2011)</i> <i>Strömberg et al. (2015)</i>
	Biochemical characterization bioaccessibility compartment	Bioaccessibility taken into account Biochemical fractions calculated from practical analysis	Necessity of long batch test for fractions assessment	<i>Yasui et al. (2006, 2008)</i> <i>Mottet et al. (2010)</i>
	NIRS	Biodegradability assessment Fast Various type of substrates	Necessity of drying and freezing the sample Bioaccessibility not taken into account	<i>Lesteur et al. (2010)</i> <i>Doublet et al. (2013)</i>
	3D fluorescence spectroscopy combined with accessibility characterization	Bioaccessibility taken into account Both biodegradability and bioaccessibility predicted Fast method	Calibrated on sludge-like samples	<i>Jimenez et al. (2014)</i>

**Table 2: Analytical protocols for biochemical compounds determination**

Organic fraction	Method type	Concentration (mg/L)	Reagent used	Standard	Reference
Proteins	Colorimetric	0-200	Folin reagent Copper sulfate 0.5% (w/w)	Bovine albumin serum	Lowry et al., 1951
	Colorimetric	0-200	Bicinchonic acid		Frølund et al., 1996
	Colorimetric	0-100	Gornall biuret reagent and NaCl		Smith et al., 1985
	Colorimetric	2-120	Coomassie brilliant blue G-250 reagent		Gornall et al., 1949
	Standard method for TKN assesment	N content x 6.25 g proteins/gN	Mineralisation and ammonia dosage	None	Bradford, 1976
Humic acids like	Colorimetric	0-200	Folin Reagent	Humic acids (Aldrich)	Frølund et al., 1996
Polysaccharides	Colorimetric	0-100	Phenol 5% (w/w) Sulfuric acid 95%	Glucose	Dubois et al., 1956
	Colorimetric	0-100	Anthrone 0.125% (w/v) Sulfuric acid 95%		Dreywood et al. 1946 Raunkjær et al., 1994
Fibers	Extractions	-	Weende method Van Soest	None	Henneberg and Stohmann, 1860; Van Soest, 1963
Lipids	Colorimetric	0-1000	Vanillin 0.6% (w/w) Phosphoric acid 85% Sulfuric acid 95%	Commercial olive oil	Frings and Dunn 1970
	Extraction Infrared spectroscopy	-	CCl <sub>4</sub> , Uvasol, Al <sub>2</sub> O <sub>3</sub> , Na <sub>2</sub> SO <sub>4</sub> , HCL 6M	cornoil	APHA, 2005
	Extraction Gravimetry		Organic solvent	-	APHA, 2005

**Table ESM: Examples of AD controllers found in the literature**

Table ESM.1: Classical Control of Biogas Plants: on/off controls & PID controls

Control type	Authors	Description	Manipulated variable	Control variable
on/off	Rozzi (1984)	proposal of three controllers (1, 2, 3) purpose of stabilization application: simulation only	alkaline solution	1) pH 2) bicarbonate 3) pH, pCO <sub>2</sub>
on/off	Andrews (1974)	application: CSTR, simulation only, wastewater	recirculation	CH <sub>4</sub> flow rate
P deadband	Denac et al. (1990)	based on alkaline consumption Application: lab-scale FBR, wastewater	- dilution rate - alkali addition	- effluent VFA - pH
I deadband	Feitkenhauer et al. (2002)	application to an acidic phase reactor, goal: max. VFA application: lab-scale CSTR, wastewater	dilution rate	VFA
PI	Batstone and Steyer (2007)	proposal of two controls (1, 2) application: simulation only (ADM1), wastewater	dilution rate	1) VFA 2) alkalinity
PID	Marsili-Libelli and Beni (1996)	purpose: stabilization application: simulation only	bicarbonate addition	bicarbonate alkalinity

Table ESM.2: Classical Control of Biogas Plants: adaptive PID and PID cascade control

Control type	Authors	Description	Manipulated variable	Control variable
adaptive PI	Perrier and Dochain (1993)	proposal of three controllers (1, 2, 3) application: simulation only	dilution rate	1) effluent COD 2) dissolved H <sub>2</sub> 3) propionate
cascade P	Liu et al. (2004)	inner loop: pH; outer loop: gas flow rate setpoint of outer loop given by rule-based supervisory system lab-scale AFB reactor, wastewater, mesophilic	dilution rate	OLR
cascade P	Boe and Angelidaki (2012)	inner loop: VFA; outer loop: gas flow rate rule-based system as in Liu et al. (2004) application: pilot-scale CSTR, manure, thermophilic	dilution rate	CH <sub>4</sub> flow rate
cascade PI	Alvarez-Ramirez et al. (2002)	inner loop: VFA; outer loop: COD application: lab-scale UASB, wastewater	dilution rate	effluent COD
cascade PID	García-Diéguez et al. (2011)	inner loop: methane flow rate; outer loop: VFA application: pilot-scale UASB-AF, wastewater, mesophilic	dilution rate	- CH <sub>4</sub> flow rate - effluent VFA

Table ESM.3: Expert Systems Control of Biogas Plants: rule-based

Control type	Authors	Description	Manipulated variable	Control variable
expert system	Boe et al. (2008)	if propionate ..., then in-/decrease feed high fluctuations in biogas flow rate, because propionate is too persistent application: lab-scale CSTR, cow manure, thermophilic	dilution rate	propionate
expert system	Barnett and Andrews (1992)	rules implemented with fuzzy logic inputs: a lot; output: a few next to dilution rate application: simulation only	dilution rate	normal operation
expert system	Chynoweth et al. (1994)	rules based on CH <sub>4</sub> flow rate, its derivative, dilution rate and its derivative able to distinguish between overloading, underloading and inhibition application: lab-scale CSTR, wastewater, mesophilic	dilution rate	CH <sub>4</sub> flow rate
expert system	Moletta et al. (1994)	inputs: pH, biogas flow rate, H <sub>2</sub> content of biogas application: lab- and pilot-scale FBR, wastewater, mesophilic	dilution rate	normal operation
expert system	Ehlinger et al. (1994)	decision tree: pH, gas and H <sub>2</sub> flow rate application: lab-scale FBR, mesophilic, wastewater	dilution rate	normal operation
expert system	Flores et al. (2000)	application: start-up of pilot-scale UASB-AF reactor, wastewater	dilution rate	normal operation
expert system	Pullammanappallil et al. (1991, 1998)	bumpless switch between four different control strategies based on a t-test: 1) set-point control, 2) constant yield control 3) batch operation, 4) constant dilution rate application: lab-scale CSTR, wastewater, mesophilic	dilution rate	CH <sub>4</sub> flow rate
expert fuzzy system	Müller et al. (1997)	H <sub>2</sub> and CH <sub>4</sub> flow rate; uses Fuzzy C-Means Clustering of Marsili-Libelli and Müller (1996) application: lab-scale FBR, wastewater, mesophilic	- bypass - storage - dilution	normal, overload, inhibition, toxicity
expert fuzzy system	Puñal et al. (2001, 2002), Carrasco et al. (2002)	many input variables application: pilot-scale UASB-AF, wastewater	flow rates	over-, underload recovery

Table ESM.4: Expert Systems Control of Biogas Plants: fuzzy controls

Control type	Author	Description	Manipulated variable	Control variable
fuzzy P	Bernard et al. (2001)	inputs: TA, VFA/TA application: pilot-scale FBR, wastewater	dilution rate	VFA/TA
fuzzy P	Scherer et al. (2009)	inputs: pH value, CH <sub>4</sub> content and specific gas flow rate application: lab-/pilot-scale CSTR, agricultural, meso-/thermophilic	dilution rate	OLR
fuzzy I	Boscolo et al. (1993)	inputs: nine variables application: pilot-scale CSTR, OFMSW, thermophilic	- feed rate - TS of feed - recycling rates	normal operation
fuzzy P + PI	Murnleitner et al. (2002)	inputs: H <sub>2</sub> , CH <sub>4</sub> , biogas flow rate, pH, filling level application: lab-scale FBR, two-stage, wastewater, mesophilic	- different flows (PI) - pH (P) - temperature (P)	overload avoidance
fuzzy PI	Estaben et al. (1997)	inputs: error to setpoints of gas flow rate and pH value and the derivatives of the errors; output: change of feed rate application: lab-scale FBR, wastewater	dilution rate	- gas flow rate - pH value
fuzzy PI	Puñal et al. (2003)	inputs: error of VFA to its setpoint and its derivative output: change of feed rate application: pilot-scale AFB, wastewater	dilution rate	effluent VFA
fuzzy PI	Garcia et al. (2007)	inputs: CH <sub>4</sub> flow rate; H <sub>2</sub> content of gas; VFA/TA output: change of feed rate application: ADM1, lab-scale UASB-AF, wastewater	dilution rate	OLR
fuzzy PI cascade	Martinez-Sibaja et al. (2007)	- inner loop (conventional PI): pH - outer loop (fuzzy PI): gas flow rate application: simulation only	dilution rate	- gas flow rate - pH value

Table ESM.5: Expert Systems Control of Biogas Plants: neural networks and special fuzzy systems

Control type	Author	Description	Manipulated variable	Control variable
hierarchical fuzzy	Steyer et al. (1997)	inputs: control error of pH, T and biogas flow rate for a small rule-set a hierarchical fuzzy structure is chosen application: lab-scale FBR, wastewater, mesophilic	dilution rate	VFA
neural network	Holubar et al. (2002, 2003)	ANN models for: pH, VFA, biogas production and composition optimal COD loading rate is solution of max. CH <sub>4</sub> flow rate and COD degradation; application: lab-scale CSTR, primary sludge	COD loading rate	CH <sub>4</sub> flow rate
neural	Wilcox et al. (1995), Guwy et al. (1997)	ANN model for bicarbonate alkalinity (BA) out of past BA values application: lab-scale FBR, ice-cream and baker's yeast WW	BA dosing pump	bicarbonate alkalinity
neural network	Emmanouilides and Petrou (1996)	adaptive on-line trained neural networks application: simulation only	dilution rate	- CH <sub>4</sub> flow rate - effluent COD
neural fuzzy	Yordanova et al. (2004)	fuzzy PI, fuzzy tuning control application: simulation only, wastewater	dilution rate	Biogas flow rate
neural fuzzy	Waewsak et al. (2010)	ANN models for: pH, TA and VFA, predicted out of past values application: lab-scale UASB-AF, synthetic WW, mesophilic	dilution rate	- high performance - stability
fuzzy supervision	Carlos-Hernandez et al. (2007)	Takagi-Sugeno supervisor switches between: 1) open loop, 2) base addition (fuzzy PI), 3) dilution rate (fuzzy PI) application: FBR, wastewater, simulation only	- base addition - dilution rate	high performance
fuzzy supervision	Carlos-Hernandez et al. (2010a)	as in Carlos-Hernandez et al. (2007) PCA and Takagi-Sugeno estimate biomass and substrate application: CSTR, wastewater, simulation only	- base addition - dilution rate	CH <sub>4</sub> flow rate
fuzzy supervision	Gurubel et al. (2013)	as in Carlos-Hernandez et al. (2010a), additional using PSO to improve setpoint tracking	- base addition - dilution rate	CH <sub>4</sub> flow rate
neural fuzzy	Carlos-Hernandez et al. (2010b)	as in Carlos-Hernandez et al. (2007) neural observer trained by EKF estimates methanogenic biomass application: FBR, abattoir wastewater, simulation only	- base addition - dilution rate	high performance

Table ESM.6: Linearizing Control of Biogas Plants

Control type	Author	Description	Manipulated variable	Control variable
linearizing	Alvarez-Ramirez et al. (1996), Monroy et al. (1996)	adaptive, no need for measuring biogas flow rate application: lab-scale UASB, wastewater, mesophilic	dilution rate	effluent COD
linearizing	Petre et al. (2007)	adaptive, asymptotic state observer application: simulation only	dilution rate	effluent COD
feedback linearization	Angulo et al. (2007)	derivation using AM1 (Bernard et al., 2001a), model-based application: simulation only, AFB reactor, wastewater	dilution rate	effluent VFA
external linearization	Renard et al. (1988)	adaptive control, influent COD needs to be measured application: lab-scale CSTR, WW (citric acid), mesophilic	dilution rate	effluent COD
external linearization	Johnson et al. (1995)	Renard et al. (1988) approach used application: lab-scale AFB, wastewater, mesophilic	dilution rate	effluent COD
linearizing	Dochain and Perrier (1993)	direct adaptive linearizing application: CSTR, simulation only	dilution rate	propionate
linearizing	Bernard et al. (2001)	adaptive control, influent COD estimated by soft sensor application: pilot-scale FBR, wastewater	- dilution rate - alkalinity	VFA/TA
linearizing	Rincon et al. (2009)	adaptive control, normal form of fold bifurcation application: simulation only, wastewater	dilution rate	effluent VFA
linearizing	Simeonov and Queinnec (2006)	model-based, organic wastes and acetate application: simulation only, CSTR, mesophilic	acetate addition	biogas flow rate
robust linearizing	Rapaport and Harmand (2002)	interval observer application: simulation only, CSTR	dilution rate	effluent COD
geometric	Méndez-Acosta et al. (2005)	to avoid overshooting fuzzy-based gain-scheduling and antiwindup scheme are used, high-gain observer application: simulation only, AFB, wastewater	dilution rate	effluent COD
geometric robust	Méndez-Acosta et al. (2008)	model-based: extended Luenberger observer application: pilot-scale AFB, wastewater	dilution rate	effluent VFA
geometric robust	Méndez-Acosta et al. (2007)	model-based: extended Luenberger observer; proposal of two controls (1, 2); TOC: total organic carbon application: pilot-scale AFB, wastewater,	dilution rate	1) VFA 2) TOC

		mesophilic		
geometric robust	Méndez-Acosta et al. (2010)	model-based: extended Luenberger observer, antiwindup structure application: simulation only, wastewater	- dilution rate - alkali solution	- VFA - TA
linearizing	Dochain and Bastin (1985)	nonlinear adaptive application: CSTR, simulation only	dilution rate	effluent VFA
generic model control	Costello et al. (1989)	improvement of Dochain and Bastin (1985) application: CSTR, simulation only, wastewater	dilution rate	effluent COD
linearizing	Petre et al. (2013)	three controls: 1) adaptive (asymptotic observer), 2) robust, 3) robust-adaptive (interval observer, both) application: CSTR, simulation only, wastewater	dilution rate	effluent COD
VSM	Tartakovsky et al. (2002, 2005)	variable structure model (VSM) containing three linear submodels, for each submodel one linearizing control application: lab-scale UASB, synthetic wastewater, mesophilic	influent COD	effluent COD
decoupled linearizing	Aguilar-Garnica et al. (2009)	two-phase AD system, modeled by PDE, observer-based estimator application: simulation only, two AFBs, wastewater	recycle flow rates	- effluent VFA - effluent COD

1 Table ESM.7: Other Advanced Controls for Biogas Plants

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Control type	Authors	Description	Manipulated variable	Control variable
disturbance monitoring	Steyer et al. (1999)	increased biogas yield caused by an impulse in feed is compared with expected. Overloading/inhibition reflected by an unsatisfactory gas yield. application: lab-scale FBR, wastewater, mesophilic	dilution rate	biogas flow rate
disturbance accommodating	Harmand et al. (2000)	ARMAX model with bias estimation application: lab-scale FBR, wastewater	dilution rate	biogas flow rate
nonlinear adaptive	Polihronakis et al. (1993)	proposal of three controls: 1), 2) and combination of both combination switches between both control objectives application: full-scale, wastewater	dilution rate	1) effluent COD 2) CH4 flow rate
adaptive robust	Hilgert et al. (2000)	ARMAX model with uncertain part, estimated by kernel estimator application: lab-scale FBR, wastewater, mesophilic	dilution rate	biogas flow rate
adaptive	Harmon et al. (1993)	taken from Pind et al. (2003) application: lab-scale CSTR, glucose	temperature	CH4 flow rate
nonlinear	Harmon et al. (1990)	constant reactor yield control application: lab-scale CSTR, synthetic WW, thermophilic	dilution rate	CH4 flow rate
sampled delayed control	Méndez-Acosta et al. (2011)	nonlinear, robust, delayed measurements, COD measured daily application: lab-scale AFB, wastewater, mesophilic	dilution rate	effluent COD
robust output feedback	Antonelli et al. (2003)	nonlinear; only measured variable: CH4 flow rate application: pilot-scale AFB, wastewater, mesophilic	dilution rate	CH4 flow rate
robust output feedback	Mailleret et al. (2003)	CH4 flow rate and input COD needed application: pilot-scale AFB, wastewater	dilution rate	effluent COD
nonlinear adaptive	Mailleret et al. (2004)	CH4 flow rate needed application: pilot-scale AFB, wastewater	dilution rate	effluent COD
nonlinear adaptive	Dimitrova and Krastanov (2009)	extremum seeking algorithm to maximize CH4 production application: simulation only	dilution rate	- effluent COD - CH4 flow rate
adaptive	Seok (2003)	recursive system identification, convex optimization problem application: lab-scale FBR, wastewater, mesophilic	dilution rate	propionate
extremum seeking	Marcos et al. (2004)	adaptive; substrate concentration kept at setpoint application: CSTR, AFB, simulation only	dilution rate	CH4 flow rate
extremum seeking	Simeonov and Stoyanov (2011)	application: CSTR, simulation only, mesophilic	dilution rate	CH4 flow rate
LQT	Mu et al. (2008)	linear quadratic tracking (LQT) and error integral action application: simulation only, lab-scale UASB, distributed	- recirculation-to-feed ratio - bypass-to-	effluent COD

		model, wastewater	feed ratio	
NMPC	Aceves-Lara et al. (2010)	asymptotic observer estimates influent, effluent and some product concentrations; dark fermentation application: lab-scale CSTR, diluted molasses, mesophilic	dilution rate	H2 flow rate
EPSAC-MPC	Ordace et al. (2012)	Extended Prediction Self-Adaptive Control (EPSAC) application: simulation only (ADM1), wastewater sludge	feed flow rates	CH4 flow rate
variable-gain	Rodríguez et al. (2006)	indirect COD control by controlling H2 in gas phase application: pilot-scale UASB-AF, wastewater	dilution rate	effluent COD
composed	Wang et al. (2013)	algebraic differential estimator, model-free application: CSTR, simulation only, agricultural, mesophilic	dilution rate	CH4 flow rate
adaptive optimization	Ryhiner et al. (1992)	steepest descent finds optimal operating point application: FBR, wastewater	dilution rate	- CH4 flow rate - VFA
saturated proportional	Grognard and Bernard (2006)	no input COD measurement needed; attracts to a region application: simulation only, wastewater	dilution rate	effluent COD
$H_{\infty}$	Flores-Estrella et al. (2013)	application: simulation only, wastewater	dilution rate	effluent COD
dynamic compensator	Simeonov and Stoyanov (2003)	linear model with interval parameters; proposes two controls (1, 2) application: simulation only	dilution rate	1) biogas flow rate 2) effluent COD
robust adaptive	Rincón et al. (2012)	Lyapunov-like function application: simulation only, wastewater	dilution rate	effluent VFA
robust interval	Alcaraz-González et al. (2005)	interval observers application: pilot-scale AFB, wastewater	dilution rate	effluent COD

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