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Additional Information

Effect of turbulent model closure and type of inlet boundary condition on a Large Eddy Simulation of a non-reacting jet with co-flow stream

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Abstract

In this paper, the behavior and turbulence structure of a non-reacting jet with a co-flow stream is described by means of Large Eddy Simulations (LES) carried out with the computational tool OpenFoam. In order to study the influence of the sub-grid scale (SGS) model on the main flow statistics, Smagorinsky (SMAG) and One Equation Eddy (OEE) approaches are used to model the smallest scales involved in the turbulence of the jet. The impact of cell size and turbulent inlet boundary condition in resulting velocity profiles is analyzed as well. Four different tasks have been performed to accomplish these objectives. Firstly, the simulation of a turbulent pipe, which is necessary to generate and map coherent turbulence structure into the inlet of the non-reacting jet domain. Secondly, a structured mesh based on hexahedrons has been built for the jet and its co-flow. The third task consists on performing four different simulations. In those, mapping statistics from the turbulent pipe is compared with the use of fluctuating inlet boundary condition available in OpenFoam; OEE and SMAG approaches are contrasted; and the effect of changing cell size is investigated. Finally, as forth task, the obtained results are compared with experimental data. As main conclusions of this comparison, it has been proved that the fluctuating boundary condition requires much less computational cost, but some inaccuracies were found close to the nozzle. Also, both SGS models are capable to simulate this kind of jets with a co-flow stream with exactitude.

Keywords: Large eddy simulations, Inlet boundary, Smagorinsky, One equation eddy, OpenFoam

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Nomenclature

τ_{ij}	Sub-grid scale stress tensor (m^2/s^2)
ν_t	Turbulent viscosity (m^2/s)
S	Rate of strain tensor (1/s)
C_s	Coefficient for SMAG model closure
C_k, C_ϵ	Coefficients for OEE model closure
R_{xx}	Spacial autocorrelation
x	Axial distance from the nozzle (mm)
r	Radial distance (mm)
D	Nozzle exit diameter (mm)
U_0	Jet velocity at the nozzle exit (m/s)
U	Axial velocity (m/s)
U_m	Maximum value of U (m/s)
U_{m0}	Maximum value of U at the nozzle (m/s)
u'	Axial velocity fluctuation (m/s)
v'	Radial velocity fluctuation (m/s)
$u'v'$	Reynolds shear stress (m^2/s^2)
Re	Reynolds number
OEE	One equation eddy model
$SMAG$	Smagorinsky model
$_nbc$	Referred to simulations performed with the mapping strategy
$_ti$	Referred to simulations performed with the fluctuating boundary condition
$_c$	Referred to simulations performed with the coarse mesh
$_r$	Referred to simulations performed with the refined mesh
$r_{1/2}$	Radial distance at which the excess velocity is half of the value of U_m (mm)

1. Introduction

Nowadays, research in combustion is linked to applications that can provide alternatives to reduce emissions and increase process efficiencies. Taking advantage of the gases produced by combustion is a good way to achieve those targets. Recirculating gas combustion products have shown to be useful in order to reduce NOx emissions by diluting the mixture and thus controlling temperature levels [1]. Flame stabilization is improved as well as NOx emissions due to the thermal energy carried by these gases, which act as the enthalpy source needed for ignition [2, 3]. Cabra et al. [4] [5], in their proposal on lifted flames with a co-flow based on combustion products seems to be a successful implementation in order to study flame stabilization by burnt gases. Due to the large experimental database, besides the sensitivity of the flame characteristics to operating conditions, this flame configuration has gained particular interest in the computational combustion community, and is frequently used for validation and development of combustion models [6]. The studies on Large Eddy Simulations (LES) in this kind of flame have been reported in literature [7–13], most of them focusing on Smagorinsky turbulence model closure. LES simulations are not common on these flames due to the cost of implementing detailed chemistry and the inaccuracy of infinitely fast chemistry approaches to simulate lifted

18 flames [7]. Avoiding this problem and considering that the study of turbulent flows in inert
19 environments turns out to be a key point to understand the fuel-air mixing process, some
20 works make an effort to study several applications that involve non-reacting turbulent
21 flows [14–16]. Inert studies are of great importance in many industrial processes which
22 include combustion systems, such as rocket engines, gas turbines, industrial furnaces and
23 internal combustion engines [17]. The inert study of this flame helps to focus only on the
24 problem of turbulence, which is one of the most influential phenomena in combustion.
25 Turbulence increases the mixing process and enhances combustion [18]. Inert calculations
26 are the first step before simulating reactive cases.

27 This paper carries out LES on a non-reacting jet with a co-flow stream that emulates
28 an inert Cabra’s experiment considering two different ways of turbulence modeling closure,
29 Smagorinsky (SMAG) and One equation Eddy (OEE). A turbulent pipe is simulated in
30 order to map its fields in the non-reacting jet domain. The results gathered by this strategy
31 are contrasted with resulting velocity profiles from the simulation using a fluctuating inlet
32 boundary condition. Also, the impact of the cell size is analyzed. Since turbulence is a
33 chaotic phenomenon the solution of two LES calculations should be different. Nonetheless,
34 its velocity statistics, e.g. perturbation velocity root mean square, can be comparable [19].
35 The simulations are also compared with experimental data.

36 2. Description of the study

37 The burner consists of a round fuel jet issuing into a co-flow of H₂ combustion products.
38 The vitiated stream is obtained from hydrogen/air lean premixed combustion and it is
39 composed of H₂O and air [5]. The central jet mixture consist of 30% H₂ and 70% N₂,
40 by volume. The bulk velocity of the fuel jet and of the co-flow velocity are of the order
41 of 100 m/s and 5 m/s respectively. Table 1 summarizes the boundary conditions used in
42 this work as well as the boundary conditions used in the experimental work developed
43 by Wu et al. [20], who studied the turbulence phenomena related with the experiment in
44 non-reacting and reacting conditions. LES results are compared with experimental data
45 from Cao et al. [21] as well. For simulations, the main flow and the co-flow are considered
46 to be the same specie with the same kinematic viscosity (2.07×10^{-5} m²/s). In order to
47 reach an equivalent Reynolds number of $Re = 18600$ in the co-flow stream, the velocity
48 is calculated with the aforementioned viscosity and results $U_0 = 1.84$ m/s.

Table 1: General boundary conditions.

	Experimental Wu et al. [20]		Experimental Cao et al. [21]		This work	
	flow	co-flow	flow	co-flow	flow	co-flow
Re	31500	17300	23600	18600	23600	18600
U_0 (m/s)	106	1.4	107	3.5	107	1.84
ϕ (mm)	4.57	190	4.57	210	4.57	210

49 3. Turbulence modelling

50 The simulations have been performed with the open-source code OpenFoam. The solver
51 for transient incompressible flows resolves Navier–Stokes equations enforced with a merged
52 PISO-SIMPLE algorithm. It is based on an Eulerian formulation. A finite-volume dis-
53 cretization with second-order central schemes for convection and diffusion terms is em-
54 ployed. Temporal discretization is performed with an implicit second order scheme. This
55 solver first sets the boundary conditions, then solves the discretized momentum equation
56 to compute an intermediate velocity field, computes the mass fluxes at cell faces and lastly
57 the pressure equation is solved.

58 LES decompose the flow variables into resolved and sub-grid scale terms. The resolved
59 scales are calculated by means of the transport equations, meanwhile the sub-grid scales
60 terms are modelled [22–24]. Both filtered variables and sub-grid scale variables are de-
61 pendent of the filter size and the impact of the modeling should decrease as the filter size
62 decrease. With the filtering procedure the momentum equation becomes:

$$\frac{\partial \bar{u}_i}{\partial t} + \frac{\partial \bar{u}_j \bar{u}_i}{\partial x_j} = -\frac{\partial \bar{P}}{\partial x_i} + \nu \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j} \quad (1)$$

63 where the variable \bar{P} also includes volumetric forces, and the SGS stress tensor is:

$$\tau_{ij} = \overline{u_i u_j} - \bar{u}_i \bar{u}_j \quad (2)$$

64 The SGS tensor cannot be determined by the resolved scales, therefore it has to be
65 modelled (system closure). This work uses two kind of turbulence model closures: the
66 Smagorinsky approach (SMAG) [25] and the one equation eddy approach (OEE) [22]. A
67 brief description of both is given in the following subsections.

68 3.1. Smagorinsky approach (SMAG)

69 It is an algebraic model (or zero equation model), which means that there is no transport
70 equation required to calculate the turbulent eddy viscosity [26]. The model obtains the
71 sub-grid stress term as a function of turbulent viscosity and the strain rate.

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2\nu_t S_{ij} \quad (3)$$

72 where S_{ij} is the rate-of-strain tensor and ν_t is the turbulent viscosity, both given by:

$$S_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad (4)$$

$$\nu_t = C_s \Delta^2 \sqrt{2 \overline{S_{ij} S_{ji}}} \quad (5)$$

73 In this last equation, C_s is the Smagorinsky constant, which has a theoretical value in
 74 the range [0.1-0.2] [27]. The value of C_s finally selected in this study is the default value
 75 defined in OpenFoam ($C_s = 0.2$). Also, Δ is the filter width, computed as the cubic root
 76 of the cell volume.

77 3.2. One equation eddy approach (OEE)

78 The net quantity of the dissipation from resolved scales is correct in the SMAG approach,
 79 but the energy locally dissipated might be incorrect [22]. For this reason, models such as
 80 OEE become important. Like for the SMAG approach, this model is also based on the
 81 definition of turbulent viscosity ν_t , and it assumes that the stress tensor is proportional
 82 to the strain stress tensor. It introduces an extra transport equation, but for the sub-grid
 83 turbulent kinetic energy ($k_{sgs} = \tau_{kk}/2$). It has been demonstrated that this strategy may
 84 improve the modeling of the sub-grid scales, allowing coarser meshes [22]. The additional
 85 transport equation for incompressible flows is:

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial (u_j k_{sgs})}{\partial x_j} = \frac{\partial}{\partial x_j} \left((\nu + \nu_t) \frac{\partial k_{sgs}}{\partial x_j} \right) - \tau_{ij} \overline{S_{ij}} - \varepsilon \quad (6)$$

86 where the viscous dissipation is usually taken as:

$$\varepsilon = C_\varepsilon \left(\frac{k_{sgs}^{3/2}}{\Delta} \right) \quad (7)$$

87 the sub-grid viscosity is modeled as:

$$\nu_t = C_k k_{sgs}^{1/2} \Delta \quad (8)$$

88 and finally, the sub-grid stress tensor is calculated as follows:

$$\tau_{ij} = -2\nu_t \overline{S_{ij}} + \frac{2}{3} \delta_{ij} k_{sgs} \quad (9)$$

89 The coefficients can be evaluated based on turbulence theory or adjusted dynamically.
 90 In this case, $C_k = 0.094$ and $C_\varepsilon = 1.048$, which are the default values given by the code.

91 4. Case set-up and numerical implementation

92 4.1. Turbulent pipe

93 One of the aims of this work is to compare how velocity statistics of the Cabra jet change
 94 using two different inlet boundary conditions. In the first case, a fluctuating boundary
 95 condition available in OpenFoam was established. In the second case, the inlet condition
 96 was pre-simulated in a turbulent pipe, and transient velocity of that case was imposed at
 97 the inlet of the main flow, thus coherent turbulent structure is ensured. In the following,
 98 a description of the turbulent pipe simulation is presented.

99 4.1.1. Mesh and mapping strategy description

100 The simulation of the turbulent pipe with periodic boundary conditions is carried out
 101 in two stages, sketched in Fig. 1. First the domain is filled with stagnated gas, which
 102 accelerates due to imposed inlet velocity. Once the flow reaches the outlet, boundary
 103 conditions are switched to cyclic. This allows the flow inside the pipe to reach a fully
 104 developed turbulent velocity profile without the necessity of having a very long domain
 105 [28].

106 Subsequently this profile is mapped and imposed as an inlet boundary condition for
 107 the non-reacting Cabra jet simulation. The geometry of the turbulent pipe with its cell
 108 distribution is shown in Fig. 2. The cylindrical domain has the same inlet diameter
 109 (4.57 mm) of the experiment carried out by Cabra et al. [5]. Its length ($15.3D = 70$ mm)
 110 was based on the convergence of turbulence statistics of others turbulent pipe simulations
 111 with similar reynolds numbers [29, 30].

112 The mesh used in this case (Fig. 2) consists of 665600 cells, 1280 in the radial direction
 113 and 520 in axial direction. The minimum cell size is 0.134 mm.

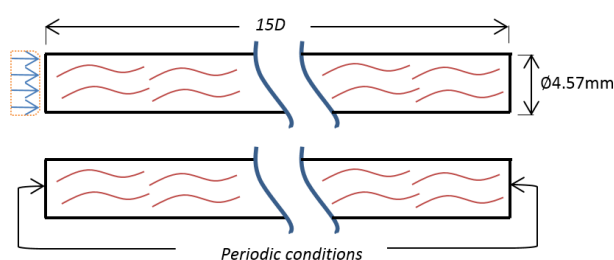


Figure 1: Boundary conditions for the turbulent pipe.

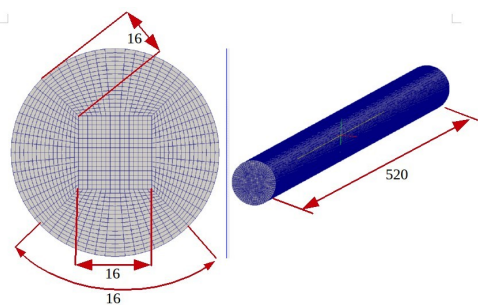


Figure 2: Cell distribution of the turbulent pipe.

114 The SGS model was OEE. Once the mean velocity at the center of the domain becomes
 115 constant in time, see Fig. 3 after 0.01 s, and two point spatial correlation shows an
 116 independence of statistics at $x/D = 9$, see Fig. 4, fields are mapped during 30 ms, which
 117 is the chosen time to simulate the inert jet. 10 ms are required to obtain a jet penetration
 118 of at least $x/D = 50$ in the Cabra jet and 20 ms more (up to 7 flow-through-times) to

gather statistics. This timing was defined by collecting information from several similar studies [7, 8, 10, 12].

4.1.2. LES Quality Assessment for the turbulent pipe

A probe is located in the center of the domain, where the velocity field will be mapped (at $x = 9D$). This probe helped to confirm whether the flow was already turbulent or not. Fig 3 exposes the captured velocity in time and its mean. This confirms that after 0.01s the flow is developed. This is also tested by the two point spatial correlation defined as:

$$R_{xx} = \frac{\sum \overline{u'(x)u'(x + \Delta x)}}{\sum \overline{u'(x)u'(x)}} \quad (10)$$

The two point correlation behavior can be seen in Fig. 4. Statistics between $x/D = 1$ and $x/D = 14$ seem to be independent from the initial signals. It confirms that statistics taken from $9D$ could be mapped and used as inlet data for the main domain.

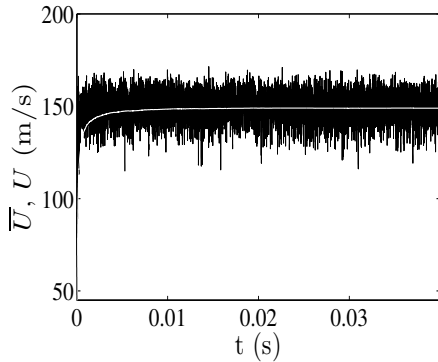


Figure 3: Velocity and its mean (probe located at $9D$ in the middle of the turbulent pipe).

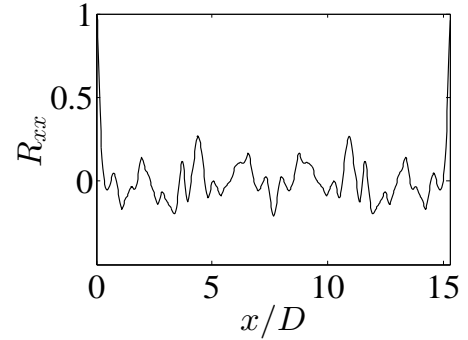


Figure 4: Spatial autocorrelation at 0.01s.

An important issue regarding LES is to know if a sufficient part of the turbulent flow energy is directly resolved by the computational grid. In this case, it is considered that the biggest scales of the flow, whose behavior is difficult to model using a SGS model, are well captured, then conferring a high level of confidence in the LES predictability [31]. Power spectra was computed from the signals of 5 ms in duration by using a windowed Fourier transform with overlapping segments of 0.5 ms in length, averaging the spectra over the segments. The results are shown in Fig. 5. Reasonable inertial range spectrum ($-5/3$ law) [32] is recovered, suggesting that the current resolution is acceptable to resolve momentum transport in the shear layer regions.

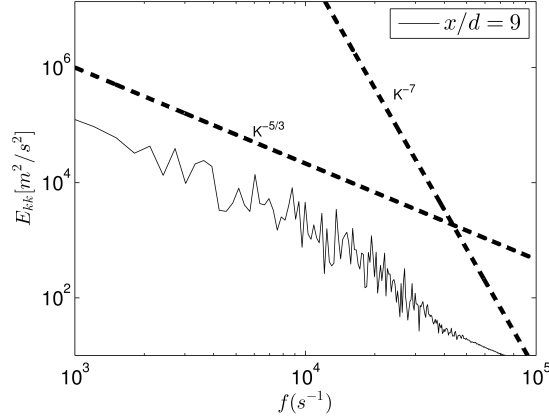


Figure 5: Energy spectra for the turbulent pipe

138 The mean velocity and its fluctuation profiles of the turbulent pipe are shown in Fig. 6.
 139 These profiles are compared with experimental inlet velocity profiles measured by Kent
 140 [33] on the Cabra jet configuration. No differences are observed in the mean velocity
 141 whilst a very small difference, of about 0.02 m/s, is found for fluctuation velocity. The
 142 simulation is accurate.

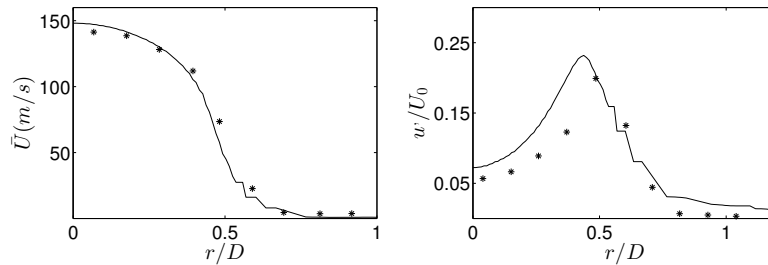


Figure 6: (Solid line) Radial profile of the mean velocity and its fluctuation in the turbulent pipe simulation, (Asterisks) Experimental data from Kent's measurements at $x/D = 0$ [33].

143 4.2. Main domain – Cabra Jet

144 4.2.1. Base mesh

145 The geometry of the domain is based on the experimental configuration of Cabra
 146 et al. [5]. This computational cylindrical domain extends radially $\sim 23D$ and axially
 147 $\sim 103D$. Jones and Navarro-Martinez [8] carried out a brief mesh independence study
 148 where resulting velocity statistics from the finest grid (~ 1.8 million of cells) were not
 149 converging yet using a similar cylindrical mesh. Because of that, the coarse mesh used in
 150 this study adopted is even finer than the finest mesh used by Jones and Navarro-Martinez's
 151 work. The coarse grid for this work consists of a structured mesh of ~ 3.7 millions

152 hexahedrons. The side view illustrated in Fig. 7 shows the axial cell distribution of the
 153 mesh. Blue arrows tips in Fig. 8 indicate the growing direction of the cell size, where r is
 154 the “common ratio” since the cell size is varying within a geometric progression. Axially,
 155 the domain is divided in two zones (see Fig. 8) with two different values of “common
 156 ratio”. The minimum cell size is located at the nozzle inlet.

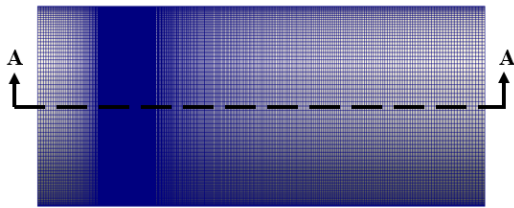


Figure 7: Side view for mesh cell distribution.

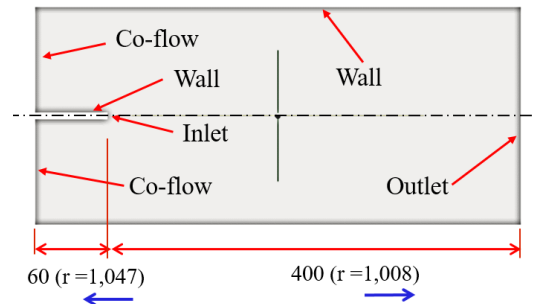


Figure 8: Section A-A of the cylindrical domain. Number of cells, growing size direction and common ratio.

157 The frontal view for mesh cell distribution is shown in Fig. 9. The mesh core (core-
 158 inlet) has the same frontal cell distribution as the domain built for the turbulent pipe
 159 (shown in Fig 2) in order to increase mapping process accuracy.

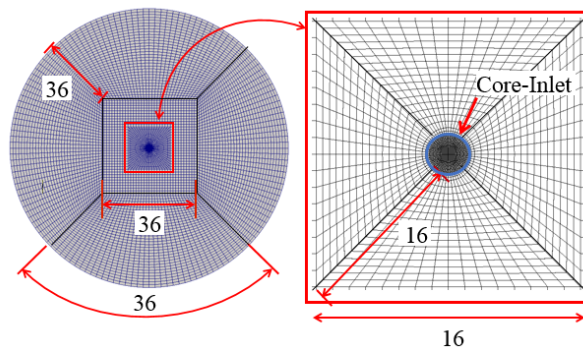


Figure 9: Frontal view for mesh cell distribution. Number of cells in different directions.

160 4.2.2. Refined mesh

161 The mesh is refined in the zone shown in Fig. 10 in order to find out if velocity
 162 statistics are being affected by reducing the cell size. This is also an attempt to obtain
 163 more accurate results despite the increase in computational cost. The resulting mesh
 164 consist of ~ 8.3 millions of hexahedrons, and the cone angle used to refine this zone (20°)
 165 was taken from results shown by Wu et al.[20]. The minimum size for the refined mesh
 166 was 0.067 mm.

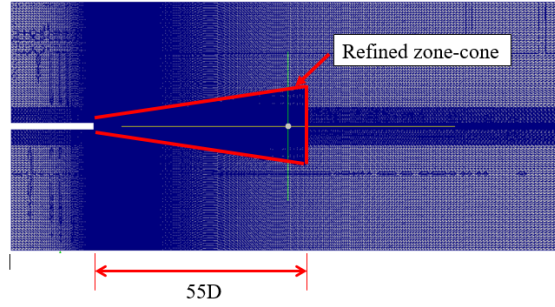


Figure 10: Refined mesh.

167 *4.2.3. LES quality assessment for the main domain*

168 Power spectrum was also computed for the coarse and the refined meshes signals,
 169 the same energy spectrum averaged by segments with length of 0.5 ms was calculated for
 170 several axial distances from the nozzle, averaging the spectra over the segments. Again,
 171 inertial range spectrum ($-5/3$ law) [34] was found, and also a slope of -7 indicating that
 172 both meshes were also calculating scales from the dissipation range, suggesting that the
 173 current resolutions, even the coarse one, were very fine (Fig. 11, 12.)

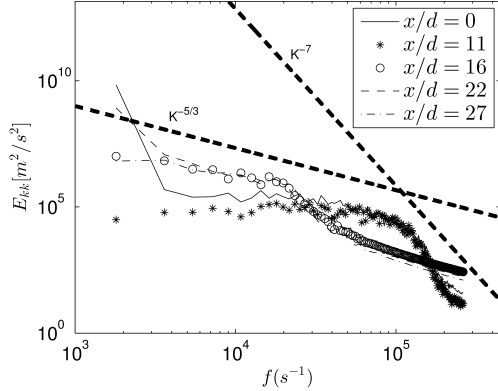


Figure 11: Energy spectra for the coarse mesh

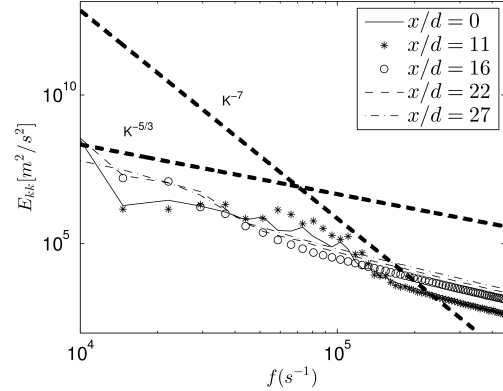


Figure 12: Energy spectra for the refined mesh

174 *4.3. Computational cost*

175 Three computer clusters were used for the calculations. One is composed of 24 processors
 176 “Intel Xeon E5-4617 @2.90GHz” and 64GB of RAM memory. Other has 24 processors
 177 “Intel Xeon E5-2630 @2.60GHz” and 64GB of RAM memory . The last one has 8 pro-
 178 cessors “Intel Xeon E5504 @2.00GHz” and 8GB of RAM memory. Computational cost
 179 per 10 ms and Courant numbers C_0 for each simulation are presented in Table 2. The
 180 simulations performed with the refined mesh take ~ 6.5 more time to achieve admissible
 181 results.

Table 2: Computational cost, Courant number and calculating machines.

Simulation	Computational cost (hrs/10 ms)	Calculating machines	C_0	Processors
turbulent pipe	66	@2.00GHz	0.85	8
OEE_nbc_c	46	@2.60GHz	0.85	24
SMAG_nbc_c	47	@2.60GHz	0.85	24
SMAG_nbc_r	301	@2.60GHz	0.85	24
SMAG_ti_c	16	@2.90GHz	0.85	24

182 5. Results

183 Table 3 shows axial velocities in the jet center for each simulation at several distances
 184 from the nozzle. These magnitudes are used to obtain dimensionless velocity profiles.
 185 As it has been said before, the aim of the study is to evaluate how the inlet boundary
 186 condition, the model closure and the cell size could affect velocity statistic profiles. In
 187 this section, results according to those objectives are displayed.

Table 3: Axial velocity in the jet center (U_m [m/s]) for several x/D .

x/D	OEE_nbc_c	SMAG_nbc_c	SMAG_nbc_r	SMAG_ti_c
1	148.47	148.08	147.76	141.36
8	88.20	83.84	86.98	91.07
10	73.8	67.85	70.53	75.06
14	52.4	51.2	49.39	59.23

188 5.1. Influence of mesh resolution

189 In this section, results obtained for the inert jet injected for both meshes (coarse and
 190 refined) using the SMAG model closure by using the mapping strategy are presented.
 191 This has been done in order to check if the velocity statistics obtained from both meshes
 192 are consistent with experimental data. In Fig. 13 it is shown that the velocity decay
 193 obtained with both meshes barely changes. This is an indication that the mesh was
 194 already fine enough to achieve accurate results.

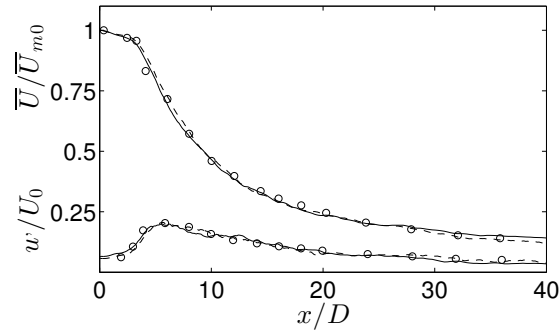


Figure 13: Velocity decay and its fluctuation in the axis direction. (Circles) measurements Wu et al. [20]. (Solid line) calculations using the coarse mesh. (Dash line) calculations using the refined mesh.

195 In Fig. 14 radial velocity profiles and its fluctuations for both meshes are presented.
 196 Again. results from both meshes almost fall on one single curve. The small variation in
 197 the results also confirms that a mesh refinement was not necessary.

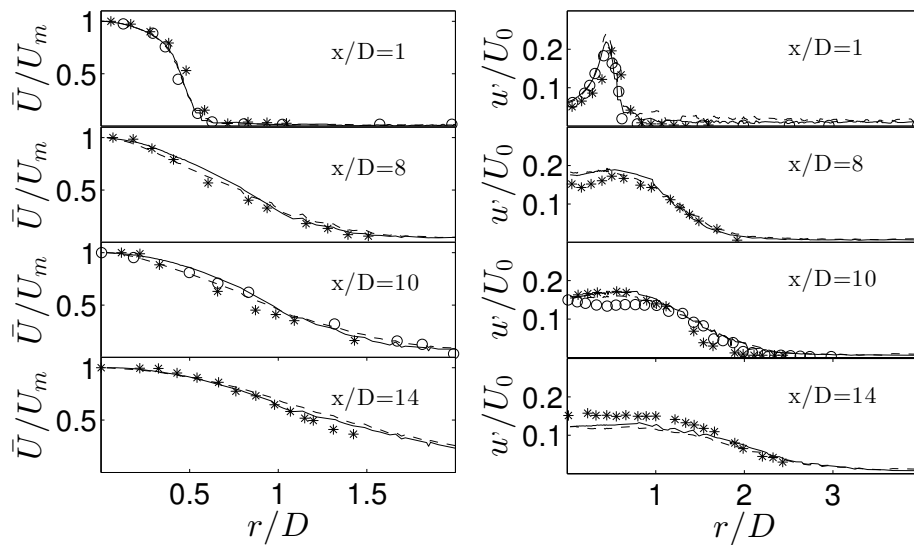


Figure 14: Radial velocity profiles. (Circles) Measurements Wu et al. [20]. (Asterisks) Measurements Cao et al. [21]. (Solid line) calculations using the coarse mesh. (Dash line) calculations using the refined mesh.

198 *5.2. Effect of inlet boundary condition*

199 In this section, results of different two simulations are shown, they were obtained for
 200 the inert jet injected in the coarse mesh, one using the mapping strategy and the other

201 one a fluctuating inlet boundary condition supplied by OpenFoam. SMAG model closure
 202 was used. This is done to check which type of inlet boundary condition could reproduce
 203 the coherent turbulent structures and velocities more adequately. If the fluctuating in-
 204 let boundary condition proves to be useful, it implies less computational cost in future
 205 simulations in this kind of jets because the simulation of a turbulent pipe could be avoided.

206 The velocity decay for the simulation carried out with the mapped and the OpenFoam
 207 boundary conditions are shown in Fig. 15. Both simulations are compared as well with
 208 experimental data. The velocity decay obtained from the simulation performed with
 209 the mapping strategy seems to fit properly with the experimental data. The fluctuating
 210 boundary condition tends to over-estimate the velocity decay. Nevertheless, it leads to
 211 acceptable results considering its low computational cost, then this kind of boundary
 212 condition could be useful.

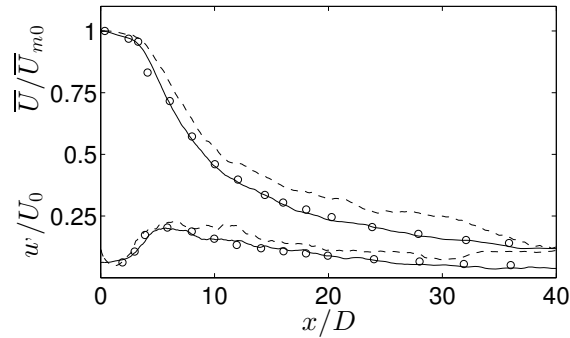


Figure 15: Velocity decay and its fluctuation in the axis direction. (Circles) measurements Wu et al. [20]. (Solid line) calculations using the mapping strategy. (Dash line) simulations carried out with *turbulentInlet* boundary condition.

213 In Fig. 16, it can be seen that close to the nozzle ($x/D < 8$) radial velocity profiles
 214 can be accurately reproduced by using the mapping strategy. The OpenFoam boundary
 215 condition does not achieve the same accuracy at those distances. Though, after $x/D = 8$,
 216 the jet simulated with the fluctuating boundary condition has exchanged enough momen-
 217 tum to reach similar profiles than experiments. Therefore this artificial tool proves to
 218 be useful if quicker results with slightly poorer accuracy (specially close to the nozzle)
 219 are required. The simulation carried out with OpenFoam boundary condition tends to
 220 over estimate fluctuations, but it is clear that it depends specially on the fluctuation scale
 221 parameter (required parameter of the boundary condition) which has been imposed to be
 222 10%. This parameter could be a key aspect to improve results performed with OpenFoam
 223 boundary condition. By reducing this parameter a reduction in velocity as well as in its
 224 fluctuation is expected.

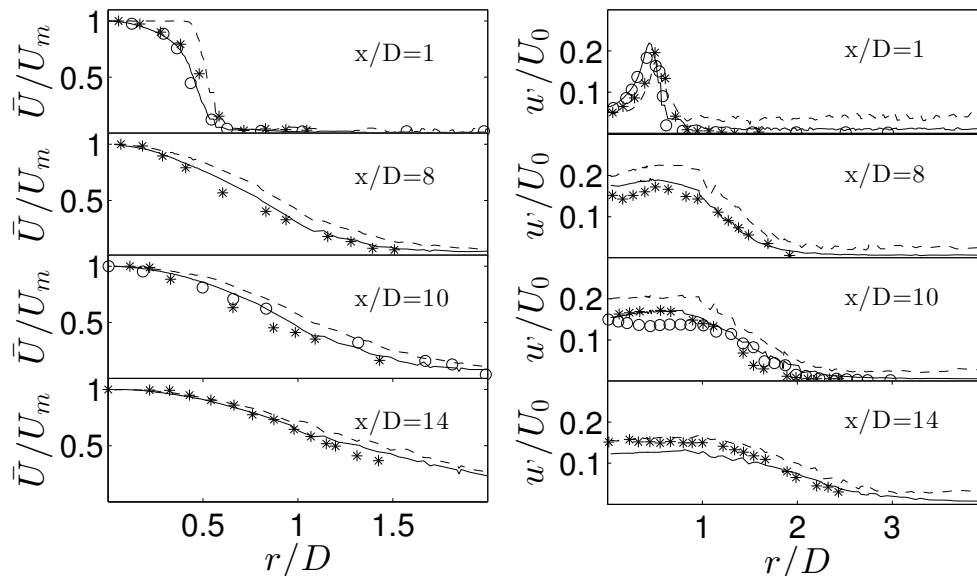


Figure 16: Radial velocity profiles. (Circles) Measurements Wu et al. [20]. (Asterisks) Measurements Cao et al. [21]. (Solid line) calculations using the new boundary condition. (Dash line) simulations carried out with *turbulentInlet* boundary condition.

225 5.3. Effect of turbulent model closure

226 In this section, results obtained for the inert jet injected in the coarse mesh, using both
 227 sub-grid scale models, SMAG and OEE, are presented. As it has been said before, the
 228 OEE model allows coarser meshes, which implies longer time steps with the same Courant
 229 number C_0 , hence less computational cost to achieve admissible results. Velocity decay
 230 for both models, depicted in Fig. 17, seems to fit properly with the experimental data.

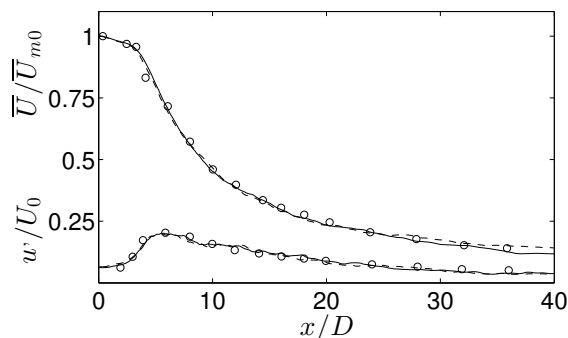


Figure 17: Velocity decay and its fluctuation in axis direction. (Circles) measurements Wu et al. [20]. (Solid line) calculations using SMAG model closure. (Dash line) calculations using OEE model closure.

231 Comparison of radial velocity profiles from both sub-grid scale models with experi-
 232 mental data is shown in Fig. 18. Both models show good accuracy in their results. This
 233 suggests that it is useful to simulate Cabra-like flames using the OEE model closure. This
 234 model is not commonly used for lifted flames according to the literature reviewed in this
 235 pa]

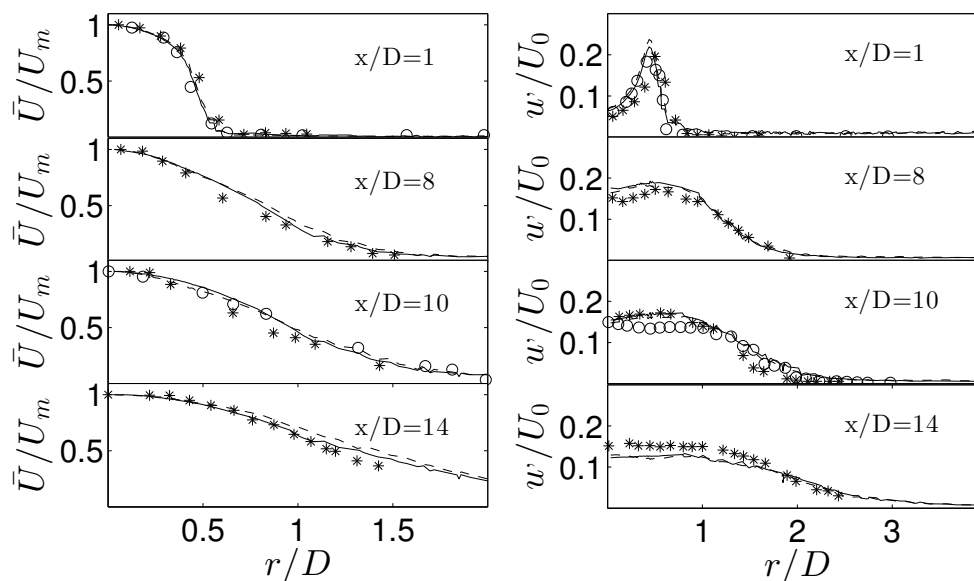


Figure 18: Radial velocity profiles. (Circles) Measurements Wu et al. [20]. (Asterisks) Measurements Cao et al. [21]. (Solid line) calculations using SMAG model closure. (Dash line) calculations using OEE model closure.

236 5.4. Self-preserving profiles

237 Turbulent jets are distinguished by having two main zones according to experimental ob-
 238 servations made on mean velocity fields [35]. Near nozzle area, called the flow development
 239 region, where there is a potential core surrounded by a mixing layer [21]. In this zone
 240 it can be also observed a non-perturbed region, where the axial velocity at the center of
 241 the jet barely decreases. The second zone is called the fully developed flow region where
 242 the mixing process has reached the whole section and therefore the non-perturbed zone
 243 disappears [36]. In this region velocity profiles become self-similar and the jet is consid-
 244 ered to be in equilibrium. This means that all radial velocity profiles tends to fall on one
 245 single Gaussian curve. Self-preserving profiles obtained with the SMAG model and using
 246 the coarse mesh are shown in Figs. 19 to 22. After $x/D = 5$, mean radial velocity profiles
 247 achieved the self-preserving zone, whereas this behavior is not appreciated for relative
 248 turbulence intensity at the studied time step.

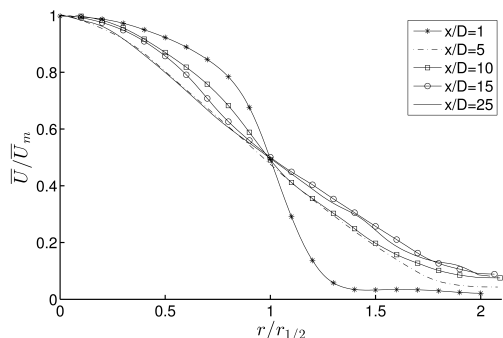


Figure 19: Radial distribution of U/U_m .

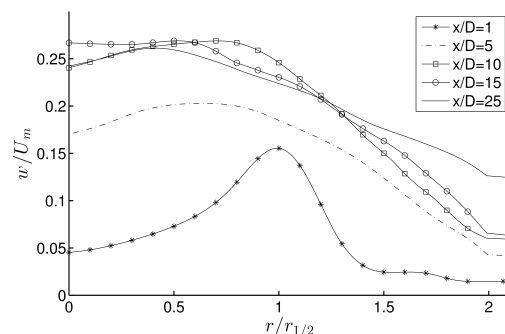


Figure 20: Radial distribution of w/U_m .

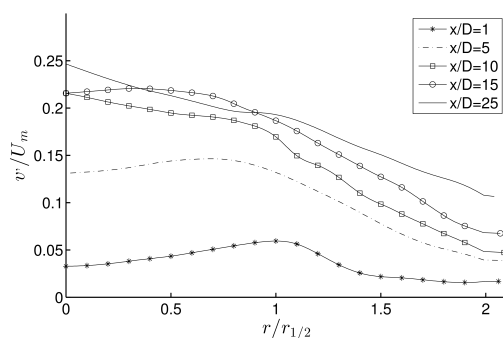


Figure 21: Radial distribution of v/U_m .

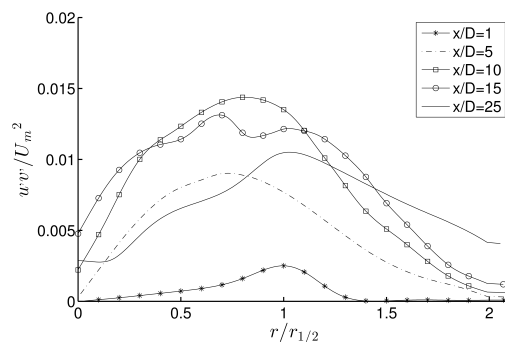


Figure 22: Radial distribution of wv/U_m^2 .

249 6. Conclusions

250 In this work, a non-reacting jet with a co-flow stream was computationally studied. The
 251 jet was simulated by using two SGS-models (SMAG and OEE), two meshes (coarse and
 252 refined) and two inlet boundary conditions (fluctuating and mapping strategy). The main
 253 findings of this numerical investigation are as follows:

- 254 1. The mapping strategy is able to properly reproduce real turbulence structure. The
 255 results obtained from this boundary condition have been more accurate than the
 256 ones obtained with OpenFoam's tool for artificial turbulence.
- 257 2. The fluctuating boundary condition tool is useful if quicker results are required, but
 258 the accuracy is lower specially close to the nozzle. Fluctuations gathered with this
 259 condition were higher than the experiments: if this tool is used, a value lower than
 260 10% for the fluctuation scale should be used.
- 261 3. Velocity profiles from simulations performed with both turbulent models seems to
 262 properly fit experimental data. This encourage future works related with Cabra's
 263 flame to use the OEE model taking into account that this model allows coarser
 264 meshes and therefore less computational cost to achieve good results.

- 265 4. With both meshes (coarse and refined mesh) similar results were obtained. This
266 means that the coarse mesh was fine enough to achieve accurate results.
267 5. Profiles obtained from SMAG_nbc_c show that after $x/D = 5$ radial velocity profiles
268 manifest to be in the self-preserving zone.

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