

Contents

Glossary	xix
List of Definitions	xxi
List of Tables	xxii
List of Figures	xxiv
List of Algorithms	xxvi
1 Motivation	1
1.1 Objectives	5
1.2 Contributions	7
1.3 Document structure	7
2 State of the art in planning and execution	8
2.1 Planning and execution architectures	9
2.1.1 Single-agent frameworks	9
2.1.2 Multi-agent frameworks	18
2.2 Approaches to planning and execution	30
2.2.1 Deliberative plan repair and replanning	33
2.2.2 Reactive planning and execution	35
2.2.3 Multi-agent planning and execution	37
2.3 Conclusions	46
3 Reactive Planning and Execution Model	48
3.1 Architecture of Planning and Execution	49
3.2 Planetary Mars scenario	53
3.3 Planning concepts	54
3.3.1 Planning task	54
3.3.2 Representing plan structures	57
3.4 Reactive Planner	61
3.4.1 Construction of a repairing structure	62

CONTENTS

3.4.2	Finding a recovery plan in a repairing structure	69
3.4.3	Calculating repairing structures for a solution plan	74
3.5	Conclusions	79
4	Evaluation of the Reactive Planner	81
4.1	Selecting the regression model	82
4.1.1	Data samples	83
4.1.2	Learning the linear regression model	87
4.1.3	Learning the bagging model	92
4.1.4	Comparing the two regression models	95
4.2	Experimental evaluation	101
4.2.1	Preparing the sample dataset	102
4.2.2	Time-bounded repairing structures	103
4.2.3	Repairing plan failures	111
4.3	Conclusions	119
5	Multi-Agent Reactive Plan Repair	120
5.1	Motivating example	122
5.2	Architecture	124
5.3	Defining the formal context	128
5.3.1	Planning tasks of the agents	128
5.3.2	Plan failures in dynamic environments	130
5.3.3	Root node of a repairing structure	132
5.4	Collaborative repair process	134
5.4.1	Multi-agent plan repair formalization	134
5.4.2	Outline of the workflow	137
5.4.3	General concepts	140
5.4.4	Execution of the reactive solution plan	150
5.5	Conclusions	156
6	Experimental evaluation in a multi-agent environment	157
6.1	Plan repair in a multi-agent context	158
6.1.1	Adapting single-agent repair methods to a multi-agent context	159
6.1.2	Repair configurations	161
6.2	Multi-agent planning tasks	164
6.2.1	Domain agentization	165
6.2.2	Rovers domain.	166
6.2.3	Elevators domain.	166
6.2.4	Transport domain.	167
6.3	General overview of the experiments	168
6.3.1	Structure of the results tables	169
6.3.2	Figures of the results tables.	170

CONTENTS

6.4	Experimental results	174
6.4.1	rovers domain	175
6.4.2	elevators domain	188
6.4.3	transport domain	194
6.5	Conclusions	200
7	Conclusions and future works	201
7.1	Conclusions	201
7.1.1	Proposed approximation	202
7.1.2	Contributions	204
7.2	Future works	208
Appendices		210
A	Planetary Mars scenario	211
A.1	Single-agent Mars scenario	211
A.1.1	PDDL3.1 Domain	211
A.1.2	List of variables	212
A.1.3	PDDL initial state	213
A.2	Multi-agent Mars scenario	213
A.2.1	PDDL3.1 domain	213
A.2.2	List of variables	215
A.2.3	PDDL3.1. problems	216
A.2.4	Solution plans	221
B	Rovers domain	222
B.1	Single-agent rovers	222
B.2	Multi-agent rovers	226
B.2.1	PDDL3.1 domain	226
B.2.2	Solution plans	229
C	Elevators domain	234
C.1	Single-agent elevators	234
C.2	Multi-agent elevators	236
C.2.1	PDDL3.1 domain	236
C.2.2	Solution plans	237
D	Transports domain	242
D.1	Single-agent transport	242
D.2	Multi-agent transport	243
D.2.1	PDDL3.1 domain	243
D.2.2	Solution plans	244

CONTENTS

E Logistics domain	248
E.1 Single-agent logistics	248
F Evaluating the Reactive Planner	250
F.1 Calculating the effective branching factor	250
F.2 Formulas to calculate the errors	252
F.2.1 Root Mean Square Error	252
F.2.2 Mean Absolute Error	252
F.2.3 Mean Absolute Percentage Error	253
G Conflict verification	254
Bibliography	256