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Additional Information

1 **Computer vision for automatic quality inspection of dried Figs (*Ficus carica***  
2 **L.)**

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13 **ABSTRACT**

14 This work develops automated systems based on computer vision to improve the quality  
15 control and sorting of dried figs of Cosenza (protected denomination of origin) focusing on  
16 two research issues. The first one was based on qualitative discrimination of figs through  
17 colour assessment comparing the analysis of colour images obtained using a digital camera,  
18 with those obtained according to conventional instrumental methods, i.e. colourimetry  
19 currently done in laboratories. Data were expressed in terms of CIE XYZ, CIELAB and  
20 HunterLab colour spaces, as well as the browning index measurement of each fruit, that were  
21 analyzed using PCA and PLS-DA based methods. The results showed that both chroma meter  
22 and image analysis allowed a complete distinction between high quality and deteriorated figs,  
23 according to colour attributes. The second issue had the purpose to develop image processing  
24 algorithms to achieve real-time sorting of figs using an experimental prototype based on

25 machine vision, advancing an industrial application. An extremely high 99.5% of deteriorated  
26 figs were classified correctly as well as 89.0% of light good quality figs. Lower percentage  
27 was obtained for dark good quality figs but results were acceptable since the most of the  
28 confusion was among the two classes of good product.

29 **Keywords:** fig; image analysis; computer vision; quality; colour; post-harvest processing

## 30 1 INTRODUCTION

31 The growing attention of consumers for regional and local products and the relationship they  
32 have with their territory represents an interesting opportunity for agricultural and rural  
33 development. The promotion of these high quality food products, which can contribute  
34 considerably to rural development and agricultural diversification, could be realized through  
35 designations of origin and geographical indications labels (European Commission, 1996; De  
36 Luca et al., 2015). The designation of the protected denomination of origin (PDO) ‘Fichi di  
37 Cosenza DOP’ (European Commission, 2011) exclusively regards naturally dried fruits of the  
38 domestic fig "*Ficus carica sativa*" (*domestica* L.) belonging to the variety ‘Dottato’ or  
39 ‘Ottato’, and presenting specific physical, chemical and organoleptic features.

40 Very nutritional and healthy, dried figs constitute a popular food for local populations of the  
41 Mediterranean area because of their content in sugars, mainly fructose and glucose, in  
42 essential amino-acids, in carotene (vitamin A), thiamine (vitamin B1), riboflavin (vitamin  
43 B2), ascorbic acid (vitamin C), and minerals such as K, P, Fe, Mg, Ca and Cu. They represent  
44 an important source of fibre and their high content in phenolic compounds strongly contribute  
45 to their definition as functional fruits (Hatano et al., 2008; Farahnaky et al., 2009; Vallejo et  
46 al., 2012). Nevertheless, this strategic cultivation often remains marginalized in many rural  
47 areas, as reported by IPGRI and CIHEAM (2003), where it could contribute significantly to  
48 their sustainable development. According to FAOSTAT ([www.faostat.org](http://www.faostat.org)), fig production in

49 Italy counted 11.520 tons in 2013. In the same year, and according to Istat data (National  
50 Institute of Statistics – Italy), Calabria is in second place after Campania (Southern Italy),  
51 both in terms of cultivated area (474 ha) and production with 2.839 tons, corresponding to  
52 24% of the national total. In Calabria (Southern Italy), fig cultivation is principally located in  
53 the province of Cosenza, where the widest-grown cultivar is the ‘Dottato’.

54 The expectations and requirements of exigent consumers lead the agro-food industries to  
55 increase the marketed product quality, extend its shelf life, reduce the environmental impact,  
56 as well as to improve the content in services, but the intrinsic biological variability between  
57 individual fruit and vegetable products make it impossible for analytical destructive methods  
58 to ensure that each individual fruit meets the high quality standards that constitute a  
59 fundamental criterion for a competitive place in a global market. Dried figs should respond to  
60 the minimum quality requirements established by UNECE (United Nations, 2014). They  
61 should be ‘intact, sound, clean, sufficiently developed, free from living pests and any of their  
62 damages, free from blemishes, areas of discolouration, free from mould filaments, free of  
63 fermentation, free of abnormal external moisture and free of foreign smell and/or taste except  
64 for a slight salty taste’. Nowadays, the quality sorting of dried figs is carried out manually by  
65 experienced operators, which are usually located on both sides of conveyors belts or rollers  
66 transporting fruits to be sorted, but visual methods are slow, subjective and do not guarantee  
67 the quality of the whole production. Hence, the agro-food industry has to implement new  
68 technologies that provide rapid and reliable results, allowing at the same time a qualification  
69 of the product along the entire supply chain.

70 Consumer willingness to purchase often depends on the appearance of the product, which  
71 may also influence the expectations relating to the organoleptic properties, and therefore  
72 consumer behaviour. Colour perception is subjective and can be considered as an indicator of  
73 freshness or maturity state (Valadez-Blanco et al., 2007). Different physical systems have

74 been developed to avoid this subjectivity for colour analysis, which may be evaluated with  
75 visual and/or instrumental procedures (González-Miret et al., 2007). In comparison,  
76 conventional instruments analyze only a small part of the sample, and therefore are not  
77 appropriate for food that often presents a heterogenic surface, and consequently, artificial  
78 vision systems have been developed in recent years in order to overcome this problem and to  
79 make colour analysis more exhaustive and meticulous including the total surface of the  
80 product while carrying out post-harvest operations (Kang & Sabarez, 2009). In this sense,  
81 non-destructive technologies for foodstuff quality assessment such as machine vision systems  
82 constitute a promising tool for quality control as well as product inspection, sorting and  
83 grading (Gómez-Sanchis et al., 2013; Pallottino et al., 2013a & 2013b; Benalia et al., 2015).  
84 Indeed, images are both a large data set and a visible entity that can be interpreted at the same  
85 time (Grahn & Geladi, 2007). Recent progress in image acquisition techniques allows areas of  
86 millions of pixels to be analysed using sophisticated systems (Martin et al., 2007).

87 Even though numerous studies have considered digital imaging employment for the various  
88 aspects of food colour assessment in the recent years (Mendoza et al., 2006; Kang & Sabarez,  
89 2009; Menesatti et al., 2009), these latter are still at experimental scale. They certainly need to  
90 be optimized for large-scale implementation in agro-food industries due to the complexity of  
91 such structures. Computer vision systems developed to work at industrial scale are by far  
92 more complex than those limited to acquire images of static fruit using still digital cameras.

93 The fruit is in movement and randomly oriented, the image acquisition has to be synchronised  
94 with the advance of the fruit and the decision resulting from the image processing must be  
95 provided in real time to deliver the fruit to the proper quality outlet. However if optimized for  
96 large scale implantation, they are of great interest because of the advantages they present:  
97 mainly, rapidness, effectiveness, accuracy and objectiveness; moreover, they are non  
98 destructive, do not need sample treatment, and are able to assess the whole area of the product

99 despite uneven features present (Cubero et al.2011). Therefore, they allow cost and labour  
100 savings, especially when used in automated processes.

101 The present work deals with the assessment of dried fig skin colour comparing two analytical  
102 methods: image analyses and conventional colourimetry, analyzing PDO certified dried figs  
103 ‘Fichi di Cosenza’, as well as deteriorated ones. Furthermore, automated sorting of figs using  
104 an experimental prototype based on machine vision systems was developed in order to  
105 confirm the obtained results and simulate post-harvest processing at industrial scale.

## 106 **2 MATERIALS AND METHODS**

### 107 **2.1. Dried fig colour assessment**

108 Two groups of dried figs belonging to the variety ‘Dottato’ were considered for trials. The  
109 first group consisted of dried figs of excellent quality harvested during the 2012 season,  
110 provided by the Consortium of ‘Fichi di Cosenza DOP’ (European Commission, 2011) in  
111 Southern Italy. The second group, however, comprised purchased fruits of the same variety  
112 ‘Dottato’, from the previous season, which showed a certain quality loss due to major sugar  
113 crystallization, as well as to fungal and insect infestations.

114 Fig skin colour was first measured by means of the chroma meter CR-400 (Minolta Co.,  
115 Osaka, Japan), using the CIE illuminant D65 and the 10° observer standard. The instrument  
116 was calibrated using a white tile reference ( $L^* = 97.59$ ,  $a^* = -0.05$ ,  $b^* = 1.65$ ).  $L^*$  value  
117 indicates lightness when it is equal to 100, or darkness if it is equal to 0. However,  $a^*$  value  
118 represents the red (positive value) or green (negative value); and  $b^*$  value constitutes the  
119 yellow (positive value) or blue (negative value) (Rodov et al., 2012). Each fruit with a mean  
120 of three measurements in different zones represented a replicate.

121 After the chroma meter measurements, image acquisition of each fig was performed with a  
122 digital camera Canon EOS 550D that captured images with a size of 2592 x 1728 pixels and a

123 resolution of 0.06 mm/pixel. Lighting was provided by eight fluorescent tubes (BIOLUX 18  
124 W/965, 6500 K, OSRAM, Germany) placed on the four sides of a square inspection chamber  
125 in a 0°/45° configuration. The camera was connected to a computer, and image analysis was  
126 performed according to a software specially developed for this purpose at the Laboratory of  
127 Artificial Vision for Agriculture (IVIA-Spain), which separates the objects (figs) from the  
128 background using the RGB.R value, and then converts the obtained R, G, B values from the  
129 pixels selected as figs into HunterLab space. The first step consists in the conversion of RGB  
130 values to CIE XYZ values, then, from CIE XYZ to  $L$ ,  $a$ ,  $b$  coordinates as described by Vidal  
131 et al., (2013) and to  $L^*$ ,  $a^*$ ,  $b^*$  coordinates attending the equations in HunterLab (2008), in  
132 both cases assuming a D65 (6500 K) illuminant and a 10° observer.

133 Since RGB colour model is device dependent (Menesatti et al., 2012), a previous calibration  
134 step was done consisting in the comparison of the colour of each patch of a digital colour  
135 checker (Digital ColorChecker SG Card, X-Rite Inc, USA) acquired using the chroma meter  
136 and the camera. The colours were then converted from RGB to CIELAB and a linear  
137 regression was done between both series of values giving a  $R^2 > 0.98$  for the three  $L^*$ ,  $a^*$  and  
138  $b^*$  components. Hence, it was considered that the camera provided accurate colours.

### 139 **2.1.2. Data analysis**

140 Data obtained from both conventional colourimetry and image analysis were then expressed  
141 in terms of  $XYZ.X$ ,  $XYZ.Y$ ,  $XYZ.Z$ ,  $L^*$ ,  $a^*$ ,  $b^*$ ,  $L$ ,  $a$ ,  $b$  coordinates, and the ratios  $L/a$ ,  $L^*/a^*$  in  
142 order to look for the best variables among all that permit the best segregation between both  
143 groups since that it was the first time that such analyses are done on dried figs. In addition, the  
144 browning index ( $BI$ ) that it is considered to be an important parameter where enzymatic or  
145 non-enzymatic browning processes occur (Mohammad et al., 2008) was also calculated and  
146 considered in the model (eq. 1, Palou et al., 1999).

147 
$$BI = \frac{100(x - 0.31)}{0.172} \quad (\text{eq. 1})$$

148 where:

149 
$$x = \frac{a + 1.75L}{5.645L + a - 3.012b}$$

150 At the end of the trial, a total of 26 parameters (variables) were obtained and statistically  
 151 analyzed according to principal component analysis (PCA) and partial least squares -  
 152 discriminant analysis (PLS-DA), using SIMCA-P v13 (MKS Umetrics AB, Sweden). In order  
 153 to compress and interpret the internal relationships between variables, and at the same time  
 154 check whether there are some of these being able to segregate between the two analyzed  
 155 classes (deteriorated and not deteriorated figs), principal component analysis PCA (Jackson,  
 156 1991) was applied. PCA is a projection method of the original variables onto new ones, called  
 157 latent variables, orthogonal and arranged according to their explained variance. This is carried  
 158 out expressing a matrix  $X$  as:

159 
$$X = TP^T + E \quad (\text{eq. 2})$$

160 where  $T$  is the score matrix,  $P$  is the loading matrix and  $E$  is the residual matrix for  $X$ . This  
 161 way makes it possible to determine the general pattern of any process, and the relevant  
 162 variables that rule it.

163 However, PCA does not necessarily search for those variables that better discriminate  
 164 between classes, but only for those gathering the highest variance in the data. Thus, when  
 165 looking for segregating, another latent-based multivariate projection model, such as PLS-DA  
 166 (Sjöström et al., 1986) is a more sensible technique to apply. PLS (Geladi & Kowalski, 1986)  
 167 models the data through the use of eq. 2 and these other following expressions:

168 
$$T = XW^* = XWP^T W \quad (\text{eq. 3})$$

169 
$$Y = TC^T + F \quad (\text{eq. 4})$$

170 where  $T$  is the score matrix,  $P$  the loading matrix for  $X$ ,  $C$  the loading matrix for  $Y$ ,  $W$  and  $W^*$   
171 weighting matrices, and  $F$  the residual matrix for  $Y$ .

172 In the case of PLS-DA,  $Y$  is built from as many dummy variables as classes we have to  
173 segregate. A dummy variable is a binary variable formed by 1's and 0's, the former linked to  
174 the class the dummy variable is related to, and zeros to the rest of observations. Hence, the  
175 PLS-DA looks for those internal directions that best segregate the classes of interest, also  
176 trying to explain  $X$  reasonably.

177 This way, it is possible to compute, from any matrix  $X$ , the prediction of  $Y$  as:

$$178 \quad Y_{pred} = XB_{PLS} = TQ^T = XW(P^TW)^{-1}Q^T \quad (\text{eq. 5})$$

179 Where

$$180 \quad B_{PLS} = XW(P^TW)^{-1}Q^T$$

181 When applied to images, these techniques belong to Multivariate Image Analyses, MIA  
182 (Prats-Montalbán et al., 2011). Together they make up the most suitable analytical tools for  
183 the trials that were carried out, taking into account that each sample was considered regarding  
184 its 26 variables.

## 185 **2.2. In-line dried fig sorting**

186 Due to the high complexity of handling small fruit and the relatively low market in  
187 comparison to other fresh fruit, there are not commercial electronic sorters of dried figs to  
188 separate them in qualities. Hence, there is a need to develop such sorter. For this purpose,  
189 automated sorting trials based on a computer vision system were performed on an  
190 experimental prototype, developed at the Laboratory of Artificial Vision for Agriculture  
191 (IVIA-Spain) that was originally designed for mandarin orange segment and pomegranate aril  
192 in-line sorting (Blasco et al., 2009a; Blasco et al., 2009b) and that was adapted for the sorting

193 of dried figs. It principally consists of three functioning elements: supply unit; inspection unit  
194 and separation unit (figure 1).



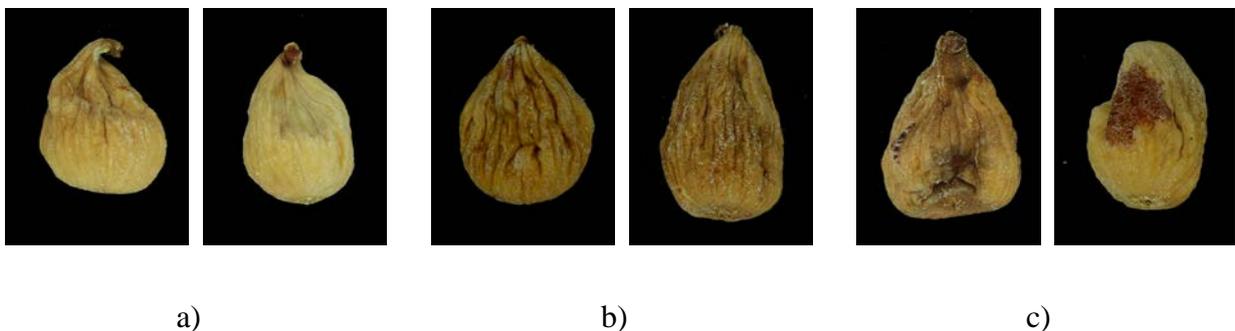
195  
196 *Figure 1. Picture of the in-line sorting prototype*

197 From the supply unit, fruit are spread on a number of conveyor belts, 30 mm wide and 250  
198 mm long, moving at a relatively high speed (0.5 m/s). They pass through the inspection unit  
199 which consists of two progressive scanning colour cameras (JAI CV-M77), placed at  
200 approximately 0.9 m above the subject, that provide RGB images (512 x 384 pixels) with a  
201 resolution of 0.70 mm/pixel. Cameras are equipped with 12 mm lens, and lighting is provided  
202 by light emitting diode (LED) lamps. The entire system is housed in a frame of stainless steel  
203 suitable for agro-food products. After each image processing, the computer sends data about:  
204 fruit position, the number of the conveyor belt on which it is located, and the corresponding  
205 category (issue) to the computer which is responsible for directing the movement of the  
206 inspected fruit to the separation unit and its subsequent categorisation.

207 The trials considered 96 figs, which had previously been classified in the subsequent three  
208 categories: 31 light PDO figs, 26 dark PDO figs and 39 deteriorated figs (figure 2). Each fruit  
209 in the validation set went through the whole classification process five times in random  
210 positions, orientations and sides, thus it was as if 480 figs were categorised. An additional set  
211 of 24 figs was used to build the models and train the image processing software.

212 One of the requirements of current quality standards for dried figs is that the contents of each  
213 package must be uniform (United Nations, 2014). Moreover, consumers are prone to purchase  
214 lots with uniformity of colours and sizes. Hence, the output of each category was established  
215 as follows:

- 216 • Category 0: (Light PDO figs): the fig arrives at the end of the conveyor belt.
- 217 • Category 1: (Dark PDO figs): the fig is ejected at the first outlet.
- 218 • Category 2: (Deteriorated figs): the fig is ejected at the second outlet.



219 Figure 2. *Samples with different colours that should belong to different categories: a) light, b) dark*  
220 *and c) defective uneven coloured figs*

221 In-line systems working in real-time have to run very fast image processing algorithms and  
222 hence it is not possible to incorporate complex segmentation models although it could be  
223 more effective in some cases. On the other hand, it is very important that the quality  
224 parameters can be easily controlled by non-experienced workers through a friendly interface.  
225 This means that, the machine has to prioritize easy to handle methods to separate the fruits  
226 over other maybe more robust but also more complex statistical methods.

227 Following this principle, image segmentation was developed based on the analysis of the  
228 colour that was done on images captured with the mentioned industrial cameras under  
229 dynamic conditions. As first step, each pixel in the image was classified as background or as  
230 belonging to an object to be analysed. Since there was a great contrast between the white  
231 background and the fruit, a threshold was enough to properly remove the background from  
232 the image analysis. Preliminary analysis of the histogram of the training images determined  
233 that a threshold value of  $T_0=100$  in the green band could separate the fruit without error.  
234 Therefore, any pixel with a value in the G channel above  $T_0$  could be considered as belonging  
235 to the background and removed. This operation was performed only in the regions of interest  
236 corresponding to the conveyor belts while the parts of the images outside these regions were  
237 not considered.

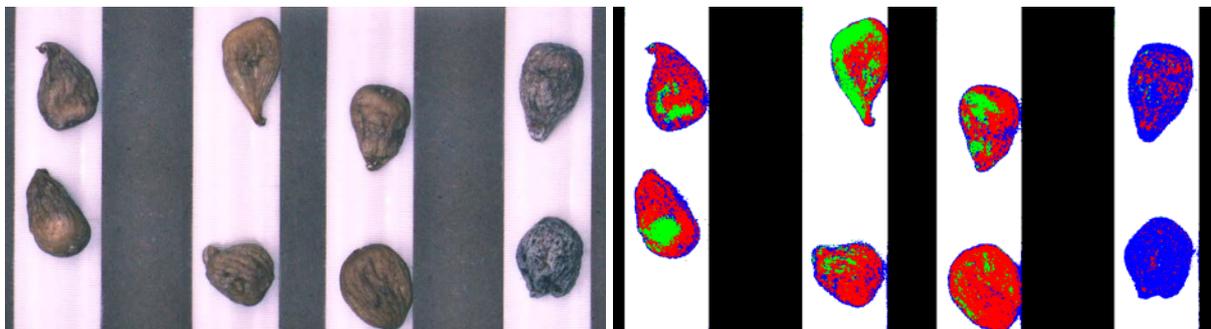
238 All remaining pixels in the images were considered as belonging to potential figs. Therefore,  
239 the RGB values of the remaining pixels were converted into CIE XYZ and CIELAB  
240 coordinates to calculate the *BI*.

241 To separate the pixels in the figs into any of the predefined classes it was necessary a previous  
242 analysis. An analysis of the variance (ANOVA) was carried out for each variable using the  
243 training samples to determine in which of the different available colour coordinates the figs  
244 that belonged to different qualities could be better discriminated, or if it was necessary, a  
245 combination of several colour coordinates. Once defined the variables, the thresholds among  
246 the three classes initially set in the sorting prototype were established from the data extracted  
247 the basic statistics (tables 3 and 4). Once determined the colour indexes and the thresholds,  
248 the algorithms were programmed to classify the pixels in the images in one of the three  
249 categories as follows, where the thresholds  $T_1$  and  $T_2$  were obtained from the previous  
250 analysis:

- 251 • If average  $BI < T_1$  the pixel was considered deteriorated
- 252 • If average  $BI \geq T_1$  and average  $XYZ.X < T_2$ , the pixel was considered a dark PDO;
- 253 otherwise the pixel was considered as belonging to a fair PDO fig.

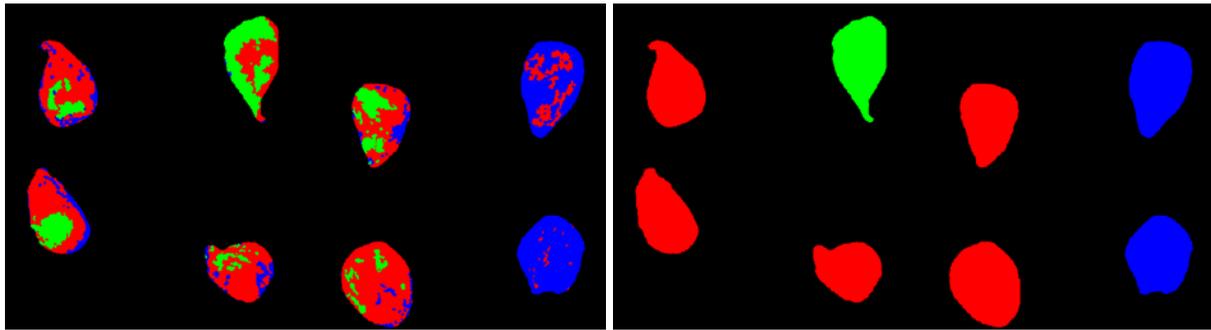
254 After the pixels-wise image segmentation, it was necessary to perform a filtering process in  
 255 order to reduce the noise caused by shadows found in the borders of the fig and by small  
 256 groups of isolated pixels. This process consisted on a two-iteration erosion of the complete fig  
 257 followed by a median filter. Finally, the decision about the category of the fig was set based  
 258 on the number of pixels of each class belonging to the fig, which is equivalent to classify the  
 259 fig into the class occupying the major area in the fig.

260 The sequence of image processing carried out by the sorting machine in real time is shown in  
 261 figure 3. The original image captured by the cameras shows the figs while they are  
 262 transported by the conveyor belts. The first step corresponds to the segmentation based on the  
 263 thresholds in the regions of interest defined by the known position of the conveyor belts. Then  
 264 the filtering is performed in order to reduce the noise and the segmentation problems caused  
 265 by shadows found in the borders of the figs. Finally, the decision is taken by counting the  
 266 amount of pixels belonging to the different classes. For the case shown in figure 3, attending  
 267 the decision of the vision system, the figs in blue belonged to the deteriorated class, the figs in  
 268 red are dark figs, and the fig in green is a light one.



270 a)

b)



271

272

c)

d)

273 Figure 3. Steps in-line image processing of the figs sorting machine. A) original image captured by the  
 274 cameras, b) segmented image, c) filtered image, and d) decision image

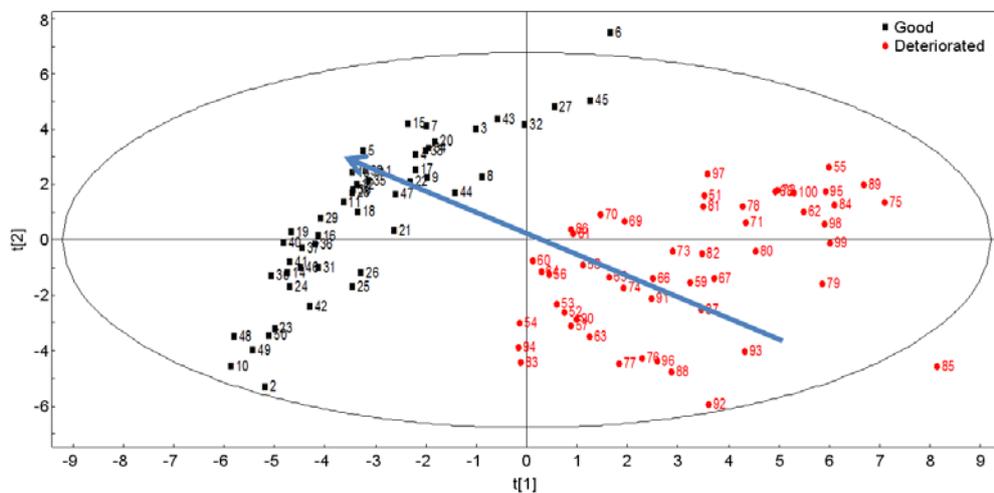
275 The tests were carried out by placing the figs into a vibrating platform that guide the fruit  
 276 randomly to the different conveyor belts of the prototype. Each fruit was transported by the  
 277 conveyor belts, analysed and sorted by the outlet corresponding to their assigned category.  
 278 This was done for the different categories of fruit separately for a proper identification and  
 279 reference of the fruit once it was separated in the outlets, since it would be difficult to  
 280 properly identify each individual fruit in the outlets after being sorted by the machine if all of  
 281 the figs would had been tested in the same trial. After each trial, the fruit in the different  
 282 outlets was accounted and tested again for five times.

### 283 3 RESULTS AND DISCUSSION

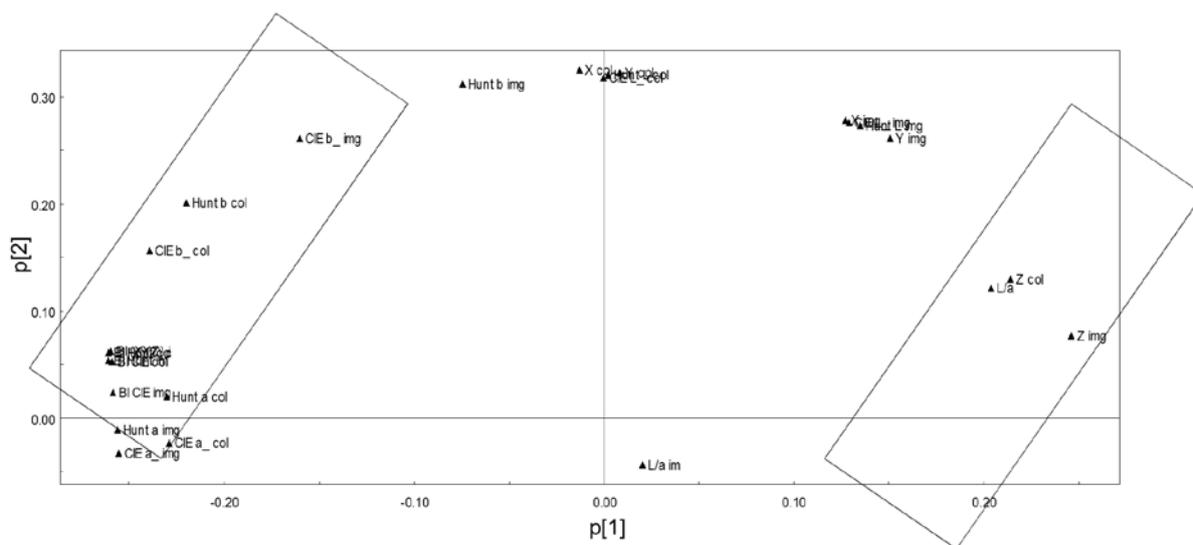
#### 284 3.1. Dried Fig colour assessment

285 Figure 4 represents the score plot of PCA (2 PC's,  $R^2$  81%), showing an overview of the  
 286 behaviour of each fruit belonging to the studied groups with PDO figs of Cosenza in black  
 287 and deteriorated ones in red. Here, as stated above, the analysis considered the totality of  
 288 variables (26), that is, those obtained by conventional colourimetry as well as those obtained  
 289 from image processing. In this case, the PCA model is able to segregate the two classes. In

290 order to assess for which ones are mainly responsible for segregation, the loadings plot (figure  
 291 5) is inspected.



292  
 293 Figure 4. Score plot of PCA results considering all the variables (image analysis and conventional  
 294 colorimetry). The ellipse represents 95% confidence interval.  
 295 The segregation between class 1 (sound figs represented by black points) and class 2  
 296 (deteriorated figs represented by red points) is mainly characterized by the variables  
 297 XYZ.Zcol, XYZ.Zimg and L/a on one hand, and CIEb\_img, Huntb\_col, and CIEb\_col, on the  
 298 other hand.

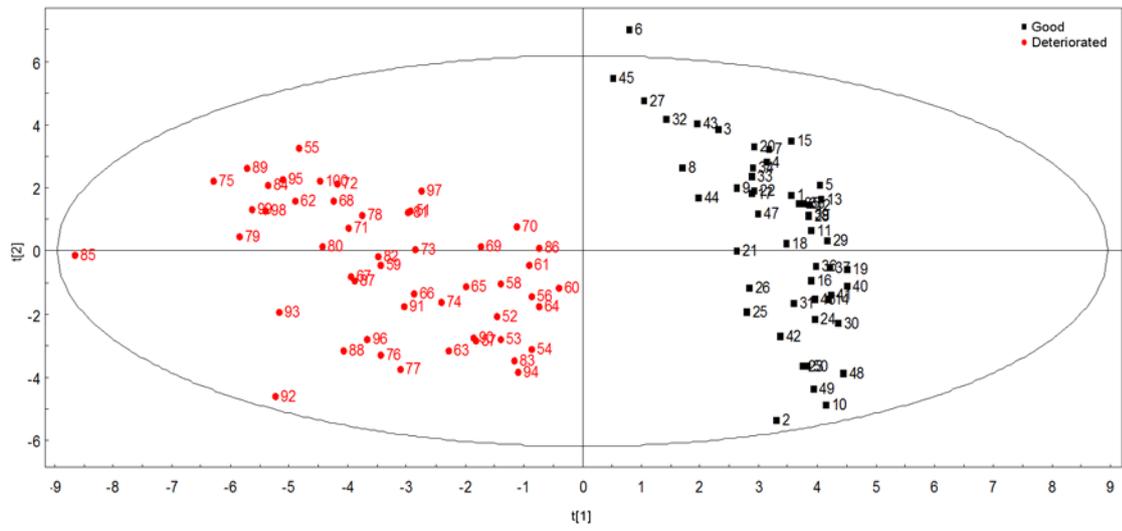


299  
 14

300 Figure 5. *Loading plot of PCA results considering all the variables (image analysis and conventional*  
301 *colorimetry). The rectangles include the most segregating variables.*

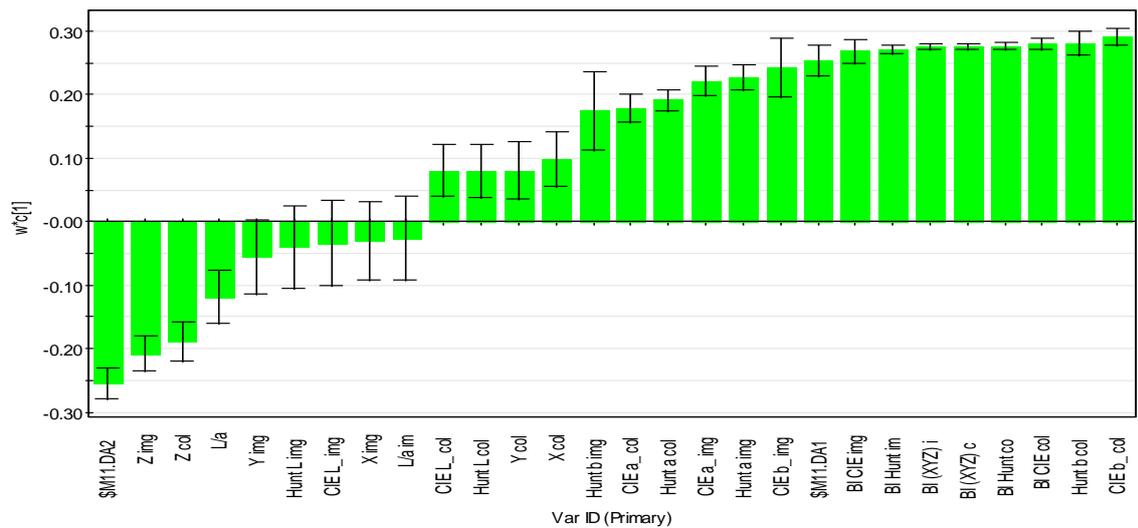
302 PLS-DA results highlight two clusters, each one corresponding to one of the assessed groups  
303 of figs (figure 6). The plot shows that the first component is able to segregate between the two  
304 classes. From the PLS-DA weights of the first component (figure 7), the variables responsible  
305 for the segregation can be derived. Note that, in the case of having more than one discriminant  
306 component in the model, other approaches (e.g. VIP's) would be more sensible. Nevertheless,  
307 in this case, since the discriminant direction is mainly related to the first latent variable, both  
308 approaches provide equivalent results (see figure 8), with the advantage that the weights  
309 provide the positive or negative correlation of each variable with each of the classes to be  
310 segregated. It must be stated that, for classification purposes, the model was built with 5 latent  
311 variables and an R<sup>2</sup>Y value of 96.5% and a Q<sup>2</sup>Y value of 95%, which in practice means that  
312 all figs were correctly classified in a 7-blocks cross-validation procedure. However, this was  
313 not the goal of the analysis, but selecting the most discriminant variables and comparing them  
314 with the ones used in the already built in-line sorting machine.

315 On the other hand, the score plots of PCA and PLS-DA show similar clusters for the two  
316 studied groups, and PCA confirms that the XYZ.Z coordinate is one of the best discriminant  
317 variables. The difference between the two score plots lies in the fact that PCA does not look  
318 for segregating both classes, but for maximizing the variance, as previously stated. Anyway,  
319 since the rotation in the components is not very large, the variables indicated by the loadings  
320 barplot (figure 9) are almost the same as the ones outlined by the first component weights of  
321 the PLS-DA model (figure 7).



322

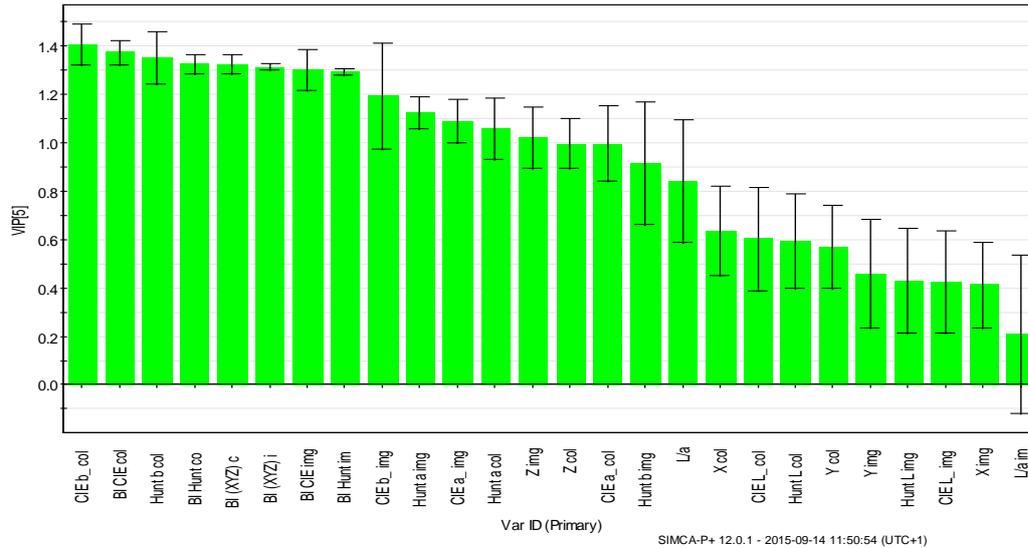
323 Figure 6. Score plot of PLS-DA results considering all the variables (image analysis and conventional  
 324 colorimetry). The ellipse represents 95% confidence interval.



R2X[1] = 0.513287 SIMCA-P+ 12.0.1 - 2015-09-14 11:52:45 (UTC+1)

325

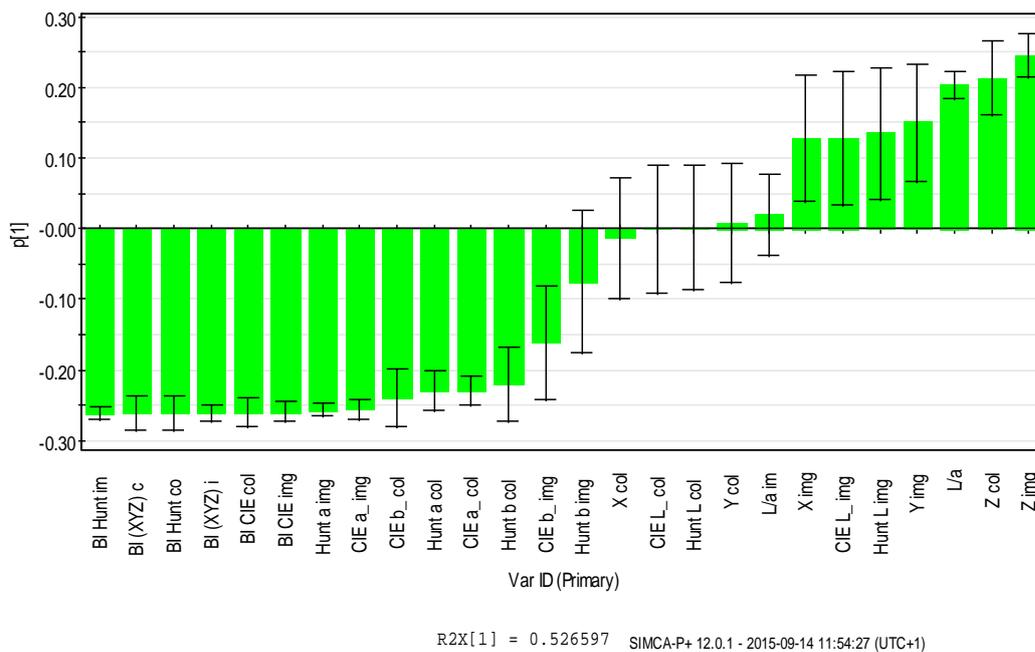
326 Figure 7. Weights plot of the first component of the PLS-DA model considering all the variables  
 327 (image analysis and conventional colorimetry)



328

329 Figure 8. *VIP's plot of the first component of the PLS-DA model considering all the variables*

330 *(image analysis and conventional colorimetry)*



331

332 Figure 9. *Columns plot of PCA for the first component considering all the variables (image analysis*

333 *and conventional colorimetry)*

334 The study carried out highlights that, in this case, both statistical analyses, PCA and PLS-DA,

335 could distinguish clearly between high quality PDO figs and deteriorated ones, showing the

336 effectiveness of both techniques used for fig colour assessment as a qualitative parameter.

337 Hence, analysis of high quality images could perfectly replace currently destructive methods

338 based on sampling for this purpose. The browning index seemed to be an interesting index  
 339 that showed this distinction, and therefore a valid indicator for dried fig quality assessment  
 340 but the colour measurement in some different spaces did not present significant differences.  
 341 Nevertheless, note that, depending on the study, the discriminant directions in PCA (if any)  
 342 might not be necessarily on the first components, hence being mandatory to look for them  
 343 throughout the ones gathered in the model (Prats-Montalbán et al., 2006).

### 344 **3.2. In-line dried fig sorting**

345 The methods, conditions, aims and equipment used for classifying the fruit in real-time using  
 346 and industrial machine are different from those used to assess colour using a standard  
 347 colorimeter and hence new variables need to be selected. ANOVA's carried out on the main  
 348 discriminant variables highlighted by the PLS-DA and PCA analyses achieved similar results  
 349 in terms of significance. From these analyses, variables *BI* and *X* were selected for  
 350 segregating the different categories of figs during the in-line real-time inspection using the  
 351 machine since the study of the basic statistics clearly determined that it was possible to set  
 352 thresholds to separate among the different categories. Tables 1 and 2 show the ANOVA for  
 353 these variables while tables 3 and 4 show the summary of the statistics. Browning index could  
 354 be clearly used to separate between good and defective figs and it was decided from these  
 355 data to use a threshold value of  $T_1=35$ . On the other hand, dark and light figs could be  
 356 separated using the *X* colour value and hence, using the data in table 4, a threshold value of  
 357  $T_2=7$  was configured in the machine.

358 Table 1. Analysis of variance for Browning Index

<i>Source</i>	<i>Sum of Squares</i>	<i>Df</i>	<i>Mean Square</i>	<i>F-Ratio</i>	<i>P-Value</i>
Between groups	9435.52	2	4717.76	83.03	0.0000
Within groups	5284.36	93	56.82		

Total (Corr.)	14719.90	95
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359

360 Table 2. Analysis of variance for *X*

<i>Source</i>	<i>Sum of Squares</i>	<i>Df</i>	<i>Mean Square</i>	<i>F-Ratio</i>	<i>P-Value</i>
Between groups	311.73	2	155.86	53.48	0.0000
Within groups	271.04	93	2.91		
Total (Corr.)	582.77	95			

361

362 Table 3. Summary Statistics for Browning Index

<i>Class</i>	<i>Average</i>	<i>Standard deviation</i>	<i>Coeff. of variation</i>	<i>Min</i>	<i>Max</i>
Light	48.27	5.43	11.24%	36.58	59.54
Dark	43.13	8.43	19.90%	31.56	61.71
Deteriorated	25.93	8.31	32.04%	8.48	41.70

363

364 Table 4. Summary Statistics for *X*

<i>Class</i>	<i>Average</i>	<i>Standard deviation</i>	<i>Coeff. of variation</i>	<i>Min</i>	<i>Max</i>
Light	8.81	1.89	21.78%	6.32	14.53
Dark	5.63	0.90	15.90%	4.08	7.75
Deteriorated	10.08	1.94	19.26%	5.56	13.15

365

366 Results of the performance of the machine are shown in table 5. At the end of the trials,  
 367 99.5% of deteriorated figs were correctly classified, as well as 89% of light PDO figs;  
 368 however, just 69.2% of accurate classification was reached for dark PDO figs. This decrease  
 369 of accuracy is related to the unevenness of the figs' skin colour. In fact, some fruits had a  
 370 lighter colour on one side than on the other; consequently, the machine classified them

371 according to the colour of the side showing as they randomly passed. It has to be remarked  
 372 that the results correspond to the inspection of the validation set of the figs five times, but  
 373 each time they fall down in a random position, orientation and side on the conveyor belts and  
 374 were captured in a different and random location in the image. This means that for each time,  
 375 the conditions and lighting of each particular fig were different.

376 A certain degree of confusion is normal using the fast classification method implemented.  
 377 However, the main confusion occurred between classes light and dark which could be  
 378 acceptable since both are good quality figs separated only for commercial reasons. On the  
 379 other hand, a little confusion happened between good and deteriorated figs that are more  
 380 important from the point of view of the final quality. An aspect to improve is that the machine  
 381 classified 3.8% deteriorated figs as dark, which, even it could be under a tolerance of 5%,  
 382 should be reduced. On the contrary, it would be of less importance if dark figs were classified  
 383 as deteriorated. These results illustrate that fig sorting, using the above-described system, was  
 384 achieved successfully. The highest percentage was obtained each time for deteriorated figs,  
 385 followed by light PDO ones, and then dark PDO figs.

386 Table 5. Results of automated sorting

Machine\Vis	Light PDO figs	Dark PDO figs	Deteriorated figs
Light PDO figs	89.0%	26.9%	0.5%
Dark PDO figs	11.0%	69.2%	0.0%
Deteriorate figs	0.0%	3.8%	99.5%

387

388 To identify a specific index to determine accurately the quality for PDO dried figs of  
 389 Cosenza, the achieved analysis has to be consolidated by further research, taking into account  
 390 additional parameters i.e., colour change according to ripeness, drying status as well as the

391 correlation of skin colour with the contents of anthocyanins (Rodov et al., 2012). This may be  
392 achieved and incorporated in the future to the in-line sorting machine with the use of faster  
393 computing units.

394 Some of the problems found could be resolved using, instead of conveyer belts, bi-conic roller  
395 conveyors (ElMasry et al., 2012) which turn the fruits as they progress, allowing the system to  
396 inspect their whole surface. On the other hand, a complex analysis of the colour or the texture  
397 of the figs would result in a better accuracy of the classification, but the computing  
398 requirements would not ensure actual real-time processing at a commercial speed.

399 Image processing time was about 15 ms, permitting an analysis of up to 65 images/s.

400 However, due to mechanical limitations of the prototype, and also because a very high speed  
401 could damage the product when it is expelled by the outlets, the speed of the conveyor belts  
402 was limited to 0.5 m/s, obtaining then 10 analysed images per second. Considering an ideal  
403 distance of 0.1 m between two consecutive figs, at the highest speed of the conveyor belts  
404 (0.5 m/s), the tested prototype has the productivity of about 40 figs/s, corresponding  
405 approximately to 2160 kg/hour. The system has been proved on a prototype with several  
406 mechanical limitations, it is expected that the performance in terms of accuracy and capacity  
407 of fruit process is higher when the system will be developed into an industrial machine.

#### 408 **4 CONCLUSIONS**

409 As currently carried out, dried fig inspection and grading methods are labour intensive and  
410 unreliable due to machine speed and inspector fatigue. Therefore, the development of an  
411 effective integrated inspection system that can detect quality according to previously  
412 established parameters of the whole fruit would be valuable for the fig industry. The present  
413 work showed that the combination of computer vision systems and latent-based multivariate  
414 statistical projection models used for this purpose allowed these objectives to be reached

415 under laboratory conditions for manual quality inspection which can be suitable for small  
416 productions or when only the control of a few number of samples is required. These results  
417 are interesting because they illustrated that both, chroma meter and image analysis allowed an  
418 effective distinction between high quality dried figs and deteriorated ones, based on colour  
419 parameters, being the photographic camera much cheaper and easy to use than the chroma  
420 meter.

421 A system for in-line sorting of figs in real-time was developed based on computer vision and  
422 colour parameters providing reliable results. This is the first attempt to create a machine  
423 capable of sorting dried figs in real-time using computer vision and a machine with capability  
424 of separating the fruit into different categories. The system could classify correctly between  
425 three classes of figs using the browning index and the *X* colour coordinate. The test were  
426 carried out in dynamic conditions with the figs being transported under the camera at high  
427 speed, and later separating the figs into different categories by different outlets depending on  
428 the decision of the vision system. This was repeated five times achieving always good results,  
429 having the major confusion between the two classes of sound figs but a little confusion of  
430 only 0.5% was done between sound and defective figs which is the most important from the  
431 commercial point of view.

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