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Additional Information

Beamforming for large-area scan and improved SNR in array-based photoacoustic microscopy

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Abstract

Beamforming enhances the performance of photoacoustic microscopy systems for large-area scan. We present a detailed study quantifying and comparing SNR using different beamforming strategies to increase the field-of-view of optical-resolution photoacoustic-microscopy systems. The system combines a low-cost PLD with a 128-element linear ultrasound probe. Three beamforming strategies are analysed: a no-beamforming method equivalent to a single-element plane transducer, a static beamforming method that mimics a single-element focused transducer, and a dynamic beamforming applying a delay-and-sum algorithm. The imaging capabilities of the system are demonstrated generating high-resolution images of tissue-mimicking phantoms containing sub-millimetre ink tubes and an ex vivo rabbit's ear. The results show that DAS beamforming increases and homogenizes SNR along 1-cm² images, reaching values up to 15 dB compared to a no-beamforming method and up 30 dB with respect to out-of-focus regions of the static configuration. This strategy makes it possible to scan larger surfaces compared to standard configurations using single-element transducers, paving the way for advanced array-based PAM systems.

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Keywords: Photoacoustic imaging, OR-PAM, array-based, DAS beamforming, large-area scan, pulsed laser diode

1. Introduction

Photoacoustic microscopy (PAM) is an imaging technique ²⁸ that combines optical excitation with ultrasound reception 29 forming images from directly depth-resolved signals by raster-³⁰ scanning the sample without applying reconstruction algo-³¹ rithms [1, 2]. It has received a growing interest over the last ³² 6 decade for its ability to provide anatomical, molecular, and ³³ functional imaging. As a short laser pulse is aimed at super-34 ficial biological tissue, some of the photons are absorbed by ³⁵ 9 chromophores (oxyhemoglobin, deoxyhemoglobin, etc.) or ex-³⁶ 10 ogenous contrast agents, inducing a local and fast temperature ³⁷ 11 rise. As a result of the local thermoelastic expansion a pressure ³⁸ 12 rise is produced leading to the generation of ultrasonic waves, ³⁹ 13 a phenomenon known as the photoacoustic effect [3]. 14

PAM is typically classified in two main categories, optical-⁴¹ 15 resolution (OR-PAM) [4], based on the optical ballistic regime, 16 and acoustic resolution (AR-PAM) [5], based on the diffusive ⁴³ 17 regime. The lateral resolution of these two modalities is inher-18 ently different [1]. In OR-PAM, the laser excitation is tightly ⁴⁵ 19 focused and hence, the size of the laser spot determines the lat- ⁴⁶ 20 eral resolution, while in AR-PAM the lateral resolution is deter-⁴⁷ 21 mined by the ultrasound system because the focal spot of the 48 22 acoustic beam is smaller than the optical one, which is gener-49 23 ally weakly focused. Resolution trades off with imaging depth ⁵⁰ 24 [6, 7]: OR-PAM achieves better lateral resolution at the expense ⁵¹ 25

of a shallow penetration [8, 9], whereas the opposite occurs in AR-PAM [10].

For the light source, OR-PAM typically uses different types of short-pulsed solid state lasers, such as Nd:YLF [4], Nd:YAG [7], Nd:YV04 [8], or even Ti:Sapphire [11]. They provide short pulses and high energy per pulse, although they generally have a high cost, large size and require a bulky cooling system. Moreover, the repetition rate may be relatively low [12]. As an inexpensive and more compact alternative, pulsed laser diodes (PLD) [13–18] or light emitting diodes (LED) [19–21] are often employed (see Ref. [22] for a thorough review on low-cost sources). Their main drawback is their poor signal-to-noise ratio (SNR) which usually requires multiple averaging.

Regarding ultrasound detectors, conventional OR-PAM systems rely on piezoelectric transducers or optical-acoustic detectors (such as Fabry-Perot ultrasound sensors) [6]. Many piezoelectric-based OR-PAM systems use focused singleelement transducers with focal spots of very few mm², often submerged in water or other fluids that allow relative displacement between sample and probe, resulting in relatively small images. Conversely, optical-acoustic detectors with improved sensitivity and wide acceptance of angles have been proposed as good candidates to increase the field-of-view (FOV) of photoacoustic images, such as detectors based on fibre optic sensors [23, 24].

Array-based PAM systems were initially proposed with different goals: As a way to leverage the ultrasound probe present in US array systems, as demonstrated by Wang and co-workers in their implementation for guiding needle biopsy of sentinel lymph nodes in rats [25], or Merhmohammadi and co-workers,

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who proposed a miniaturized array-based photoacoustic endo-110 56 scopic imaging system designed for volumetric dual-modal US111 57 and PA images [26]; to take advantage of the in-depth dynamic 12 58 focusing capability of ultrasound arrays to form volumetric im-113 ages [27, 28]; or to improve the imaging speed for obtaining¹¹⁴ real-time imaging systems [29–32]. Hajireza et al. reported an115 61 array-based optical resolution photoacoustic microendoscopy116 62 system composed of a fibre laser and a 128-element ultrasound₁₁₇ 63 linear array. With the acquired signals, they later performed₁₁₈ 64 delay-and-sum (DAS) beamforming to produce small images119 65 $(< 1 \text{ mm}^2)$ of the vasculature of the ear of a rat [33]. Zheng₁₂₀ 66 and co-workers applied DAS beamforming within the surface121 67 of the imaging plane, showing the SNR improvement when us-122 68 ing a 64-element phased array compared to images obtained₁₂₃ 69 using only one element of the phased array [34]. However, the₁₂₄ 70 capabilities of DAS beamforming within the imaging plane to125 71 increase the FOV and SNR with respect to other standard con-126 72 figurations, i.e., single-element plane or focused transducers,127 73 remains unexplored. 128 74

In this work, we study the performance of several beamform-129 75 ing strategies to generate large area images in an array-based130 76 OR-PAM system using a low-cost PLD laser as the excitation131 77 source. We show that DAS beamforming makes it possible to132 78 greatly increase and spatially homogenize the SNR of the im-133 79 age, especially in out-of-focus regions, compared to other PAM₁₃₄ 80 configurations featuring single-element ultrasonic transducers.135 81 In addition, the use of DAS beamforming avoids the need to dis-136 82 place the ultrasound probe with respect to the imaged sample.137 83 Images of sub-millimetre polyethylene tubes filled with India138 84 ink embedded in tissue mimicking phantoms and the microvas-139 85 culature of an ex vivo rabbit ear were acquired in order to eval-140 86 uate the performance of the system. A detailed laser beam spot141 87 characterization was performed by both optical and acoustical142 88 means yielding a lateral resolution of 200 x 119 μ m², while the₁₄₃ 89 experimental results of the developed PAM system demonstrate144 90 a spatially homogenized SNR increase up to nearly 30 dB for145 91 out-of-focus regions along a large area scan of around 1 cm²,¹⁴⁶ 92 compared to a classical static focus configuration. 147 93

94 **2. Materials and methods**

2.1. Laser diode excitation and beam optics configuration

A high-power PLD of 650 W output peak power and 905 \pm_{153} 96 10 nm central wavelength was used (model 905D5S2L3J08X,154 97 Laser Components, Germany). As depicted in Fig. 1, the laser 155 98 diode is driven by forward current pulses from a variable volt-156 99 age driver module (LDP-V 80-100, PicoLAS, Germany) in or-157 100 der to produce a burst of optical power pulses at a 2 kHz rep-158 101 etition rate and 100 ns pulse width (0.02% duty cycle) dur-159 102 ing a given excitation time. The PLD pulsed operation was160 103 set to a safe and non-destructive regime well below its abso-161 104 lute maximum ratings of 150 ns pulse width and 0.1% duty cy-162 105 cle. The laser diode driver is first configured from a dedicated₁₆₃ 106 microcontroller-based board, which sets the laser diode output₁₆₄ 107 power, ranging linearly from the laser threshold up to the max-165 108 imum optical for the driver voltages 23-100 V; and also mon-166 109

itors safe operation settings like temperature and voltage limits. Afterwards, it runs as a signal-follower of the square pulse train sent by the pulse generator to the driver input signal port. Timing synchronization between the ultrasound DAQ system and PLD output pulses is achieved through a TTL trigger signal generated by the ultrasound system to the pulse generator.

The PLD is a mini-stack of 30 single-emitters arranged in 2 columns with 5 bars of 3 emitters each, which results in a structured light pattern emitted from a whole rectangular area of $800 \times 440 \ \mu m^2$. It emits an elliptic and relatively high divergent beam with full-angle divergence of 10° and 25° for the horizontal (slow axis) and vertical (fast axis) planes, respectively. The PLD beam quality for each plane is $M^2 \approx$ (121, 166), which can be determined from the well-known relation $BPP = M^2 (\lambda/\pi)$ for its nominal wavelength $\lambda = 905$ nm and $BPP \approx (35, 48)$ mm mrad, the beam-parameter product of the emitting surface radius and half-divergence, $BPP \equiv w_0 \theta$. Laser diode stacks have in general high M-squared values, much greater than a diffraction-limited beam $M^2 >> 1$ due to their inherently multimodal emission, which will limit the smallest beam spot size achievable by any optics, and ultimately the lateral resolution of OR-PAM imaging systems.

The optics scheme used to deliver and concentrate the laser beam power from the PLD into a small spot excitation area inside the imaging target (phantom or tissue) is shown in Fig. 1. The PLD optics comprises two plano-convex aspheric lenses, both with suitable anti-reflection coatings in the NIR range. A first lens of $f_1 = 20.1$ mm focal length, a diameter of 25 mm and high numerical aperture NA=0.6 (ACL2520U-B, Thorlabs), is used to collect and collimate, or pre-focus, the light from a highly divergent beam emitted by the PLD stack. A second lens of shorter focal length of $f_2 = 10.5$ mm, with 12 mm on diameter and NA=0.54 (ACL1210U-B, Thorlabs), focalises the laser into a small spot area corresponding to the beam waist at the focus of this two-lens optical scheme. The aperture stop of this configuration is limited to the clear aperture of the focusing lens CA=10.8 mm. The distances for this optical configuration were set to: $s_1 = 50$ mm from the laser diode emitting surface to the collimating lens object principal plane H_1 , and $s_2 = 11$ mm from there to the focusing lens image principal plane H'_2 . The working distance (WD) is defined from the last lens mount surface to the focused beam waist giving thus the usable laser excitation depth inside the target volume, as depicted in the optical schematic of Fig. 1. After simulations of this optical configuration, based on both ray-tracing and M-squared-corrected Gaussian optics, the WD for our setup was set to 2.3 mm on air, and 3 mm on water (with refractive index n = 1.33). Note that the WD from the lens backplane would be longer but it is shortened by the lens mount fixing ring of 1.7 mm width.

The laser power distribution cross-section at the beam focus was obtained in order to better determine the beam spot size and also the power eventually delivered to it, as presented later in Section 3.1. A cross-section image at the focal plane was acquired from ray-tracing simulations to be analysed and compared to a measured image of the focus taken with a beam profiler CCD camera (LT665, Ophir, Israel) and a 60 mm focal lens in a 4f-imaging configuration with magnification one-to-one.

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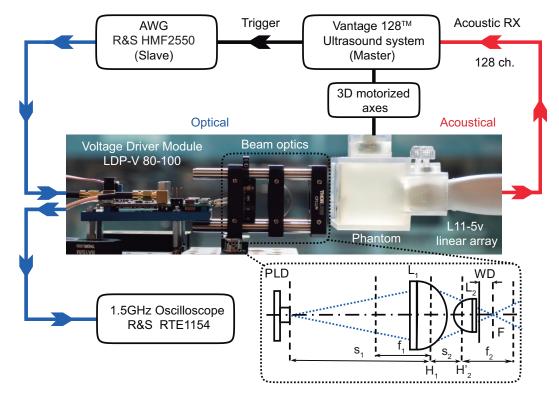


Figure 1: Schematic diagram and main building blocks of the PAM system. Blue arrows refer to the signals of the optical part, starting from the arbitrary waveform generator to the driver and oscilloscope, while red lines represent the received acoustic signals from the ultrasound probe to the Vantage system, which acts as the master and controls trigger, emitted and received signals, as well as the mechanical rastering of the sample. A detailed beam optic diagram is included describing the PLD optical configuration for focusing the laser beam at the focusing plane (F).

The beam spot size given by optical means can then be com-194
pared to the beam spot size measured from the photoacoustic195
images, applying in the Edge Spread Function (ESF) method,196
as a way of cross-checking and validate both imaging measure-197
ments. 198

The beam power delivered at the focal plane was measured₁₉₉ 172 with a calibrated integrating sphere (AvaSphere-30) into a 6-200 173 mm diameter aperture port, connected by a fibre optical ca-201 174 ble (FC-UVIR600-1-ME) to a Czerny-Turner monochromator202 175 spectrometer (AvaSpec-ULS2048XL-EVO) with 1.5 nm spec-203 176 tral resolution, being all these elements from Avantes, Nether-204 177 lands. This measurement was then used in the simulation to205 178 calibrate the power distribution image at the same focal plane,₂₀₆ 179 so that the power delivered into a delimited spot area was es-2017 180 timated more accurately. The PLD emission wavelength and₂₀₈ 181 its bandwidth were also measured from the acquired laser spec-209 182 trum. 183 210

184 2.2. Ultrasound detection and beamforming

As illustrated in Fig. 1, the system uses a transmission mode213 185 configuration where the incident light and the US reception are214 186 located at opposite sides of the sample. The ultrasound acquisi-215 187 tion system is a Vantage 256TM (Verasonics, USA) connected to₂₁₆ 188 a 128-element linear US probe (L11-5v, Verasonics, USA). The217 189 Vantage system generates the TTL trigger signal that synchro-218 190 nizes the arbitrary waveform generator that sends the electrical219 191 pulses to the Voltage Driver Module and PLD. Acoustic sig-220 192 nals are collected across all 128 elements simultaneously at a221 193

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PRF of 2 kHz and averaged 256 for the gelatin phantom experiments and 512 for ex vivo experiments. The ultrasound probe is acoustic-impedance matched to the phantom using coupling gel. Gelatin-based phantoms were produced inside a custommade plastic container using 6% m/V of gelatin 200-220 bloom, adding 0.1% m/V of formaldehyde to increase long-term stability [35]. Hollow polyethylene tubes (0.85 mm out-diameter, 0.42 mm in-diameter) filled with India ink were inserted close to the surface of the gelatin to simulate blood vessels. The phantom container was attached to a 3D scanning motor for positioning and raster-scanning of the sample in a two-dimensional plane perpendicular to the laser beam at its focusing plane.

RF-signals corresponding to each of the channels at every scanned point were registered. Data is later processed in a MATLAB (Mathworks, USA) environment in order to generate maximum intensity projection (MIP) images. Three different beamforming strategies were followed to illustrate and quantify the advantages of the dynamic beamforming. First, a no-beamforming approach in which, for every scanning point, signals are directly summed up without taking into account the delay between the ultrasound wave and the position of each element of the array, a behaviour analogous to what a singleelement plane transducer would present. Second, a static beamforming strategy where all 128 signals are combined in order to have a fixed focusing position in reception for every scanning point, which imitates a single-element focused transducer placed at a fixed position. Finally, we evaluate the performance of a DAS beamforming strategy, where the focusing is dynamically repositioned at every measured point to match the location273
 of the laser excitation. For a given scan position, the output sig-274
 nal using the DAS algorithm reads

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$$y_{DAS}(t) = \sum_{i=1}^{N} y_i(t - \Delta_i)$$
 (1)

where N = 128 is the number of elements of the ultrasound probe, $y_i(t - \Delta_i)$ is the signal received by the *i*-th channel of the array considering its corresponding delay Δ_i , which is obtained as the three-dimensional distance between the position of the laser focus within the focusing plane F, and the position of the *i*-th element of the array, assuming a speed of sound c = 1540 m/s.

233 3. Results

234 3.1. Laser beam focus characterization

The laser beam energy distribution delivered at the focal²⁷⁸ 235 plane was first obtained by ray-tracing simulation of the optical279 236 configuration (Fig. 1). The simulation was implemented con-280 237 sidering the total power emission from the PLD stack source, as281 238 an array of single laser diode emitters according to the manufac-282 239 turer geometrical and optical specifications; followed by the op-283 240 tics set, with their specific aspheric lens geometries, NIR anti-284 241 reflection coatings and corresponding mount apertures. Fig-285 242 ure 2 (a) shows the simulation output image of the laser beam286 243 pattern within a $1 \times 1 \text{ mm}^2$ area at the focusing plane position,²⁸⁷ 244 which corresponds to a working distance of 2.3 mm and diver-288 245 gence of around 22° and 45° for horizontal and vertical planes,289 246 respectively. This simulation allowed us to make a good es-290 247 timation of the energy delivered into any region of the beam291 248 focusing plane, after performing an energy calibration in order292 249 to get the fluence map of the simulated image (in mJ/cm² units).²⁹³ 250 For that purpose, a measurement of the total power was per-294 251 formed using the spectrometer and integrating sphere, where its295 252 sample port is just placed at the beam focusing plane of the op-296 253 tics setup. A total power of 300.5 W was measured over the 254 6 mm diameter sample port, and then applied to the same aper-297 255 ture area in the simulated beam power distribution, yielding a₂₉₈ 256 total energy of 30.05 μ J in this area for the laser pulse width₂₉₉ 257 $\tau_p = 100$ ns. The power measurement was eventually per-300 258 formed in the spectrometer by averaging 1000 energy pulses₃₀₁ 259 acquired for a 10 ms time integration window per pulse, and₃₀₂ 260 after integrating the full spectrum, with measured central wave-303 261 length and bandwidth of 907±7 nm, in agreement with the laser₃₀₄ 262 specifications. 263 305

As a result, the laser pulse energy delivered at the focusing₃₀₆ 264 plane could be more accurately estimated from the calibrated307 265 fluence map shown in Fig. 2(a), being 21.7 μ J for a 1 × 1 mm²₃₀₈ 266 fluence map image size and 10.7 μ J for the laser rectangular₃₀₉ 267 spot area $200 \times 119 \ \mu m^2$ (overlaid in the fluence map image₃₁₀ 268 with one pixel size error of 4.54 μ m), as it was measured by₃₁₁ 269 photoacoustic means using the ESF presented in the follow-312 270 ing section. A PLD peak emission power of 510 W was also313 271 measured for several optical configurations with the integrating₃₁₄ 272

sphere, which approximately match to maximum forward current given by the PLD driver at around 45 A. This means laser power transport efficiencies of 68% for the setup optics into the focusing plane, and a 54% for the power delivered to the beam spot area.

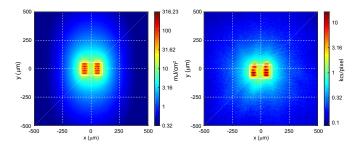


Figure 2: Laser energy distribution at its focusing plane. (a) Ray-tracing simulation. (b) Experimental measurement with a CCD camera and a 4f-imaging lens.

The simulated beam pattern image is also compared to the experimental image of the beam focus pattern shown in Fig. 2 (b) which was taken with a 60 mm focal lens and a CCD NIR camera at 4*f*-imaging distance from the PLD focusing plane with 1:1 magnification. The acquired image size is 224×224 pixels for the camera set to 1×1 mm² aperture and having 4.54 μ m pixel size. Due to the high sensitivity of the CCD detector a set of neutral density filters were applied to attenuate light by a factor 10^{-6} . Synchronization for triggering the camera, at its minimum 30 μ s exposure time, was directly performed from the pulse train signal from function generator driving also the PLD driver. Note also that the beam focus image is not calibrated and thus shown in counts per pixel units. In this case it was not possible to perform an experimental energy calibration, since the power arriving to the camera detector after the imaging lens does not conserve proportionality with respect to the power at the object focusing plane. This is mainly due to some spatial filtering made by the imaging lens over the highly divergent beam exiting after the focusing plane.

3.2. Lateral resolution: Edge Spread Function

The lateral resolution of the PAM system, defined by the laser beam spot size, was characterized from both optical and acoustical experimental measurements, as shown in Fig. 3. First, data from the optical characterization of the laser beam focus shown in Fig. 2 (b), was extracted and averaged for every horizontal and vertical line along the x-y plane within the rectangular spot area to obtain one single line for each orientation, as shown in Figs. 3 (a, b). The beam spot size of this complex profile is defined by taking the full-width at half-maximum (FWHM) from a Gaussian fit (solid blue lines), as a first order approximation of the more complex power profile. The resulting measurement of the PLD optical beam excitation spot was $222 \times 127 \ \mu m^2$. Similar results were obtained for the simulated data, shown in Fig. 2 (a), with an estimated spot size of $217 \times 112 \ \mu m^2$. For the acoustical characterization, we made use of the edge spread function estimation considering the different horizontal and vertical properties of the PLD beam profile.

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A highly absorbing 180-µm black vinyl strip was embedded₃₄₈ 315 in the phantom at around 1 mm beneath its surface and partially₃₄₉ 316 imaged, as shown in the insets of Figs. 3(c, d). The scanned₃₅₀ 317 area was $2 \times 2 \text{ mm}^2$ for both horizontal and vertical orienta-351 318 tions, with step increments of 10 μ m, and the detected signals₃₅₂ 319 were averaged 256 times. The laser diode driver was set to half353 320 of its maximum range (at 50V), which means that an optical₃₅₄ 321 power of 150 W was eventually delivered to the focal excitation355 322 region, as obtained from linear calibration of the previous laser356 323 power measurement. The measured photoacoustic profile lines357 324 are shown as solid black lines in Figs. 3(c, d) for the horizontal₃₅₈ 325 and vertical orientations, respectively. A representative trajec-359 326 tory of the measured profiles is shown in the insets by red dotted₃₆₀ 327 lines. All measured profiles within the imaged area were aver-361 328 aged to obtain a single ESF. Their respective spatial derivatives,362 329 i.e., linear spread functions (LSF) were fitted using a Gaussian363 330 function. The lateral resolution extracted from the FWHM of₃₆₄ 331 the fitted curve was 199.8 μ m and 118.9 μ m for the horizontal₃₆₅ 332 and vertical orientations, respectively. The laser pulse energy₃₆₆ 333 within the lateral resolution spot area would be of 5.3 μ J, which₃₆₇ 334 means an average fluence of 222 mJ/cm², as determined from₃₆₈ 335 previous laser energy estimations. 369 336

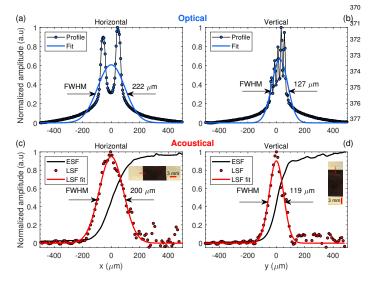


Figure 3: Lateral resolution evaluation. (a) Horizontal and (b) vertical optical *x-y* experimental profiles of the laser beam at its focus and beam spot size from Gaussian fitting at FWHM. (c) Horizontal and (d) vertical ESFs, LSFs and corresponding Gaussian fittings obtained from photoacoustic measurements.

The beam spot sizes measured by optical and acoustical 337 methods show a good agreement between them. This seems 338 to indicate that in the photoacoustic interaction, where the laser 339 energy is converted into a thermoelastic expansion after heating 340 the targeted material, a smoothing of the spikes of the underly-341 ing laser distribution is produced, possibly due to the integra-342 tion of the laser energy density (fluence or intensity) when it is 343 absorbed by the material. 344

345 3.3. Gelatin phantoms 2D imaging

To evaluate the performance of the PAM system and graph-379 ically show the differences between the different beamforming380 strategies we first took 2D large-area images of gelatin phantoms including polyethylene tubes filled with India ink (inner diameter 0.42 mm, outer diameter 0.85 mm). The scanned area was nearly 1 cm² (1.2 cm × 0.8 cm), using step increments of 50 μ m, resulting in images having 39862 pixels. Registered signals were averaged 256 at every point of the image. As previously determined, the laser excitation corresponds to 5.3 μ J pulse energy and 222 mJ/cm² average fluence in the focus spot area. Figure 4 (a) illustrates a photograph of the phantom and highlights the imaged area.

Following the acquisition of the RF-signals for all 128 channels of the ultrasound probe at every point of the image, data was processed and summed-up differently according to the three proposed beamforming strategies. First, for the no beamforming strategy, data from every channel were directly summed up (see Fig. 4 (b)). Then, for the static beamforming strategy, time delays for every channel were calculated in order to point the focus in reception at the point (2,0) mm, and time signals were time-shifted accordingly (Fig. 4 (c)). Finally, for the dynamic beamforming strategy, the focal law in reception was set to match the location of the imaged pixel using the DAS algorithm, (Fig. 4 (d)). Once the beamforming strategy was applied, the photoacoustic image was obtained by considering the MIP, plotting the result in logarithmic scale. These results clearly indicate that if a large-area image is desired, neither the no-beamforming nor the static beamforming strategies can provide sharp images, failing to achieve enough and uniform contrast for the whole scanned area. On the other hand, when applying a dynamic beamforming strategy, the SNR along the imaged area is greatly homogenized and increased around 20 dB, enhancing the overall contrast.

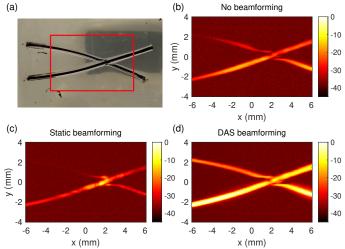


Figure 4: **2D** photoacoustic images using gelatin phantoms. (a) Photograph of the surface of the phantom including polyethylene tubes at its surface. The red rectangle represents the scanned area. 2D photoacoustic images of the gelatin phantoms using a single set of experimental data, applying (b) nobeamforming, (c) static beamforming aimed at the crossing point of the PE tubes and (d) dynamic beamforming aiming the focusing point at the focal spot of the laser for every scanned point.

An additional photoacoustic experiment was performed to better quantify the differences between the three beamforming

strategies. A single polyethylene tube filled with India Ink was407 381 located inside a gelatin phantom nearly at its surface in a quasi-408 382 horizontal position, i.e., aligned to the x-axis. Note that since 409 383 the ultrasound array is a 1D probe, the dynamic focusing strat-384 egy is only feasible along the x-axis and z-axis. The scanned₄₁₀ 385 area for this experiment was 0.6 cm² (2 cm \times 0.3 cm), using 386 step increments of 50 μ m, for a total of 24862 pixels (401 × 62). 387 412 As before, 256 signals were averaged at every point of the im-388 age with 5.3 μ J of laser pulse energy and 222 mJ/cm² of fluence⁴¹³ 389 per point. A photograph of the sample is shown in Fig. 5 (a).⁴¹⁴ 390 Photoacoustic images extracted from MIP of the processed time 415 391 series signals are shown in Figs. 5(b, c, d) for all three beam-392 forming strategies. Finally, Fig. 5 (e) represents the comparison 393 of SNR along the horizontal x-axis at the y point corresponding $\frac{418}{419}$ 394 to the centre of the tube. 420

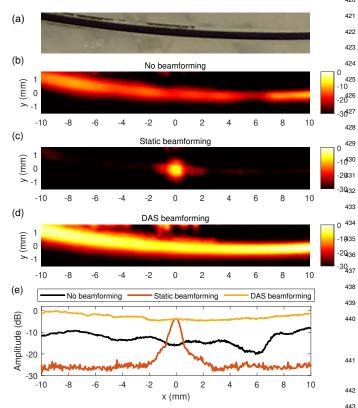


Figure 5: SNR comparison between beamforming strategies. (a) Photograph444 of the gelatin phantom featuring an India Ink filled PE tube. 2D photoacoustic445 images using (b) no beamforming, (c) static beamforming, and (d) dynamic₄₄₆ beamforming. (e) SNR comparison along the x-axis at the centre of the tube. 447

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Results shown in Fig. 5 (e) represent a clear picture of the dif-449 ference in performance between the three beamforming strate-450 397 gies. First, for the sake of consistency, note that the static451 398 and dynamic beamforming strategies have the same SNR when452 399 evaluated at the focus of the former. The dynamic beamforming453 400 strategy offers a quite homogeneous SNR along the polyethy-454 401 lene tube for almost 2 cm, with variations below 3 dB. More-455 402 over, this small variations are influenced by small differences456 403 in the depth along the z-axis of the tube, considering its size457 404 with respect to the depth of field of the laser at its focus (ap-458 405 proximately 1 mm). When comparing these results with a no-459 406

beamforming strategy, there exists an overall reduction of 10 to 20 dB in SNR. If compared to the static beamforming strategy, the SNR increase nearly reaches 30 dB for out-of-focus regions.

3.4. Rabbit ear 2D imaging

To evaluate the performance of the proposed PAM system in a more realistic environment, ex vivo images of a rabbit's ear were taken. Rabbit ears were provided by the Instituto de Ciencia Animal (ICTA) of the Universitat Politècnica de València (accredited animal care facility ES462500001091) in agreement with European legislation. Two strategies (nobeamforming and dynamic beamforming) were considered for the same set of experimental data. The scanned area was 0.72 cm^2 (1.2 cm × 0.6 cm), using step increments of 50 μ m, resulting in images having 29282 pixels. Since the optical absorption coefficient for blood at the working wavelength is around 10 cm⁻¹, more than one order of magnitude lower than for India ink, which is around 200-400 cm^{-1} [1, 35], the number of averages when imaging the rabbit ear was increased to 512 laser pulse shots at the same excitation energy of 5.3 μ J and 222 mJ/cm² fluence per image point. A photograph of the rabbit's ear including a rectangle indicating the scanned area and the corresponding photoacoustic images using the two beamforming techniques are shown in Fig. 6. The obtained results highlight the relevance of the dynamic beamforming, shown in Fig. 6(c), not only to homogenize the SNR along the scanned area, but most importantly, in this case, to discern different elements of the rabbit ear's vasculature, which are hardly visible for the no-beamforming case shown in Fig. 6 (b). Beamformed image highlights the presence of several capillaries of different size and allows to see details that are even hardly visible by a direct visualization of the photograph shown in Fig. 6 (a). Note that the SNR improvement obtained in this experiment is consistent with the results presented previously for the phantom. where the improvement was between 10 and 20 dB.

4. Conclusions

In this work, we have compared different beamforming strategies in terms of signal-to-noise ratio with an array-based photoacoustic microscopy system. We demonstrate that DAS beamforming allows to greatly extend the imaging area of photoacoustic images. In addition, the signal-to-noise ratio is increased and spatially homogenized along the imaging plane. In particular, we utilized a low-cost PLD controlled by a voltage driver module and combined with an optics scheme composed of two plano-convex aspheric lenses as the laser excitation, achieving a rectangular focal spot of $200 \times 119 \ \mu m^2$ and a pulse energy ranging from 3.2 to 10.7 μ J, for a fluence within the laser focal spot between 134 and 450 mJ/cm². The lateral resolution of the system was characterized from both optical and acoustical measurements based on the edge spread function method, obtaining a very good agreement between them. Images of polyethylene tubes filled with India ink embedded in tissue-mimicking phantoms comparing different beamforming techniques demonstrated the benefits of applying dynamic

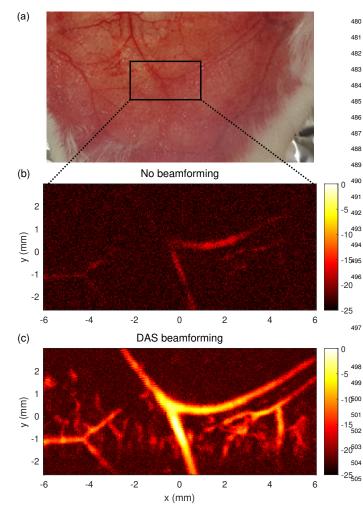


Figure 6: **Ex vivo rabbit ear 2D PAM imaging.** (a) Photograph of the excised₅₀₆ rabbit ear, where the black rectangle indicates the scanned area. PAM images of the rabbit ear vasculature comparing (b) no-beamforming and (c) dynamic beamforming.

beamforming in the imaging plane to form very large areas 460 (around 1 cm² and nearly 40000 pixels) with an improved and 461 homogenized SNR along the whole imaged area, reaching im-462 512 provements up to nearly 30 dB compared to a static focus con-463 513 figuration. Finally, ex vivo large-area images of the microvas-464 -514 culature of the ear of a rabbit were taken, observing the pres-515465 ence of capillaries of different sizes, obtaining similar SNR im-466 provements when applying dynamic beamforming as those us-467 517 ing gelatin phantoms, and therefore validating these results in a_{518}^{11} 468 more realistic environment. 469 519

One of the advantages of DAS beamforming in OR-PAM⁵²⁰₅₂₀ 470 systems is that the ultrasound probe and the imaged sample can 471 be physically coupled, allowing fast scanning during large-area 472 imaging for in vivo applications. Regarding the obtained SNR 473 improvements using DAS beamforming, note that advanced⁵²¹ 474 beamforming algorithms such as DMAS, DS-DMAS, F-DMAS 475 [36–38], sparsity-based beamforming [39], eigen-space based₅₂₂ 476 minimum variance [40], or even sinthetic aperture focusing523 477 techniques [41, 42] could be applied to further enhance SNR₅₂₄ 478 in the present OR-PAM system. 525 479

In addition, large-area scan images are limited by the required scanning times, which ultimately depend on the PRF of the laser, but also on the scanning method and number of averages. Although real-time imaging of large areas might still be difficult to achieve in OR-PAM because imaging speed is ultimately limited by the acoustic wave propagation in soft tissues, imaging large areas within a few minutes is still feasible with the existing technology. In this regard, the imaging speed can be improved dramatically by using higher PRFs combined with fast laser scanning methods such as micro-electro-mechanical systems (MEMS) or galvanometer-based scanning methods. In these configurations, the dynamic beamforming techniques reported in this work can be applied to synchronise the alignment between the optical and acoustical focal spots during large-area scans, improving and homogenizing the signal-to-noise ratio of photoacoustic microscopy images for practical biomedical applications.

Author contributions

Conceptualization, A.C., J.J.G.G, N.J, J.M.B and F.C.; Data curation, A.C., J.J.G.G. A.D; Funding acquisition, F.C. J.M.B; Software, A.C., J.J.G.G, A.D. and N.J.; Writing–original draft preparation, A.C and J.J.G.G.; writing–review and editing, A.C., J.J.G.G, A.D, N.J, J.M.B and F.C.; Supervision, A.C., J.J.G.G, N.J, J.M.B and F.C.; project administration, J.M.B and F.C.; All authors have read, critically reviewed and agreed to the final version of the manuscript.

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