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Additional Information

Stability and accuracy of deterministic project duration forecasting methods in Earned Value Management

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1 Stability and accuracy of deterministic project duration
2 forecasting methods in Earned Value Management

3 **Structured abstract**

4 **Purpose:** Earned Value Management (EVM) is a project monitoring and control technique
5 that enables the forecasting of a project's duration. Many EVM metrics and project duration
6 forecasting methods have been proposed. However, very few studies have compared their
7 accuracy and stability.

8 **Design/methodology/approach:** This paper presents an exhaustive stability and accuracy
9 analysis of 27 deterministic EVM project duration forecasting methods. Stability is measured
10 via Pearson's, Spearman's, and Kendall's correlation coefficients; while accuracy is
11 measured by Mean Squared and Mean Absolute Percentage Errors. These parameters are
12 determined at ten percentile intervals to track a given project's progress across 4,100 artificial
13 project networks with varied topologies.

14 **Findings:** Findings support that stability and accuracy are inversely correlated for most
15 forecasting methods, and also suggest that both significantly worsen as project networks
16 become increasingly parallel. However, the $AT+PD-ES_{min}$ forecasting method stands out as
17 being the most accurate and reliable.

18 **Originality:** Unlike previous research comparing EVM forecasting methods, this one
19 includes all deterministic methods (classical and recent alike) and measures their
20 performance in accordance with several parameters. Activity durations and costs are also
21 modelled akin to those of construction projects.

22 **Practical implications:** Implications of this study will allow construction project managers to
23 resort to the simplest, most accurate and most stable EVM metrics when forecasting project
24 duration. They will also be able to anticipate how the project topology (i.e. the network of

25 activity predecessors) and the stage of project progress can condition their accuracy and
26 stability.

27 **Keywords:** Earned Value Management; construction projects; project duration; deterministic
28 forecasting; metrics stability; time estimates accuracy.

29 **Article classification:** Research article.

30 **Introduction**

31 Earned Value Management (EVM) is a deterministic project monitoring and control
32 technique widely adopted in many industries, including construction (Batselier and
33 Vanhoucke, 2015a). EVM can measure whether a project is behind (or ahead) of schedule
34 and whether it is costing more (or less) than planned. These applications are extremely useful
35 for project managers taking corrective actions to bring the project back on track (Vanhoucke,
36 2010). Another common application of EVM metrics is generating forecasts of when the
37 project will finish and how much it will cost by the time it is completed.

38 EVM has been included in the Project Management Body of Knowledge (PMBOK)
39 Guide since its first edition in 1987. However, EVM has also been adopted by many other US
40 government agencies [e.g. the National Aeronautics and Space Administration (NASA) and
41 the United States Department of Energy]. More recently, EVM has also been standardized in
42 other regions such as Australia (e.g. AS 4817-2003 and AS 4817-2006) and Europe (ISO
43 21508:2018). In parallel with its adoption by governments, practitioners, certification and
44 professional bodies, EVM has also received extensive research attention (Vanhoucke, 2011,
45 2013).

46 Due to its relative simplicity, EVM also allows conveying in simple terms to top
47 management how the project is performing. To do this, it relies on a series of *metrics* whose
48 values can be updated whenever the *actual* activity durations, costs and percentages of

49 completion are measured. These measurements should take place at approximately regular
50 time intervals during project execution and are commonly known as *tracking periods*.

51 The present study will focus on project *duration* methods. These are commonly
52 known in EVM as Estimated time At Completion or just EAC(t). EAC(t) methods have
53 received much less research attention than their cost counterpart (Batselier and Vanhoucke,
54 2015b). Yet, many EVM metrics and EAC(t) expressions have been proposed over the last 20
55 years. Earlier EAC(t) expressions mostly resorted either directly to classical EVM metrics
56 [Planned Value (PV), Actual Cost (AC) and Earned Value (EV)] or their derived indicators
57 [the Schedule Performance Index (SPI) or the Schedule Cost Index (SCI)]. In 2003, though, a
58 fourth metric named Earned Schedule (ES) was proposed by Lipke (2003). Several EAC(t)
59 expressions have used the ES metric since, also in combination with its derived performance
60 indicators [e.g. the SPI(t) or the SCI(t)]. Finally, and much more recently, other EAC(t)
61 expressions have been proposed based on exponential smoothing and further reformulations
62 of the ES metric (e.g. ES(e), ES_{min}, ES_{max}) (Ballesteros-Pérez et al., 2019).

63 Among recent variants of EAC(t) methods, some have not been intrinsically
64 deterministic [e.g. (Acebes *et al.*, 2015; Elshaer, 2013; Nadaf *et al.*, 2019)]. However, this
65 study will focus on *deterministic* methods. Deterministic methods are the most common
66 nowadays in the EVM framework and they are also simpler and easier to use (Vanhoucke,
67 2013). These make deterministic EVM quite appealing to most construction practitioners.

68 Apart from EVM project duration forecasting methods, other more advanced
69 techniques have also been proposed (e.g. fuzzy logic, neural network analysis, Bayesian
70 inference, Monte Carlo simulation, statistical learning and artificial intelligence methods,
71 Kalman filter algorithms, and endless variants of PERT) (Bai *et al.*, 2020; Ballesteros-Pérez,
72 Cerezo-Narváez, *et al.*, 2020). However, most of these techniques are also more computer
73 demanding and/or data-intensive than the EVM deterministic expressions analyzed here.

98 are all numbered on the first column for easier reference in the upcoming sections.

99 Broadly speaking, most of these methods (but not all) resort to one of these three
100 standard EAC(t) formula configurations: PD/PF , $MAX(PD, AT)/PF$ or $AT+(PD-ES_x)/PF$.
101 Where: PD is the project Planned Duration (before it starts); AT is the Actual (current) Time;
102 $MAX(\cdot)$ is the maximum of two variables; ES_x is one of the variants of the Earned Schedule
103 metric (e.g. ES , ED , $ES(e)$, ES_{min} , etc.); and PF is a Performance Factor that can be 1 or
104 another indicator such as SPI , $SPI(t)$, $SPI(t)(e)$, $SPI(t)_{ESmin}$, $SPI(t)_{ESmax}$, SCI , $SCI(t)$, $SCI(t)(e)$,
105 $SCI(t)_{ESmin}$, $SCI(t)_{ESmax}$, even an exponential smoothing factor (e.g. $T_{t,SPI(t)}$, $T_{t,AT}/T_{t,ES}$ or $T_{t,EDI}$).

106 ***Previous research comparing EAC(t) methods' accuracy***

107 The first comparison of EAC(t) project duration methods was performed by
108 Vanhoucke (2010). He compared methods 1-9 from Table 1. In his comparison, method 7
109 was the most accurate but considering Mean Absolute Performance Errors (MAPE) only.

110 Five years later, Batselier and Vanhoucke (2015b) compared the same methods 1-9,
111 but this time with 23 real projects. Again, method 7 turned out to be the most accurate. In the
112 present study we will not use real projects, though. This is because *stability* calculations
113 require multiple realizations of the same project (which can only be obtained by simulation).
114 Then, Batselier and Vanhoucke (2015c) compared methods 7, 15, 16 and some of Eslhaer's
115 (2013) non-deterministic EAC(t) expressions. Again, method 7 was the most accurate.

116 In 2017, Khamooshi and Abdi (2017) compared methods 10-13, 22 and 24 with
117 another 19-real-project dataset. In their analyses, methods 22 and 24 were the top performers.
118 Both methods 22 and 24 were proposed by the authors and resorted to exponential
119 smoothing. In the same year, Batselier and Vanhoucke (2017b) proposed method 20, which
120 was also coincidentally based on exponential smoothing. However, they only compared it
121 against method 9, observing just a marginal accuracy improvement.

122 Also in 2017, de Andrade and Vanhoucke (2017) compared methods 7 and 15 on a
123 14-real-project subset extracted from Batselier and Vanhoucke's (2015b) dataset. Method 7
124 was again the top performer (regarding accuracy as measured by MAPEs only).

125 More recently, Ballesteros-Pérez et al. (2019) compared methods 1-22 and 25. In his
126 study, method 22 was the best but very closely followed by methods 7, 14, 16 and 25. This
127 study, however, omitted methods 23, 24, 25 and 27, and neglected the stability analysis. Also,
128 it only calculated the MAPEs (not the MSEs), nor did it use activity durations and costs
129 similar to those of real construction projects.

130 As can be seen, no previous study has compared all EVM project duration methods,
131 nor used activity durations and cost representations of real construction projects. These
132 aspects justify the current comprehensive comparative analysis. Additionally, our analysis
133 will include measurements of the methods' Mean Squared Errors (MSEs) besides MAPEs
134 (the only error metric previously reported). This is relevant as MSEs allow for the detection
135 of *sporadic* but significant deviations from the project duration estimates. Namely, MSEs, on
136 measuring *quadratic* deviations instead of *absolute*, grow quicker when significant deviations
137 appear and are more difficult to dilute in error averages. MAPEs, on the other hand, tend to
138 *blur* sporadic deviations as long as the method is accurate most of the time.

139 ***Previous research comparing EAC(t) methods' stability***

140 Regarding the stability of EAC(t) methods within the temporal dimension,
141 significantly fewer studies can be found in the literature. Stability of the cost dimension, on
142 the other hand, was defined early on as the time point in the project life-cycle at which the
143 Cost Performance Index (CPI) is already deemed to be accurate and constant (De Koning and
144 Vanhoucke, 2016). Several formative studies referred to a rule of thumb which suggested
145 that, from approximately the 20% stage of project completion onwards, cost estimates do not

146 differ much from final project costs (Sato *et al.*, 2017). However, later studies have
147 consistently denied the existence of such a putative point (Henderson and Zwikael, 2008;
148 Khafri *et al.*, 2018; Kim *et al.*, 2019; Petter *et al.*, 2015).

149 Among those studies that addressed cost stability, a few also included a description of
150 the variability that some EVM *time* indicators experience during project execution. The SPI
151 and the SPI(t) were the commonly preferred indicators [e.g. (Henderson and Zwikael, 2008;
152 De Koning and Vanhoucke, 2016; Ladeeda and Jeevan, 2020; De Marco *et al.*, 2016; Petter
153 *et al.*, 2015)]. In those studies, researchers determined whether these indicators remained
154 within an arbitrary interval (e.g. ± 0.1 or ± 0.2) from a given point until the end of the project
155 execution (Khafri *et al.*, 2018; Petter *et al.*, 2015). Most of them also resorted to real projects,
156 rather than artificial ones which, as stated earlier, remains the only way of assessing multiple
157 potential outcomes of the same project (Kim, 2016; Ladeeda and Jeevan, 2020). However,
158 some of these studies did focus on specific project factors potentially influencing stability:
159 namely project duration and budget, project network topology, the S-curve of the project's
160 baseline, and so forth. Some of their results have been at least partially inconclusive
161 (Henderson and Zwikael, 2008; De Koning and Vanhoucke, 2016), but they did find that
162 project duration and budget do not seem to influence project stability in real projects. They
163 also suggested that the steeper the project expenditure S-curve line was in the middle, the
164 more likely the expected stability of the CPI, SPI, and SPI(t) later in the project.

165 We can only find three studies focusing on the time stability of EAC(t) methods. The
166 first was Wauters and Vanhoucke (2015) who compared 12 EAC(t) methods' stability and
167 accuracy. The methods' accuracy was measured with MAPEs, whereas stability was
168 measured with an ad-hoc *Mean Lags* estimator. This *Mean Lags* estimator was similar to the
169 MAPE in the sense that it measured the differences in the EAC(t) estimates from one tracking
170 period to the next in absolute percentage values. The authors claimed that their estimator had

171 the advantage of being independent of each method's accuracy. That is indeed true, but that is
172 not the only way of detaching stability from accuracy. In this regard, an EAC(t) method that
173 consistently claimed that project duration equals the Planned Duration (PD) would be
174 perfectly stable, but utterly useless for project managers. Additionally, it seems more
175 advisable comparing the possible EAC(t) estimates at one tracking period, not with the next
176 tracking period's, but with the actual project durations, that is, with the final set of possible
177 Real Duration (RD) values. We are of course assuming a probabilistic approach here as, by
178 definition, it is the only way of assessing the stability of multiple possible project realizations.
179 This is, as mentioned earlier, the very reason why this study cannot resort to a real projects
180 dataset to perform the EAC(t) methods stability analysis.

181 The other two studies which compared some EAC(t) methods' stability (but this time
182 not their accuracy) were Batselier and Vanhoucke's (2017a) and de Andrade et al.'s (2019).
183 They proposed a Regularity Index (RI) which measured deviations in the project value
184 accrued during execution. Namely, this index measured the Planned Value (PV) curve's
185 degree of closeness to a perfectly linear curve. However, this RI indicator conceives the
186 evolution of the PV as linear, when indeed it is usually closer to an S-shaped curve in most
187 construction projects (Hürol *et al.*, 2020). This is because, in most construction projects, more
188 activities are being performed (and therefore generating associated costs) in the middle stages
189 of the project as compared to the initial and final stages (Narbaev and De Marco, 2017). Also,
190 this RI indicator conflates accuracy with stability.

191 Hence, due to the limitations highlighted in the three previous studies mostly
192 regarding their ad hoc stability indicators, our study will resort to parametric order correlation
193 coefficients (e.g. Spearman's and Kendall's) for measuring EAC(t) methods' stability. These
194 order correlation coefficients are also more statistically robust, and their interpretation easier.

195 To serve as a summary of the works reviewed in this section, Table II is included.

196 This table summarizes the scope and limitations of previous studies, comparing some EVM
197 project duration forecasting methods.

198 < Insert Table II here >

199 **Research methods**

200 *Artificial project networks dataset*

201 In our study, we use an artificial projects dataset which boasts 4,100 activity-on-node
202 networks with varied topologies (different configurations of activities' predecessors). Each
203 project has 30 activities plus two dummy activities (zero cost and duration) indicating the
204 start and end of each project. This dataset was generated with RanGen2, a robust random
205 network generator validated in previous research (Demeulemeester *et al.*, 2003; Vanhoucke
206 *et al.*, 2008). This same dataset has been used by other studies on EVM (e.g. (Ballesteros-
207 Pérez, Sanz-Ablanedo, *et al.*, 2019; Batselier and Vanhoucke, 2015c; Colin and Vanhoucke,
208 2014; 2010, 2011)). The complete project dataset is currently curated by the Ghent University
209 Operations Research & Scheduling Research Group. All project files can be downloaded at:
210 <https://www.projectmanagement.ugent.be/research/data> (MT set). For each project, a file
211 containing all activities' predecessors information can be found. Files also contain
212 information on resource allocation that will not be used in this study.

213 More precisely, these 4,100 projects were generated by setting staggered values of the
214 Serial-Parallel (SP) indicator. The SP indicator measures how close a project is to a serial
215 network (SP=1) or a parallel network (SP=0). The SP is calculated as:

$$216 \quad SP = \frac{q-1}{n-1} \quad (1)$$

217 Where q is the number of activities in the path with the highest number of activities
218 (which is not necessarily the longest in duration), and n is the total number of (non-dummy)
219 activities in the network (30 in our case for all projects).

220 This way our project dataset contains networks with $SP=\{7\%, 17\%, 28\%, 38\%, 48\%,$
221 $59\%, 69\%, 79\%, 90\%\}$. More rounded values (e.g. $SP=10\%, 20\%, 30\%...$) were not possible
222 due to the fixed amount of activities within each network (30). Also, we did not consider
223 perfectly serial ($SP=100\%$) or parallel ($SP=0$) projects, as those configurations are not
224 representative of real construction projects [see some average SP values of building, civil
225 engineering, industrial and services projects in Ballesteros-Pérez et al. (2020), Table 9].

226 Finally, while the 4,100 projects were generated by increasing values of the SP
227 indicator, other topological indicators were also calculated. They can be found in the Excel
228 file of the *Supplemental material* for each network. These other indicators are the Coefficient
229 of Network Complexity (CNC), the Order Strength (OS), the Activity Distribution (*AD*), the
230 Length of Arcs (*LA*), and the Topological Float (*TF*). Further details on the meaning and
231 calculations of these topological indicators can be found in Vanhoucke (2010). However, we
232 will not refer to them anymore as our analyses did not find any significant stability nor
233 accuracy correlation with any of them.

234 *Activity durations and costs*

235 Despite previous studies having assumed different distributions for modeling activity
236 durations and costs, we use correlated Lognormal distributions whose variability resembles
237 that of real construction projects. Several studies support, in fact, that the distribution of
238 activity durations and costs closely resembles Lognormal distributions in real construction
239 projects (Colin and Vanhoucke, 2016; Trietsch *et al.*, 2012; Vanhoucke, 2015). Furthermore,
240 a recent analysis of construction activities also measured that the activities' duration-cost
241 correlation can vary between 0 (no correlation whatsoever) and 100% (perfect correlation)
242 (Ballesteros-Pérez, Sanz-Ablanedo, *et al.*, 2020).

243 Hence, we generate Lognormally-distributed activity duration and cost values with

244 some partial correlation between both values. Mathematical details on how these durations
 245 and values are generated are included in the *Appendix*.

246 Additionally, when calculating the project schedules, all activities are scheduled to
 247 start as soon as possible (ASAP scheduling). Activity preemption is not allowed.

248 ***Accuracy and stability measurement***

249 For measuring the *accuracy* of the 27 EAC(t) project duration forecasting methods we
 250 calculate the Mean Squared Errors (MSEs) and Mean Absolute Percentage Errors (MAPEs)
 251 at 10% of project progress tracking intervals (respect the Real project Duration RD). Namely,
 252 for each EAC(t) method and tracking interval (AT), we calculate:

$$253 \quad MSE_{AT} = \frac{1}{M} \sum_{m=1}^M \left\{ \frac{1}{K} \sum_{k=1}^K \frac{(RD_{mk} - EAC(t)_{AT})^2}{RD_{mk}} \right\} \quad (2)$$

$$254 \quad MAPE_{AT} = \frac{1}{M} \sum_{m=1}^M \left\{ \frac{1}{K} \sum_{k=1}^K \frac{|RD_{mk} - EAC(t)_{AT}|}{RD_{mk}} \right\} \quad (3)$$

255 Where:

256 M is the total number of projects analyzed ($M=4100$) and $m=1, 2 \dots 4100$.

257 K is the total number of simulation runs per project ($K=100$) with $k=1, 2 \dots 100$.

258 RD_{mk} is project m 's Real Duration in simulation run k .

259 $EAC(t)_{AT}$ is the project duration estimate at tracking period $AT=10\%, 20\% \dots 100\%$ of RD_{mk} .

260 For the sake of simplicity, though, we will not use an extra subscript to refer to each of the 27
 261 EAC(t) forecasting methods.

262 As justified earlier, the MAPE allows us to directly anticipate the order of magnitude
 263 of our errors when we use EAC(t) methods in real contexts. The MSE, on the other hand,
 264 allows detecting occasional, but significant errors of the EAC(t) methods.

265 For measuring the methods' *stability*, we resort to three correlation coefficients:

266 Pearson's linear correlation (R), Spearman's rank correlation (ρ), and Kendall's rank
 267 correlation (τ). The use of Spearman and Kendall's coefficients was justified in the *Literature*
 268 *review* section. Pearson's correlation calculations are only included for comparative purposes.

269 Namely, Pearson's R correlation of the EAC(t) estimates at every tracking period AT
 270 with the final Real project Duration (RD) is calculated as:

$$271 \quad R_{AT} = \frac{1}{M} \sum_{m=1}^M \left\{ \frac{\sum_{k=1}^K (EAC(t)_{AT} - \overline{EAC(t)_{AT}}) (RD_{mk} - \overline{RD_{mk}})}{\sqrt{\sum_{k=1}^K (EAC(t)_{AT} - \overline{EAC(t)_{AT}})^2} \sqrt{\sum_{k=1}^K (RD_{mk} - \overline{RD_{mk}})^2}} \right\} \quad (4)$$

272 Where $\overline{EAC(t)_{AT}}$ represents the average of the EAC(t) estimates at tracking period
 273 AT in the $K=100$ simulation runs; and $\overline{RD_{mk}}$ represents the average of project m 's RD values
 274 in the $K=100$ simulation runs.

275 Pearson's linear correlation coefficient R has the advantage of having a
 276 straightforward interpretation, i.e., the higher R , the more (linearly) proportional RD values
 277 are expected to be respect to the EAC(t) estimates. However, it also has some important
 278 limitations. First, it mixes accuracy and stability. Hence, it is useful as a combined indicator
 279 but misleading for measuring stability only. Second, the relationship between EAC(t) and RD
 280 is expected to be nonlinear, at least for early tracking periods. Third, Pearson's correlation
 281 assumptions (that both variables are normally distributed, linearity and homoscedasticity) do
 282 not seem realistic in our analysis. Hence, we propose using rank correlation coefficients.

283 Spearman's rank correlation coefficient ρ is calculated at every tracking period AT as:

$$284 \quad \rho_{AT} = \frac{1}{M} \sum_{m=1}^M \left\{ 1 - \left(6 \sum_{k=1}^K d_{mk}^2 / K(K^2 - 1) \right) \right\} \quad (5)$$

285 Where d_{mk} is the difference between the ranking (order) values of $EAC(t)_{AT}$ and RD_{mk}
 286 for project m , for the $K=100$ simulation runs and at a particular tracking period AT, that is,

287 $d_{mk} \equiv \text{rank}(EAC(t)_{AT}^k) - \text{rank}(RD_{mk})$ for $k=1,2\dots K$.

288 Spearman's correlation has the advantage of being parametric, thus, capable of
 289 detecting nonlinear relationships among the EAC(t) estimates and the RD values.
 290 Additionally, Spearman's correlation does not carry any assumptions about the distribution of
 291 the data and works very well with ordinal data (as in our analysis). The calculation of ρ is not
 292 computationally demanding either. However, Spearman's ρ is a little more sensitive to errors
 293 and less robust than Kendall's τ .

294 That is why we also suggest the calculation of Kendall's τ correlation coefficient for
 295 measuring the stability of the EAC(t) estimates at any tracking period AT:

$$296 \quad \tau_{AT} = \frac{1}{M} \sum_{m=1}^M \left\{ \frac{4P_m}{K(K-1)} - 1 \right\} \quad (6)$$

297 Where P_m represents the number of concordant pairs between the EAC(t) estimates
 298 and the RD values for each project m , that is:

$$299 \quad P_m = \sum_{k=1}^{K-1} \sum_{\ell=k+1}^K \mathbf{1} \left\{ \left(EAC(t)_{AT}^\ell - EAC(t)_{AT}^k \right) \left(RD_{mk}^\ell - RD_{mk}^k \right) > 0 \right\} \quad (7)$$

300 Where $\mathbf{1}(\cdot)$ is a binary operator that equals 1 when the condition is fulfilled and 0
 301 when it is not.

302 Kendall's rank correlation coefficient is the more robust of all three correlation
 303 coefficients for measuring the methods' stability. However, its values tend to be lower than
 304 Spearman's and it also is much more computationally expensive. Particularly, the
 305 calculations involved in Kendall's τ are proportional to K^2 , that is, 10.000 assuming $K=100$.
 306 (number of simulation runs per project). However, since we are evaluating 4,100 projects, 27
 307 EAC(t) methods and 10 tracking periods, the number of calculations quickly skyrockets
 308 ($10^4 \cdot 4100 \cdot 27 \cdot 10 = 1.107 \cdot 10^{10}$). This is the reason why only 100 iterations were performed per

309 project. Otherwise, for $K=1000$ simulation runs per project, for example, the computational
310 effort would have required months of computing time for an average computer.

311 Still, as the total number of simulations is circa half a million ($4,100 \text{ projects} \cdot 100$
312 $\text{simulations/project} = 0.41 \cdot 10^6$) this will provide us with enough accuracy up to the second
313 decimal place in our results. The latter as the error of Monte Carlo estimates are proportional
314 to $1/\sqrt{n^\circ \text{ simul. runs}} = 1/\sqrt{M \cdot K} = 1/\sqrt{0.41 \cdot 10^6} = 0.00156 < 1\%$ (Koehler *et al.*, 2009).

315 Finally, for the sake of clarity, Figure 1 includes a graphical description of both
316 Spearman and Kendall's correlation coefficients interpretation.

317 **< Insert Figure 1 here >**

318 For the examples shown in Figure 1, Pearson's correlation coefficient would have
319 turned out low values. This is because this coefficient measures relative numerical deviations
320 between the EAC(t) estimates and the project's possible Real Duration RD outcomes.

321 However, both Spearman's ρ and Kendall's τ coefficient values depend on relative
322 order differences, not on pairwise numerical differences. Hence, it does not matter whether
323 each pair of (EAC(t), RD) values is numerically close, nor whether their deviations follow a
324 nonlinear relationship. What matters is the degree of coincidence between the relative orders
325 of both sets of values. If there is a good match, then EAC(t) estimates will remain in an
326 approximately constant percentile until the project finishes. This means each EAC(t) estimate
327 will point towards the correct RD value from that tracking period onwards. This calculation
328 becomes much more accurate of course, as we count on more data points. That is why we
329 used $K=100$ (iterations) points per project.

330 **Results**

331 Once the artificial projects dataset, the simulation framework and the analysis

332 variables have all been described, Figure 2 and 3 present the 27 EAC(t) project duration
333 forecasting methods' stability and accuracy results for the 4,100 artificial projects. As
334 justified earlier, the methods' stability is represented by three correlation coefficients
335 (Pearson's R , but mostly Spearman's ρ and Kendall's τ) at the top of both Figures 2 and 3.
336 The methods' accuracy, on the other hand, is measured by MSEs and MAPEs both at the
337 bottom left and center of Figures 2 and 3, respectively. The difference between Figures 2 and
338 3 lays in the performance results of each sub-table being classified by tracking period AT
339 (Figure 2) or by the value of the Serial-Parallel indicator SP (Figure 3). A performance
340 summary table is also included at the bottom right corner of Figures 2 and 3.

341 **< Insert Figure 2 here >**

342 **< Insert Figure 3 here >**

343 Interpretations of these two tables are rich but highly varied. We will focus on the
344 most relevant only. Further details presented by projects can be found as *Supplemental*
345 *material*.

346 ***EAC(t) methods stability***

347 Comparatively speaking, the average results of the three correlation coefficients (see
348 summary tables at the bottom right corner of Figures 2 and 3) are not that different. However,
349 Kendall's τ correlation values are significantly lower and produce slightly different results.

350 As expected, the closer the tracking period is to the end of the project in Figure 2 (AT
351 values closer to 100% of RD), the higher the stability and accuracy of all EAC(t) methods.
352 This agrees with almost all existing research on both project duration and cost forecasting
353 (Henderson and Zwikael, 2008; De Marco *et al.*, 2016; Warburton *et al.*, 2017). It is worth
354 noticing, though, that AT=100%RD does not represent a finished project but a project that
355 has just less than one day left to finish. Otherwise, stability and accuracy results would have

356 been perfectly stable and accurate at AT=100%RD for most methods.

357 Analogously, but now in Figure 3, the higher the Serial-Parallel indicator (meaning
358 more serial networks), the more stable and accurate all methods become. This echoes the
359 results of Vanhoucke (2010) and Ladeeda and Jeevan (2020). Particularly, R and ρ values are
360 very high for projects with SP>80%. Conversely, for parallel projects with SP<30%, all
361 EAC(t) methods are quite unstable. In fact, among Kendall's τ results, we can even find some
362 negative correlation values. This means EAC(t) methods produced estimates which are
363 reversed in order with the actual RD values. This can only be fully appreciated, though, in the
364 project-by-project results in the *Supplemental material*. Therein, it can be observed how for
365 projects with low SP values, almost all EAC(t) methods have negative correlation values
366 during the early stages of project execution (AT<30%RD). This renders all EAC(t) methods
367 useless at the early stages of a project when the project network is close to parallel. Thus,
368 EAC(t) methods may still be accurate, but lower EAC(t) estimates will point towards longer
369 RD values, whereas higher EAC(t) estimates will end up in shorter project durations.

370 Regarding projects with SP values between 20% and 80%, we can find moderate
371 correlation coefficients in most cases (R , ρ and τ values between 0.40 and 0.80). But it must
372 be borne in mind that these are *average* values for all tracking periods. That is, if a
373 correlation coefficient is, for example, 0.50, this means that it will probably have been close
374 to 0 at early tracking periods, but surely above 0.80 in later stages. Hence, for projects with
375 moderate SP values, most EAC(t) methods are sufficiently stable, but only once half of the
376 project execution has been exceeded. This is also in agreement with previous studies [e.g. (de
377 Andrade *et al.*, 2019; Batselier and Vanhoucke, 2017a; Wauters and Vanhoucke, 2015)] and
378 can be better appreciated in the AT>50%RD columns presented within the three tables at the
379 top of Figure 2.

380 ***EAC(t) methods accuracy***

381 Regarding EAC(t) methods' accuracy (tables at the bottom half of Figures 2 and 3),
382 we can find a similar pattern for both the MSEs and the MAPEs. Particularly, it is only from
383 the middle of the project execution onwards ($AT > 50\%RD$ in Figure 2) that the errors are
384 relatively small ($MSEs < 1$ and $MAPEs < 10\%$) for most EAC(t) methods. This agrees with the
385 findings of Ballesteros-Pérez et al. (2019) who analyzed some EAC(t) methods using
386 MAPEs.

387 When it comes to the influence of the network topology in Figure 3, most EAC(t)
388 methods perform sufficiently well ($MAPEs < 10\%$) for projects with $SP > 50\%$ (rather serial
389 projects). The same happens with MSEs but only for projects whose $SP > 60\%$. This means
390 that, halfway through the project execution, we can still find some sporadic but relevant
391 estimation errors in most EAC(t) methods.

392 On the other side of the spectrum, Figure 2 shows that most EAC(t) methods seem to
393 be very inaccurate during the first third of the project execution ($AT < 30\%RD$), even until
394 much later in projects with $SP < 30\%$. This issue had not been identified within the extant
395 literature on EVM, however, the results clearly indicate that, at this execution stage, $MAPEs$
396 $\gg 10\%$ and $MSEs$ are usually above unity.

397 ***Top-performing EAC(t) methods***

398 In the two tables at the bottom right corner of Figures 2 and 3, we can find a summary
399 of which methods perform well (*) or excel (**) in both stability and accuracy dimensions.
400 Figure 2 depicts an average assessment considering that there are more possible network
401 combinations of projects in the dataset with intermediate values of the SP indicator (as also
402 happens in real projects). In Figure 2, methods 14 and 22 are the top performers, but methods
403 7, 12, 16, 20 and 25 are also good. It is worth highlighting that almost all of these EAC(t)

404 methods use the configuration $AT+(PD-ES_x)/PF$ with a Performance Factor $PF=1$, that is,
405 one of the simplest mathematical configurations. Similar findings had also been reported by
406 Vanhoucke (2010) and Ballesteros-Pérez et al. (2019), although the authors compared fewer
407 EAC(t) methods.

408 However, when analyzing the summary performance results in Figure 3, we find some
409 unexpected results. When averaged by the SP indicator, most methods that are stable are not
410 accurate, and vice versa. This was earlier suggested by Wauters and Vanhoucke (2015) but
411 could not be validated by Batselier and Vanhoucke (2017a) or de Andrade et al. (2019).
412 However, there is one method that is sufficiently stable and highly accurate (method 22). This
413 method uses the configuration $AT+PD-ES_{min}$, where ES_{min} is the Earned Schedule calculated
414 on the most delayed path during the project execution. Method 22 limits the quadratic errors
415 very early ($AT>40\%RD$) compared to other methods, and from that point onwards we can
416 also expect project duration estimates to differ $<10\%$ from the final Real Duration RD.

417 Finally, it is worth noticing that among methods 22 to 27, there are several which are
418 very stable and others which are very accurate. Since these six methods are quite similar to
419 each other (they use variants of the same metrics ES_{min} and ES_{max} with different Performance
420 Factors), future efforts might look for superior combinations of these metrics. This is left for
421 future research, however, as it is not the intention of this paper to propose new EAC(t)
422 methods.

423 **Discussion**

424 Results have shown that in parallel projects ($SP<25\%$), most EAC(t) methods are very
425 inaccurate and unstable ($MSEs>1$, $MAPEs>15\%$ and correlation coefficients $<40\%$). The
426 opposite happens to serial projects ($SP>60\%$) in which most EAC(t) methods are quite
427 accurate and stable ($MSEs<0.5$, $MAPEs<10\%$ and correlation coefficients $>70\%$). In projects

428 with intermediate topologies ($25\% < SP < 60\%$), we can expect most EAC(t) methods to
429 become sufficiently accurate and stable too, but only approximately from the middle of the
430 project execution onwards.

431 A pertinent question is, how can real construction projects benefit from these
432 findings? Inevitably, when a project manager observes that the duration forecast anticipates a
433 project duration significantly longer than that originally envisaged, he or she may need to
434 take action to bring the project back on track. The project manager will then either have to
435 allocate more resources to make the existing project(s) more efficient and/or make the
436 contractors work overtime. However, the specific nature of the systemic project changes
437 triggered by a likely late completion date falls beyond the remit of this work. However, a
438 construction manager might ask ‘which are the serial-parallel (SP) values of real construction
439 projects so that we can select the best project duration forecasting method?’

440 In this regard, serial projects tend to perform the most relevant activities one after the
441 other. Highway projects, pipelines, train tracks, and renewable energy projects are some
442 examples of projects with high SP values (Ballesteros-Pérez, Sanz-Ablanedo, *et al.*, 2020).
443 However, when they have enough resources, these projects’ activities can also be partially
444 executed in parallel. Examples of parallel projects with low SP values are usually those that
445 involve several but simple and homogeneous construction units. Examples are residential
446 condominiums, quarry earthworks, off-site prefabrication, etc. (Ballesteros-Pérez, Sanz-
447 Ablanedo, *et al.*, 2020). In between, we can find most construction projects whose schedules
448 boast a mixture of series and parallel paths. Among them, we have most buildings, industrial
449 facilities, water treatment plants, etc.

450 Hence, when choosing a project duration forecasting method, the project manager will
451 need to consider the project seriality and/or the number of resources he/she counts on to
452 perform the project. If many parallel paths or lines of work are expected to be active

453 simultaneously, most EAC(t) methods will provide very inaccurate and unstable estimates, at
454 least until the end of the project is near. But probably by then, the project might be very
455 difficult to bring back on track if it was delayed and/or was too expensive. For these types of
456 projects, other suitable project control and duration forecasting alternatives would be
457 Schedule Risk Analysis (SRA) or Stochastic Network Analysis (SNA) (Ballesteros-Pérez,
458 Cerezo-Narváez, *et al.*, 2019).

459 Conversely, if the project has just a few parallel paths and/or few resource teams,
460 earned value management EAC(t) methods constitute a simpler yet accurate and stable
461 alternative for forecasting the project duration. For most construction projects with
462 $30\% < SP < 100\%$, the EAC(t) methods described here will also be a good alternative.
463 However, apart from method 22 (which becomes reliable from 40% of the project execution
464 onwards), the others might need to wait until 50-60% of the project has been executed. Many
465 project managers may still find that this point as too late to take corrective actions
466 (Ballesteros-Pérez, Elamrousy, *et al.*, 2019), and it probably is.

467 **Conclusions**

468 Earned Value Management (EVM) is a common project monitoring and control
469 technique for measuring how a project is performing in both time and cost dimensions. Over
470 the last 20 years, many EVM-based project duration forecasting expressions (named EAC(t))
471 have been proposed. However, their accuracy and stability had not been exhaustively
472 measured. Among the very limited studies comparing EAC(t) methods' accuracy or stability,
473 none has included all recent EAC(t) expressions, most have used *ad hoc* indicators whose
474 results are difficult to generalize, and they did not simulate activities' variability according to
475 real construction projects.

476 This study has performed a comparison of all deterministic EAC(t) project duration

477 forecasting methods found in the literature (27 methods to date). The methods' stability has
478 been measured using three correlation coefficients (namely, Pearson's, Spearman's, and
479 Kendall's), whereas accuracy has been measured with Mean Squared Errors (MSEs) and
480 Mean Absolute Percentage Errors (MAPEs). Additionally, all of these parameters have been
481 evaluated and analyzed at 10% project progress intervals on a project dataset with 4,100
482 artificial networks with varied Serial-Parallel (SP) indicator values.

483 The most relevant results point out that almost all EAC(t) methods produce very
484 inaccurate estimates until at least half of the project is completed. On the contrary, in the last
485 third of the project, most methods are very accurate. Regarding stability, most EAC(t)
486 methods are quite unstable in the early third of the project execution. However, in the last
487 third, all EAC(t) methods become quite stable.

488 Regarding project topology, the results support that stability and accuracy are
489 inversely correlated for most EAC(t) methods, and that both significantly worsen as project
490 networks become more parallel (mostly for projects with $SP < 30\%$).

491 Among the top-performing EAC(t) methods, method 22: $AT+PD-ES_{min}$ is quite stable
492 and highly accurate, even from the early stages of project progress. It also shows promise for
493 further enhancing its accuracy and stability by combining it with other similar methods that
494 use the ES_{min} and ES_{max} metrics. This is expected to be addressed in future research.

495 A comparison of current EVM project *cost* forecasting methods is expected to be
496 addressed in future research. This should be relatively straightforward once all cost-related
497 performance indicators have been parametrized and included within the calculation
498 framework developed for this paper. A performance comparison of deterministic vs non-
499 deterministic project forecasting methods, incorporating both time and cost dimensions, will
500 also be developed. However, this will involve departing from the EVM framework and

501 implementing alternative calculation approaches (e.g. multivariate regression, statistical
502 learning, fuzzy logic, etc.)

503 Limitations of this study are mostly related to the size of the projects in the dataset
504 and the number of simulations performed in each project. Regarding the project size, all
505 networks had 30 (non-dummy) activities. Regarding the number of simulations, only 100
506 simulation runs per project were performed. The size and number of simulations were
507 intentionally restricted to avoid the number of calculations from skyrocketing, especially
508 when it comes to calculating Kendall's rank correlation coefficient. However, considering the
509 analysis encompassed 4,100 different projects, we still expect our results to be sufficiently
510 representative of most real construction projects.

511 **Appendix**

512 This appendix provides detailed explanations on how the activity durations and costs
513 were generated for each of the 4,100 artificial projects. Their activity duration and cost mean
514 values and dispersion values were generated so that they resembled those from real
515 construction project activities. Activity durations and costs were also correlated.

516 Namely, Lognormally-distributed activity durations (d_i) were generated in this study
517 for each activity i by means of these expressions:

$$518 \quad d_i \sim e^{\text{Normal}(\text{mean}=\mu_i, \text{st.dev.}=\sigma_i)} \quad (8)$$

$$519 \quad \mu_i \sim \text{Normal}(\text{mean} = 1, \text{st.dev.} = 0.25) \quad (9)$$

$$520 \quad \sigma_i \sim \mu_i \cdot \text{Uniform}(\text{lower bound} = 0.25, \text{upper bound} = 0.75) \quad (10)$$

521 Where e is Euler's number; $\text{Normal}(\cdot)$ and $\text{Uniform}(\cdot)$ are the Normal and Uniform
522 distributions, respectively; μ_i is the Normal distribution mean calculated according to
523 equation (9); and σ_i is the activity durations standard deviation according to equation (10).
524 The Normal distribution of d_i in equation (8) becomes Lognormal when exponentiated. The

525 Uniform distribution in equation (10) acts as the Coefficient of Variation ($CV_i = \sigma_i/\mu_i$) whose
 526 values are set to resemble those of real construction projects as measured by Ballesteros-
 527 Pérez et al. (2020).

528 Activity costs (c_i) are also randomly generated for each project and activity i , but now
 529 introducing a duration-cost correlation coefficient (δ_i):

$$530 \quad c_i \sim e^{(\mu'_i + \sigma'_i \cdot X_i)} \quad (11)$$

$$531 \quad \mu'_i \sim Normal(\text{mean} = 10, \text{st. dev.} = 1) \quad (12)$$

$$532 \quad \sigma'_i \sim \mu'_i \cdot Uniform(\text{lower bound} = 0.25, \text{upper bound} = 0.75) \quad (13)$$

$$533 \quad X_i \sim \delta_i \cdot \frac{LN(d_i) - \mu_i}{\sigma_i} + \sqrt{1 - \delta_i^2} \cdot Normal(\text{mean} = 0, \text{st. dev.} = 1) \quad (14)$$

$$534 \quad \delta_i \sim Uniform(\text{lower bound} = 0.0, \text{upper bound} = 1.0) \quad (15)$$

535 Where most variables are analogous to previous equations (8) to (10), but now some
 536 of them with an apostrophe (') indicating that they refer to costs instead of durations.

537 X_i refers to an auxiliary correlated Normally-distributed random variable. This variable helps
 538 simplifying the mathematical expressions above and allows generating activity costs which
 539 are correlated with the activity durations. Namely, the value of X_i is partially conditioned by
 540 the d_i value obtained from equation (8), and the rest is randomly generated according to a
 541 standard Normal distribution. Again, the values chosen in equations (13) and (15) are
 542 representative of real construction activities (Ballesteros-Pérez, Sanz-Ablanedo, *et al.*, 2020).

543 Each project calculation involves variables μ_i , μ'_i , σ_i , σ'_i and δ_i being randomly
 544 generated for each activity at the outset. These variables are forced to remain constant when
 545 100 stochastic simulations are performed for each project. Hence, 100 d_i and c_i values are
 546 stochastically generated in these 100 projects simulations while keeping the other variables
 547 constant. Only with this approach is it possible to ensure that each activity duration and cost
 548 keeps the same average, dispersion, and correlation values across simulations.

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Table I. Project Duration forecasting methods EAC(t) (all variables and mathematical details can be found in the *Supplemental material*)

ID	Method	EAC(t)	Mathematical expression	Authors	Brief description
1	EVM	PV1	$EAC(t)_{EVM\ PV1} = PD(1 - (EV - PV)/BAC)$	(Anbari, 2004)	Methods 1-3 adjust the Planned Project Duration (<i>PD</i>) by subtracting a Time Variance factor ($TV = SV/PV_{rate} = (EV - PV) \cdot PD/BAC$) in method 1; or by dividing <i>PD</i> by the Schedule Performance Index (<i>SPI</i>) or the Schedule Critical Index (<i>SCI</i>) in methods 2 and 3, respectively.
2	EVM	PV2	$EAC(t)_{EVM\ PV2} = PD/SPI$		
3	EVM	PV3	$EAC(t)_{EVM\ PV3} = PD/SCI$		
4	EVM	ED1	$EAC(t)_{EVM\ ED1} = MAX(PD, AT) + AT(1 - SPI)$	(Jacob, 2003)	Methods 4 to 6 were originally expressed as a function of a metric named Earned Duration ($ED' = AT \cdot SPI$). <i>ED'</i> has nothing to do with the <i>ED</i> metric from methods 14 and 15. These <i>EAC(t)</i> expressions, though, have been worked out and skip the use of <i>ED'</i> .
5	EVM	ED2	$EAC(t)_{EVM\ ED2} = MAX(PD, AT)/SPI$		
6	EVM	ED3	$EAC(t)_{EVM\ ED3} = MAX(PD, AT)/SCI + AT(1 - (1/CPI))$		
7	EVM	ES1	$EAC(t)_{EVM\ ES1} = AT + PD - ES$	(Lipke, 2003)	Methods 7 to 9 follow the formula $AT + (PD - ES)/PF$, where <i>ES</i> is the Earned Schedule and <i>PF</i> is a Performance Factor. <i>PF</i> equals 1 in method 7; $PF = SPI(t) = ES/AT$ in method 8, or $PF = SCI(t) = SPI(t) \cdot CPI$ in method 9.
8	EVM	ES2	$EAC(t)_{EVM\ ES2} = AT + (PD - ES)/SPI(t)$		
9	EVM	ES3	$EAC(t)_{EVM\ ES3} = AT + (PD - ES)/SCI(t)$		
10	EDM	PV1	$EAC(t)_{EDM\ PV1} = PD(1 - (TED - TPD))/BAC(t)$	(Khamooshi and Golafshani, 2014)	Methods 10 to 15 were proposed under the Earned Duration Management (EDM) framework. In EDM, the activity (planned and actual) costs are replaced by activity (planned and actual) durations. Metric names change, but methods 10-15 are equivalent to 1, 2, 4, 5, 7 and 8, respectively. There are no counterparts of <i>CPI</i> and <i>SCI</i> in EDM, that is why methods 3, 6 and 9 do not have equivalent methods in EDM.
11	EDM	PV2	$EAC(t)_{EDM\ PV2} = PD/EDI$		
12	EDM	ED1	$EAC(t)_{EDM\ ED1} = MAX(PD, AT) + AT(1 - EDI)$		
13	EDM	ED2	$EAC(t)_{EDM\ ED2} = MAX(PD, AT)/EDI$		
14	EDM	ES1	$EAC(t)_{EDM\ ES1} = AT + PD - ED$		
15	EDM	ES2	$EAC(t)_{EDM\ ES2} = AT + (PD - ED)/DPI$		
16	ESM	ESM1	$EAC(t)_{ESM\ ESM1} = AT + PD - ES(e)$	(Lipke, 2011)	Methods 16 to 18 are similar to methods 7 to 9. However, these replace the Earned Schedule (<i>ES</i>) with the effective Earned Schedule (<i>ES(e)</i>). <i>ES(e)</i> represents the fraction of Earned Value (<i>EV</i>) performed according to the original schedule, as measured by the p-factor (Lipke 2004).
17	ESM	ESM2	$EAC(t)_{ESM\ ESM2} = AT + (PD - ES(e))/SPI(t)(e)$		
18	ESM	ESM3	$EAC(t)_{ESM\ ESM3} = AT + (PD - ES(e))/SCI(t)(e)$		
19	XSM	XSM1	$EAC(t)_{XSM\ XSM1} = AT + (PD - ES)/T_{i, SPI(t)}$	(Khamooshi and Abdi, 2017)	Methods 22 to 24 apply exponential smoothing techniques so that they weight not just immediate (current) metrics progress, but also past information to some extent. Namely, methods 19 and 20 are the counterparts of method 7 with different smoothing factors <i>T</i> ; whereas method 21 is the equivalent of method 14.
20	XSM	XSM2	$EAC(t)_{XSM\ XSM2} = AT + (PD - ES)/(T_{i, AT}/T_{i, ES})$	(Batselier and Vanhoucke, 2017)	
21	XSM	XSM3	$EAC(t)_{XSM\ XSM3} = AT + (PD - ES)/T_{i, EDI}$	(Khamooshi and Abdi, 2017)	
22	ES _{min}	ES1	$EAC(t)_{ESmin\ ES1} = AT + PD - ES_{min}$	(Ballesteros-Pérez et al., 2019)	Methods 22 to 24 are the counterparts of methods 7 to 9, respectively. However, these methods replaced the Earned Schedule metric (<i>ES</i>) with the Earned Schedule min metric (<i>ES_{min}</i>). <i>ES_{min}</i> measures the project progress as a function of its most delayed path.
23	ES _{min}	ES2	$EAC(t)_{ESmin\ ES2} = AT + (PD - ES_{min})/SPI(t)_{ESmin}$		
24	ES _{min}	ES3	$EAC(t)_{ESmin\ ES3} = AT + (PD - ES_{min})/SCI(t)_{ESmin}$		
25	ES _{max}	ES1	$EAC(t)_{ESmax\ ES1} = AT + PD - ES_{max}$		Methods 25 to 27 are equivalent to methods 7 to 9, respectively. However, the former replaced the Earned Schedule metric (<i>ES</i>) with the Earned Schedule max metric (<i>ES_{max}</i>) while the latter measure the project progress as a function of its most advanced path.
26	ES _{max}	ES2	$EAC(t)_{ESmax\ ES2} = AT + (PD - ES_{max})/SPI(t)_{ESmax}$		
27	ES _{max}	ES3	$EAC(t)_{ESmax\ ES3} = AT + (PD - ES_{max})/SCI(t)_{ESmax}$		

Table II. Summary of the relevant existing research on deterministic EVM project duration forecasting methods on accuracy and stability

Study (Reference)	Accuracy		Stability Ad-hoc indicator	Project dataset		EAC(t) methods	
	MAPE	MSE		N° simulated projects	N° real projects	Methods compared	Top performers
(Vanhoucke 2010)	✓		-	4100	-	1-9	7
(Batselier and Vanhoucke 2015b)	✓		-	-	23	1-9	7
(Batselier and Vanhoucke 2015c)	✓		-	-	23	7, 15 & 16	7
(Khamooshi and Abdi 2017)		✓*		-	19	10-13, 22 & 24	22 & 24
(Batselier and Vanhoucke 2017b)	✓		-	-	23	9 & 20	9
(de Andrade and Vanhoucke 2017)	✓		-	-	14	7 & 15	7
(Ballesteros-Pérez et al. 2019)	✓		-	4100	23	1-22 & 25	22
(Wauters and Vanhoucke 2015)	✓		Mean lags indicator	90	2	1-9**	7
(Batselier and Vanhoucke 2017a)	✓		Regularity index	Not specified	23	1-9	7
(de Andrade et al. 2019)	✓		Regularity index	-	57	7-9, 14 & 15	7 & 14
This study	✓	✓	R , ρ and τ correlations	4100	-***	1-27	22

* Khamooshi and Abdi (2017) actually used the Root Mean Squared Error (RMSE) which is quite an unusual error metric.

** Wauters and Vanhoucke also compared the performance of one non deterministic EVM method proposed by Elshaer (2013).

*** Due to the probabilistic approach adopted in this study to measure the EAC(t) methods stability, it is not possible to resort to real projects.

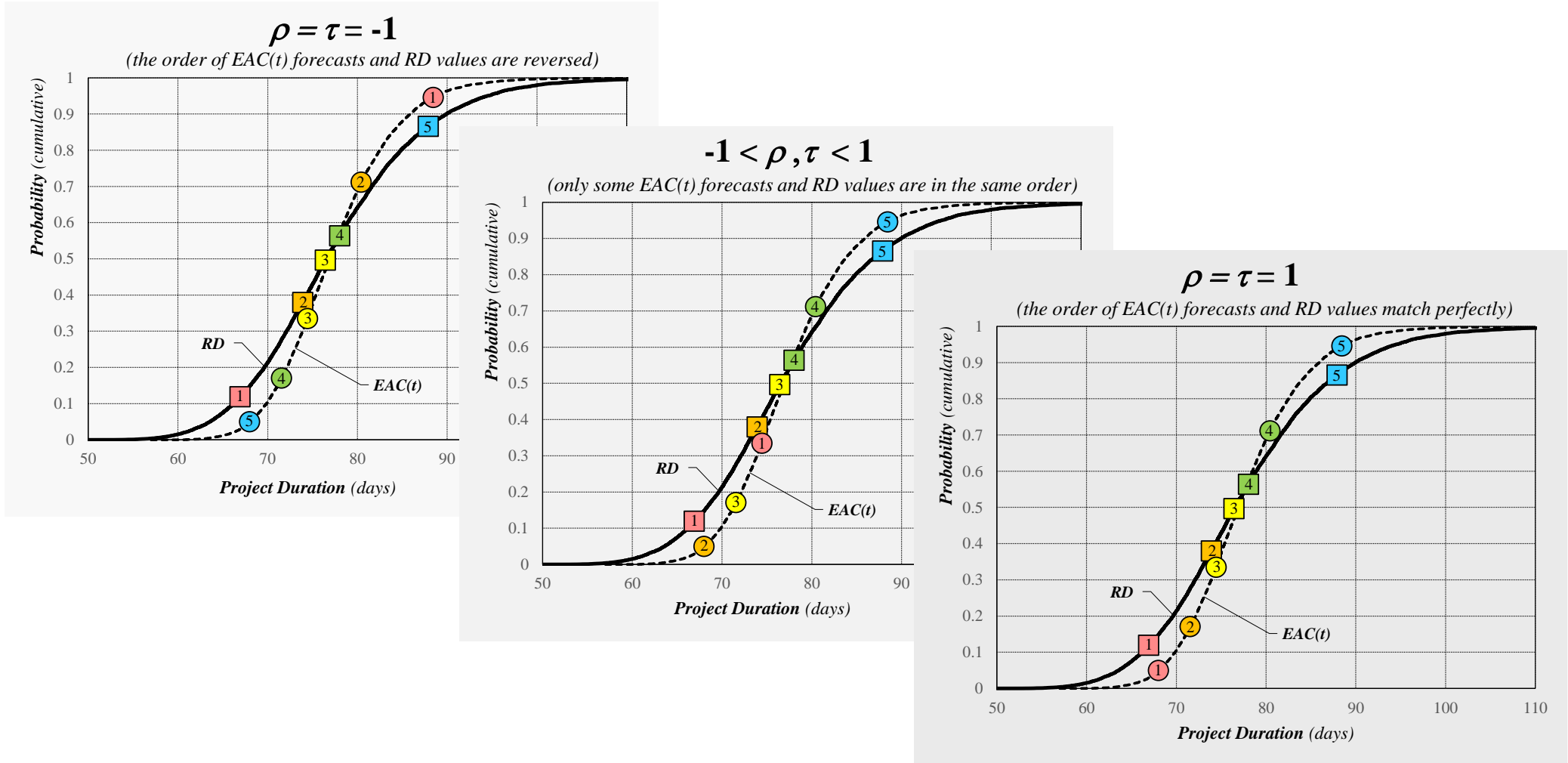


Figure 1: Interpretation of EAC(t) metrics stability through Spearman's ρ and Kendall's τ parametric tests of rank correlation.

Average Pearson's R													Average Spearman's Γ													Average Kendall's τ													
Track. per. (%RD) \blacktriangleright			0%	10%	20%	30%	40%	50%	60%	70%	80%	90%	100%	Avg.	0%	10%	20%	30%	40%	50%	60%	70%	80%	90%	100%	Avg.	0%	10%	20%	30%	40%	50%	60%	70%	80%	90%	100%	Avg.	
ID	Method	EAC(t)	0.00	0.29	0.40	0.50	0.58	0.66	0.73	0.80	0.86	0.90	0.92	0.58	0.00	0.27	0.40	0.50	0.58	0.65	0.70	0.75	0.77	0.77	0.71	0.61	0.00	0.09	0.13	0.23	0.30	0.36	0.40	0.43	0.43	0.36	0.10	0.27	
1	EVM	PV1	0.00	0.25	0.39	0.50	0.58	0.64	0.69	0.71	0.72	0.70	0.63	0.58	0.00	0.27	0.40	0.50	0.58	0.65	0.70	0.75	0.77	0.77	0.71	0.61	0.00	-0.02	0.13	0.23	0.30	0.36	0.40	0.43	0.43	0.36	0.10	0.27	
2	EVM	PV2	0.00	0.27	0.37	0.46	0.53	0.59	0.65	0.69	0.71	0.70	0.63	0.56	0.00	0.31	0.40	0.49	0.57	0.63	0.69	0.74	0.77	0.77	0.71	0.61	0.00	0.14	0.21	0.28	0.33	0.38	0.42	0.44	0.44	0.37	0.10	0.31	
3	EVM	PV3	0.00	0.20	0.28	0.35	0.41	0.45	0.48	0.49	0.47	0.42	0.35	0.39	0.00	0.23	0.30	0.37	0.42	0.46	0.49	0.51	0.50	0.46	0.37	0.41	0.00	0.11	0.17	0.21	0.25	0.28	0.30	0.31	0.30	0.26	0.20	0.24	
4	EVM	ED1	0.00	0.25	0.39	0.51	0.60	0.68	0.75	0.82	0.88	0.94	0.98	0.68	0.00	0.28	0.40	0.50	0.59	0.66	0.73	0.80	0.87	0.95	0.99	0.68	0.00	-0.08	0.09	0.20	0.28	0.34	0.41	0.47	0.55	0.65	0.74	0.81	0.36
5	EVM	ED2	0.00	0.27	0.37	0.46	0.54	0.61	0.70	0.79	0.87	0.94	0.98	0.65	0.00	0.31	0.40	0.49	0.57	0.64	0.71	0.78	0.87	0.95	0.99	0.67	0.00	0.14	0.21	0.28	0.34	0.38	0.43	0.49	0.56	0.66	0.75	0.82	0.42
6	EVM	ED3	0.00	0.21	0.29	0.38	0.46	0.53	0.63	0.73	0.84	0.93	0.98	0.60	0.00	0.24	0.33	0.41	0.49	0.56	0.63	0.72	0.81	0.92	0.98	0.61	0.00	0.12	0.18	0.24	0.29	0.34	0.39	0.46	0.54	0.65	0.75	0.82	0.40
7	EVM	ES1	0.00	0.28	0.44	0.56	0.65	0.73	0.80	0.86	0.92	0.97	1.00	0.72	0.00	0.27	0.41	0.52	0.61	0.69	0.76	0.83	0.90	0.96	1.00	0.70	0.00	-0.03	0.14	0.25	0.34	0.42	0.49	0.56	0.64	0.73	0.80	0.87	0.43
8	EVM	ES2	0.00	0.31	0.40	0.50	0.59	0.67	0.75	0.83	0.90	0.96	1.00	0.69	0.00	0.31	0.42	0.51	0.60	0.67	0.75	0.82	0.89	0.95	0.99	0.69	0.00	0.16	0.24	0.31	0.38	0.44	0.50	0.57	0.64	0.73	0.80	0.87	0.48
9	EVM	ES3	0.00	0.23	0.33	0.43	0.52	0.61	0.70	0.79	0.87	0.95	1.00	0.64	0.00	0.26	0.36	0.46	0.54	0.63	0.71	0.79	0.87	0.95	0.99	0.66	0.00	0.14	0.21	0.28	0.34	0.40	0.47	0.54	0.63	0.72	0.80	0.87	0.45
10	EDM	PV1	0.00	0.31	0.45	0.55	0.62	0.68	0.73	0.76	0.76	0.74	0.66	0.62	0.00	0.30	0.43	0.52	0.61	0.67	0.73	0.78	0.80	0.80	0.72	0.64	0.00	0.01	0.16	0.25	0.33	0.39	0.44	0.47	0.48	0.43	0.18	0.31	
11	EDM	PV2	0.00	0.34	0.42	0.50	0.57	0.63	0.69	0.73	0.75	0.74	0.66	0.60	0.00	0.34	0.43	0.52	0.60	0.66	0.72	0.77	0.80	0.80	0.72	0.64	0.00	0.17	0.24	0.30	0.36	0.40	0.45	0.48	0.49	0.43	0.18	0.35	
12	EDM	ED1	0.00	0.31	0.45	0.56	0.64	0.71	0.79	0.85	0.91	0.96	0.99	0.70	0.00	0.30	0.42	0.52	0.61	0.68	0.75	0.83	0.90	0.96	1.00	0.64	0.00	-0.06	0.11	0.22	0.31	0.37	0.44	0.51	0.59	0.69	0.77	0.85	0.39
13	EDM	ED2	0.00	0.34	0.42	0.50	0.58	0.65	0.74	0.82	0.90	0.96	0.99	0.69	0.00	0.34	0.43	0.52	0.60	0.66	0.74	0.81	0.89	0.96	1.00	0.69	0.00	0.17	0.24	0.30	0.36	0.41	0.46	0.52	0.60	0.69	0.77	0.85	0.45
14	EDM	ES1	0.00	0.31	0.46	0.57	0.66	0.74	0.81	0.87	0.93	0.97	1.00	0.73	0.00	0.30	0.43	0.53	0.62	0.70	0.77	0.84	0.91	0.96	1.00	0.71	0.00	-0.03	0.15	0.26	0.35	0.42	0.50	0.57	0.65	0.73	0.81	0.89	0.44
15	EDM	ES2	0.00	0.35	0.43	0.52	0.60	0.68	0.76	0.83	0.90	0.96	1.00	0.70	0.00	0.35	0.44	0.53	0.61	0.69	0.76	0.83	0.90	0.96	1.00	0.71	0.00	0.18	0.25	0.32	0.38	0.45	0.51	0.58	0.65	0.73	0.81	0.89	0.49
16	ESM	ES1	0.00	0.29	0.44	0.55	0.64	0.72	0.80	0.86	0.92	0.97	1.00	0.72	0.00	0.28	0.41	0.51	0.60	0.68	0.76	0.83	0.90	0.96	0.99	0.69	0.00	-0.03	0.14	0.25	0.33	0.41	0.49	0.56	0.64	0.72	0.80	0.87	0.43
17	ESM	ES2	0.00	0.27	0.38	0.48	0.57	0.66	0.74	0.82	0.89	0.96	1.00	0.68	0.00	0.27	0.39	0.49	0.58	0.66	0.74	0.82	0.89	0.95	0.99	0.68	0.00	0.14	0.22	0.30	0.37	0.43	0.50	0.57	0.64	0.73	0.80	0.87	0.47
18	ESM	ES3	0.00	0.21	0.31	0.41	0.51	0.60	0.69	0.78	0.87	0.95	1.00	0.63	0.00	0.24	0.35	0.44	0.53	0.62	0.70	0.79	0.87	0.95	0.99	0.65	0.00	0.12	0.20	0.27	0.33	0.40	0.47	0.54	0.62	0.72	0.80	0.87	0.45
19	XSM	XSM1	0.00	0.26	0.41	0.51	0.59	0.67	0.75	0.82	0.89	0.96	1.00	0.69	0.00	0.25	0.40	0.51	0.60	0.67	0.75	0.82	0.89	0.95	0.99	0.68	0.00	0.09	0.22	0.30	0.37	0.43	0.50	0.57	0.64	0.72	0.80	0.87	0.46
20	XSM	XSM2	0.00	0.30	0.45	0.55	0.63	0.70	0.76	0.83	0.90	0.96	1.00	0.71	0.00	0.28	0.42	0.52	0.61	0.68	0.75	0.82	0.89	0.95	0.99	0.69	0.00	0.06	0.20	0.29	0.37	0.43	0.50	0.57	0.64	0.73	0.80	0.87	0.46
21	XSM	XSM3	0.00	0.29	0.44	0.53	0.61	0.68	0.76	0.84	0.91	0.97	1.00	0.70	0.00	0.27	0.42	0.52	0.61	0.68	0.76	0.83	0.90	0.96	1.00	0.69	0.00	0.10	0.22	0.30	0.37	0.43	0.50	0.57	0.64	0.73	0.81	0.87	0.47
22	ES _{min}	ES1	0.00	0.34	0.47	0.58	0.67	0.75	0.82	0.88	0.93	0.97	1.00	0.74	0.00	0.32	0.45	0.55	0.64	0.71	0.79	0.85	0.91	0.96	1.00	0.72	0.00	0.06	0.19	0.29	0.37	0.44	0.51	0.58	0.66	0.74	0.81	0.86	0.46
23	ES _{min}	ES2	0.00	0.32	0.42	0.52	0.60	0.69	0.77	0.84	0.91	0.96	1.00	0.70	0.00	0.34	0.45	0.54	0.63	0.70	0.77	0.84	0.91	0.96	1.00	0.71	0.00	0.20	0.27	0.34	0.40	0.46	0.53	0.59	0.66	0.74	0.81	0.86	0.50
24	ES _{min}	ES3	0.00	0.28	0.37	0.45	0.54	0.63	0.72	0.80	0.89	0.96	1.00	0.66	0.00	0.31	0.40	0.49	0.58	0.66	0.74	0.81	0.89	0.95	1.00	0.68	0.00	0.18	0.25	0.31	0.37	0.43	0.50	0.57	0.64	0.73	0.81	0.86	0.48
25	ES _{max}	ES1	0.00	0.24	0.40	0.54	0.64	0.73	0.80	0.87	0.92	0.97	1.00	0.71	0.00	0.26	0.38	0.50	0.60	0.69	0.77	0.84	0.90	0.96	1.00	0.69	0.00	-0.01	0.14	0.25	0.34	0.42	0.49	0.57	0.65	0.73	0.81	0.86	0.44
26	ES _{max}	ES2	0.00	0.38	0.45	0.54	0.62	0.70	0.77	0.84	0.91	0.96	1.00	0.72	0.00	0.38	0.46	0.55	0.63	0.70	0.77	0.83	0.90	0.96	1.00	0.72	0.00	0.19	0.26	0.33	0.40	0.46	0.52	0.58	0.65	0.73	0.81	0.86	0.49
27	ES _{max}	ES3	0.00	0.30	0.37	0.47	0.55	0.64	0.72	0.81	0.89	0.96	1.00	0.67	0.00	0.32	0.41	0.50	0.58	0.66	0.73	0.81	0.89	0.95	1.00	0.68	0.00	0.17	0.23	0.30	0.36	0.42	0.49	0.56	0.64	0.73	0.81	0.86	0.47

Average MSEs													Average MAPEs													
Track. per. (%RD) \blacktriangleright			0%	10%	20%	30%	40%	50%	60%	70%	80%	90%	100%	Avg.	0%	10%	20%	30%	40%	50%	60%	70%	80%	90%	100%	Avg.
ID	Method	EAC(t)	1.35	42.37	24.04	6.11	3.25	1.87	1.13	0.75	0.49	0.32	0.25	0.95	0.14	0.14	0.13	0.13	0.12	0.11	0.10	0.10	0.10	0.10	0.12	0.12
1	EVM	PV1	1.35	1.33	1.21	1.07	0.94	0.83	0.75	0.71	0.74	0.85	1.08	0.95	0.14	0.14	0.13	0.13	0.12	0.11	0.10	0.10	0.10	0.12	0.12	
2	EVM	PV2	1.35	117.7	48.29	14.13	6.96	3.07	1.65	1.17	0.92	0.89	1.08	19.58	0.14	0.29	0.24	0.20	0.17	0.15	0.13	0.11	0.10	0.12	0.16	
3	EVM	PV3	1.35	351.0	204.8	31.47	14.03	7.35	4.16	3.13	2.45	2.04	1.94	62.24	0.14	0.46	0.37	0.30	0.26	0.23	0.20	0.18	0.17	0.16	0.25	
4	EVM	ED1	1.35	1.47	1.30	1.17	1.02	0.87	0.73	0.62	0.48	0.32	0.18	0.82	0.14	0.14	0.14	0.13	0.12	0.11	0.10	0.10	0.08	0.07	0.04	0.10
5	EVM	ED2	1.35	117.7	48.29	14.13	6.96	3.08	1.64	1.09	0.68	0.34	0.13	19.40	0.14	0.29	0.24	0.20	0.17	0.15	0.13	0.11	0.09	0.07	0.03	0.15
6	EVM	ED3	1.35	348.1	201.0	28.82	11.76	5.33	2.33	1.42	0.81	0.37	0.13	60.00	0.14	0.44	0.34	0.26	0.22	0.18	0.14	0.12	0.09	0.07	0.03	0.19
7	EVM																									

Average Pearson's R											Average Spearman's ρ											Average Kendall's τ										
Serial-Par. (%SP) ▶	7%	17%	28%	38%	48%	59%	69%	79%	90%	Avg.	7%	17%	28%	38%	48%	59%	69%	79%	90%	Avg.	7%	17%	28%	38%	48%	59%	69%	79%	90%	Avg.		
ID	Method	EAC(t)	0.30	0.41	0.48	0.57	0.66	0.74	0.82	0.88	0.93	0.62	0.30	0.40	0.47	0.58	0.67	0.74	0.81	0.87	0.93	0.62	-0.16	0.13	0.24	0.35	0.44	0.51	0.58	0.66	0.74	0.62
1	EVM	PV1	0.23	0.39	0.47	0.57	0.67	0.73	0.80	0.85	0.86	0.62	0.22	0.38	0.45	0.57	0.67	0.73	0.80	0.87	0.91	0.62	-0.33	0.03	0.17	0.31	0.41	0.48	0.56	0.64	0.68	0.33
2	EVM	PV2	0.39	0.38	0.42	0.53	0.63	0.71	0.79	0.84	0.86	0.62	0.40	0.38	0.44	0.57	0.66	0.73	0.80	0.87	0.91	0.64	0.05	0.15	0.22	0.35	0.44	0.50	0.57	0.64	0.69	0.40
3	EVM	PV3	0.27	0.27	0.32	0.41	0.48	0.55	0.58	0.59	0.57	0.45	0.28	0.29	0.32	0.43	0.49	0.54	0.57	0.60	0.61	0.46	0.03	0.13	0.17	0.27	0.32	0.36	0.39	0.41	0.42	0.28
4	EVM	ED1	0.23	0.40	0.48	0.58	0.68	0.73	0.81	0.87	0.93	0.63	0.22	0.38	0.46	0.57	0.67	0.73	0.80	0.87	0.93	0.63	-0.51	-0.05	0.12	0.29	0.40	0.48	0.55	0.64	0.73	0.29
5	EVM	ED2	0.39	0.38	0.42	0.53	0.63	0.71	0.80	0.87	0.93	0.63	0.40	0.38	0.44	0.57	0.66	0.73	0.80	0.87	0.94	0.64	0.05	0.15	0.22	0.35	0.44	0.50	0.57	0.65	0.74	0.41
6	EVM	ED3	0.29	0.30	0.35	0.46	0.55	0.65	0.74	0.83	0.92	0.56	0.31	0.32	0.36	0.50	0.58	0.67	0.74	0.82	0.91	0.58	0.04	0.14	0.19	0.31	0.38	0.45	0.52	0.61	0.71	0.37
7	EVM	ES1	0.15	0.44	0.53	0.62	0.72	0.79	0.86	0.91	0.96	0.67	0.15	0.40	0.49	0.60	0.69	0.76	0.84	0.90	0.95	0.64	-0.53	0.03	0.22	0.34	0.44	0.52	0.60	0.68	0.77	0.34
8	EVM	ES2	0.36	0.41	0.46	0.57	0.68	0.76	0.84	0.90	0.96	0.66	0.34	0.40	0.47	0.59	0.69	0.77	0.84	0.90	0.95	0.66	0.01	0.19	0.28	0.38	0.46	0.54	0.61	0.69	0.77	0.44
9	EVM	ES3	0.28	0.34	0.42	0.51	0.61	0.71	0.79	0.87	0.95	0.66	0.28	0.35	0.43	0.55	0.64	0.72	0.79	0.87	0.94	0.62	0.02	0.17	0.25	0.35	0.43	0.50	0.57	0.66	0.76	0.41
10	EDM	PV1	0.28	0.47	0.52	0.61	0.71	0.77	0.84	0.89	0.89	0.66	0.24	0.44	0.49	0.60	0.68	0.75	0.83	0.89	0.93	0.65	-0.39	0.08	0.21	0.34	0.43	0.51	0.59	0.67	0.72	0.35
11	EDM	PV2	0.51	0.45	0.47	0.57	0.67	0.75	0.83	0.88	0.89	0.67	0.51	0.44	0.48	0.59	0.68	0.75	0.83	0.89	0.93	0.68	0.08	0.19	0.26	0.37	0.45	0.52	0.60	0.67	0.73	0.43
12	EDM	ED1	0.28	0.48	0.53	0.62	0.71	0.77	0.85	0.91	0.96	0.68	0.24	0.44	0.50	0.60	0.68	0.75	0.83	0.89	0.95	0.65	-0.57	-0.02	0.17	0.32	0.42	0.50	0.59	0.67	0.77	0.32
13	EDM	ED2	0.51	0.45	0.47	0.57	0.67	0.75	0.84	0.90	0.96	0.68	0.51	0.44	0.48	0.59	0.68	0.75	0.83	0.89	0.95	0.68	0.08	0.19	0.26	0.37	0.45	0.52	0.60	0.68	0.77	0.44
14	EDM	ES1	0.21	0.49	0.56	0.63	0.73	0.79	0.86	0.91	0.96	0.68	0.17	0.45	0.52	0.60	0.69	0.76	0.84	0.90	0.95	0.65	-0.59	0.04	0.24	0.34	0.45	0.52	0.60	0.68	0.77	0.34
15	EDM	ES2	0.47	0.47	0.50	0.58	0.68	0.76	0.84	0.91	0.96	0.69	0.46	0.45	0.50	0.60	0.69	0.77	0.84	0.90	0.95	0.69	0.05	0.22	0.30	0.39	0.47	0.54	0.61	0.69	0.77	0.45
16	ESM	ES1	0.23	0.44	0.52	0.62	0.72	0.79	0.86	0.91	0.96	0.67	0.21	0.40	0.48	0.59	0.69	0.76	0.83	0.90	0.95	0.65	-0.51	0.03	0.21	0.34	0.44	0.52	0.60	0.68	0.77	0.34
17	ESM	ES2	0.26	0.36	0.43	0.55	0.67	0.76	0.84	0.90	0.96	0.64	0.26	0.35	0.44	0.58	0.68	0.76	0.84	0.90	0.95	0.64	-0.03	0.16	0.26	0.37	0.46	0.54	0.61	0.69	0.77	0.43
18	ESM	ES3	0.22	0.30	0.39	0.50	0.61	0.70	0.79	0.87	0.95	0.59	0.23	0.32	0.40	0.54	0.64	0.72	0.79	0.87	0.94	0.61	0.00	0.15	0.24	0.34	0.43	0.50	0.57	0.66	0.76	0.41
19	XSM	XSM1	0.14	0.43	0.49	0.56	0.67	0.75	0.84	0.90	0.96	0.64	0.13	0.39	0.48	0.59	0.68	0.76	0.83	0.89	0.95	0.63	-0.28	0.15	0.27	0.37	0.46	0.53	0.61	0.68	0.77	0.40
20	XSM	XSM2	0.18	0.45	0.53	0.61	0.69	0.76	0.83	0.89	0.95	0.65	0.16	0.40	0.49	0.59	0.69	0.76	0.83	0.89	0.95	0.64	-0.42	0.11	0.26	0.37	0.46	0.53	0.61	0.68	0.77	0.37
21	XSM	XSM3	0.20	0.48	0.52	0.58	0.67	0.76	0.84	0.90	0.96	0.66	0.17	0.45	0.51	0.59	0.68	0.76	0.83	0.89	0.95	0.65	-0.31	0.17	0.28	0.37	0.46	0.53	0.61	0.68	0.77	0.40
22	ES _{min}	ES1	0.38	0.50	0.58	0.65	0.74	0.80	0.86	0.91	0.96	0.71	0.35	0.47	0.55	0.62	0.71	0.77	0.84	0.90	0.95	0.68	-0.18	0.14	0.27	0.36	0.46	0.53	0.60	0.68	0.77	0.40
23	ES _{min}	ES2	0.40	0.44	0.50	0.59	0.69	0.77	0.85	0.91	0.96	0.68	0.37	0.46	0.54	0.62	0.70	0.77	0.84	0.90	0.95	0.68	0.14	0.26	0.33	0.40	0.48	0.55	0.62	0.69	0.77	0.47
24	ES _{min}	ES3	0.39	0.41	0.46	0.53	0.63	0.71	0.79	0.87	0.95	0.64	0.37	0.43	0.50	0.58	0.65	0.73	0.80	0.87	0.94	0.65	0.15	0.24	0.31	0.37	0.44	0.51	0.58	0.66	0.76	0.45
25	ES _{max}	ES1	-0.06	0.33	0.54	0.62	0.72	0.78	0.85	0.91	0.96	0.63	0.10	0.31	0.51	0.60	0.69	0.76	0.83	0.90	0.95	0.63	-0.40	0.01	0.24	0.34	0.45	0.52	0.60	0.68	0.77	0.36
26	ES _{max}	ES2	0.53	0.49	0.55	0.59	0.69	0.76	0.84	0.91	0.96	0.70	0.50	0.49	0.56	0.62	0.70	0.77	0.84	0.90	0.95	0.70	0.06	0.23	0.34	0.40	0.47	0.54	0.61	0.69	0.77	0.46
27	ES _{max}	ES3	0.49	0.42	0.49	0.53	0.62	0.71	0.79	0.87	0.95	0.65	0.48	0.44	0.51	0.58	0.65	0.73	0.80	0.87	0.94	0.67	0.07	0.21	0.31	0.37	0.44	0.50	0.57	0.66	0.76	0.43

Average MSEs											Average MAPEs											
Serial-Par. (%SP) ▶	7%	17%	28%	38%	48%	59%	69%	79%	90%	Avg.	7%	17%	28%	38%	48%	59%	69%	79%	90%	Avg.		
ID	Method	EAC(t)	2.69	2.68	2.76	2.94	2.23	1.19	0.82	0.50	0.29	0.88	0.34	0.22	0.18	0.15	0.12	0.09	0.07	0.05	0.04	0.12
1	EVM	PV1	1.84	1.41	1.00	0.80	0.76	0.66	0.59	0.47	0.43	0.88	0.27	0.18	0.14	0.11	0.09	0.08	0.07	0.06	0.05	0.12
2	EVM	PV2	2.5	3.97	4.46	4.86	4.04	1.94	1.40	0.78	0.54	2.72	0.34	0.22	0.19	0.17	0.14	0.11	0.09	0.07	0.05	0.15
3	EVM	PV3	3.3	7.8	8.78	9.06	10.05	4.87	4.56	3.54	3.01	6.10	0.41	0.30	0.27	0.26	0.23	0.19	0.18	0.15	0.14	0.24
4	EVM	ED1	1.75	1.50	1.03	0.82	0.82	0.80	0.68	0.50	0.36	0.92	0.26	0.18	0.14	0.11	0.10	0.09	0.08	0.06	0.05	0.12
5	EVM	ED2	2.5	3.97	4.46	4.86	4.08	1.95	1.42	0.77	0.45	2.71	0.34	0.22	0.19	0.17	0.14	0.11	0.09	0.07	0.05	0.15
6	EVM	ED3	3.1	7.1	7.77	7.31	7.89	2.69	1.96	1.00	0.52	4.37	0.40	0.28	0.24	0.21	0.17	0.13	0.11	0.07	0.05	0.18
7	EVM	ES1	1.77	1.39	0.93	0.69	0.60	0.46	0.32	0.20	0.09	0.72	0.26	0.18	0.13	0.10	0.08	0.07	0.05	0.04	0.03	0.10
8	EVM	ES2	2.56	1.70	2.63	2.71	1.65	0.95	0.53	0.28	0.11	1.46	0.35	0.21	0.20	0.16	0.12	0.09	0.07	0.05	0.03	0.14
9	EVM	ES3	3.21	3.19	4.28	5.90	3.25	1.60	0.95	0.47	0.16	2.56	0.40	0.27	0.25	0.21	0.16	0.11	0.08	0.06	0.03	0.17
10	EDM	PV1	1.85	1.37	0.94	0.71	0.64	0.53	0.38	0.27	0.25	0.77	0.27	0.18	0.13	0.10	0.09	0.07	0.06	0.04	0.03	0.11
11	EDM	PV2	2.55	1.75	1.56	2.09	1.46	0.99	0.53	0.31	0.23	1.28	0.35	0.19	0.16	0.15	0.11	0.09	0.07	0.05	0.03	0.13
12	EDM	ED1	1.77	1.42	0.99	0.73	0.67	0.54	0.39	0.23	0.10	0.76	0.26	0.18	0.13	0.10	0.09	0.08	0.06	0.04	0.03	0.11
13	EDM	ED2	2.55	1.75	1.56	2.09	1.47	0.99	0.53	0.29	0.11	1.26	0.35	0.19	0.16	0.15	0.11	0.09	0.07	0.05	0.03	0.13
14	EDM	ES1	1.78	1.38	0.91	0.68	0.59	0.46	0.32	0.20	0.09	0.71	0.26	0.18	0.13	0.10	0.08	0.07	0.05	0.04	0.03	0.10
15	EDM	ES2	2.62	1.49	2.29	2.45	1.60	0.95	0.5													

Supplemental online material

Results from the 4100 simulated projects can be downloaded here <https://bit.ly/3d8jRII> . The link allows you to download a 87 MB Excel spreadsheet file. Please, be patient when downloading and opening it. A list of all abbreviations, variables and mathematical expressions used in the paper follows in Table S1.

Table S1. List of major EVM-related abbreviations, variables and mathematical expressions used in the paper.

Variable	Unit	Description	Expression
AC	Money	(Project) Actual Cost (at tracking period AT)	$AC = \sum_{i \in N} AC_{i,AT}$
$AC_{i,AT}$	Money	Activity i 's Actual Cost (at tracking period AT)	-
AT	Time	Actual Time (current tracking period). Also named AD .	-
AT_t	Time	Ongoing (Project) duration at tracking period t	-
BAC	Money	(Project) Budget At Completion (planned total project cost estimate)	-
$BAC(t)$	Time	(Project) Duration At Completion (sum of all activities' TPD or planned d_i at the end of the project)	$BAC(t) = \sum_{i \in N} d_i$
BAC_i	Money	Activity i 's total planned cost	-
c_i	Money	Activity i 's cost	-
CPI	1	(Project) Cost Performance Index (at tracking period AT)	$CPI = \frac{EV}{AC}$
CV_i	1	Activity i 's Coefficient of Variation	$CV_i = \frac{\sigma_i}{\mu_i}$
d_i	Time	Activity i 's duration	-
d_{mk}	Ranks	Difference between the ranking (order) values of $EAC(t)_{AT}$ and RD_{mk} for project m , for the K simulation runs at a particular tracking period AT .	$d_{mk} \equiv rank(EAC(t)_{AT}^k) - rank(RD_{mk})$ for $k=1,2,\dots,K$.
DPI	1	(Project) Duration Performance Index (EVM's $SPI(t)$ counterpart in EDM) (at tracking period AT)	$DPI = \frac{ED}{AT}$
$EAC(t)_{AT}$	Time	Project Duration forecasting estimate at tracking period AT .	-
$EAC(t)_x$	Time	Project Duration forecasting method x	See Table 1
$\overline{EAC(t)}_{AT}$	Time	Average of the $EAC(t)$ estimates at tracking period AT in the K simulation runs.	

Variable	Unit	Description	Expression
ED	Time	(Project) Earned Duration (EVM's ES counterpart in EDM) (at tracking period AT) as formulated by Khamooshi and Golafshani (2014). Also named $ED(t)$	$ED = t + \frac{TED - TPD_t}{TPD_{t+1} - TPD_t}$
ED'	Time	(Project) Earned Duration (at tracking period AT) as formulated by Jacob (2003)	$ED = AT \cdot SPI$
EDI	1	(Project) Earned Duration Index (EVM's SPI counterpart in EDM) (at tracking period AT)	$EDI = \frac{TED}{TPD}$
EDI_t	1	(Project) EDI at tracking period t	$EDI_t = \frac{TED_t}{TPD_t}$
EDM	-	Earned Duration Management	-
ES	Time	(Project) Earned Schedule (at tracking period AT)	$ES = t + \frac{EV - PV_t}{PV_{t+1} - PV_t} \cdot (t+1 - t)$
$ES(e)$	Time	(Project) Effective Earned Schedule (ES calculated with $EV(e)$) (at tracking period AT)	$ES(e) = t + \frac{EV(e) - PV_t}{PV_{t+1} - PV_t}$
ES_i	Time	Activity i 's Earned Schedule (at tracking period AT)	$ES_i = SD_i + PC_i \cdot d_i$
ESM	-	Earned Schedule Management	-
ES_{max}	Time	(Project) Maximum Earned Schedule (at tracking period AT)	$ES_{max} = MAX \{ES_i : PC_i \in (0,1], i \in N\}$
ES_{min}	Time	(Project) Minimum Earned Schedule (at tracking period AT)	$ES_{min} = MIN \{ES_i + s_i : PC_i \in [0,1), i \in N\}$
ES_t	Time	(Project) ES at tracking period t	-
EV	Money	(Project) Earned Value (at tracking period AT)	$EV = \sum_{i \in N} EV_{i,AT}$
$EV(e)$	Money	(Project) Effective Earned Value (at tracking period AT)	$EV(e) = \left[1 - (1-p) \left(1 - PC \cdot e^{-\frac{1-PC}{2}} \right) \right] EV$
$EV_{i,AT}$	Money	Activity i 's Earned Value (at tracking period AT)	-
$EV_{i,AT}$	Money	Activity i 's Earned Value at tracking period AT	-
EVM	-	Earned Value Management	-
EV_t	Money	(Project) Earned Value at tracking period t	$EV_t = \sum_{i \in N} EV_{i,t}$
i	-	Activity i (one of the activities of the project schedule with $i=1,2,\dots,N$)	-
k	-	Each of the simulation runs in the experiments ($k=1,2,\dots,K$ in the paper)	-
K	Sim. Runs	Number of simulation runs in the experiments ($K=100$ in the paper)	-
m	-	Project m (one of the 4100 simulated projects of the dataset)	-
M	-	Total number of projects (4100 in the dataset)	-
$MAPE_{AT}$	-	Mean Absolute Percentage Error at tracking period AT .	See eq. (3) in the paper

Variable	Unit	Description	Expression
MSE_{AT}	-	Mean Squared Error Error at tracking period AT.	See eq. (2) in the paper
n	Activities	Total number of (non-dummy) activities scheduled in the ongoing project (30 in the projects dataset)	-
N	units	Total number of planned tracking periods of a project	-
p	1	(Project) Schedule adherence p -Factor (at tracking period AT)	$p = \frac{\sum_{i \in N} \min(PV_{i,ES}, EV_{i,AT})}{\sum_{i \in N} PV_{i,ES}}$
P_m	Concordant pairs	Number of concordant pairs between the EAC(t) estimates and the RD values for each project m .	See eq. (7) in the paper
PC	1	(Project) Percentage of Completion (at tracking period AT)	$PC = \frac{EV}{BAC}$
PC_i	1	Activity i 's Percentage of Completion (at tracking period AT)	$PC_i = \frac{EV_i}{BAC_i}$
PD	Time	(Project) Planned Duration (total project duration estimate)	-
PF	-	Performance Factor that can be 1 or another indicator such as SPI , $SPI(t)$, $SPI(t)(e)$, $SPI(t)_{ESmin}$, $SPI(t)_{ESmax}$, SCI , $SCI(t)$, $SCI(t)(e)$, $SCI(t)_{ESmin}$, $SCI(t)_{ESmax}$, even an exponential smoothing factor (e.g. $T_{t,SPI(t)}$, $T_{t,AT}/T_{t,ES}$ or $T_{t,EDI}$)	-
PV	Money	(Project) Planned Value (at tracking period AT)	$PV = \sum_{i \in N} PV_{i,AT}$
$PV_{i,AT}$	Money	Activity i 's Planned Value (at tracking period AT)	-
$PV_{i,ES}$	Money	Activity i 's Planned Value at tracking period ES	-
PV_{rate}	Money/time	(Project) Planned Value rate (at tracking period AT)	$PV_{rate} = BAC/PD$
PV_t	Money	(Project) Planned Value at tracking period t	$PV_t = \sum_{i \in N} PV_{i,t}$
q	Activities	Number of activities in the path with the highest number of activities of a project (which is not necessarily the longest in duration)	-
R_{AT}	1	Pearson's linear correlation coefficient at tracking period AT.	See eq. (4) in the paper
RAC	Money	(Project) Real (budget) At Completion (only known once the project is completed)	-
RD	Time	(Project) Real Duration (only known once the project is completed)	-
RD_{mk}	Time	Real (Actual) Duration of project m in the simulation run k .	-
\overline{RD}_{mk}	Time	Average of project m 's Real Duration values in the K simulation runs.	-

Variable	Unit	Description	Expression
SCI	1	(Project) Schedule Cost Index using original EVM metrics (at tracking period AT)	$SCI = SPI \cdot CPI$
$SCI(t)$	1	(Project) Schedule Cost Index using the ES metric (at tracking period AT)	$SCI(t) = SPI(t) \cdot CPI$
$SCI(t)_{ESmax}$	1	(Project) Schedule Cost Index using the ES_{max} metric (at tracking period AT)	$SCI(t)_{ESmax} = SPI(t)_{ESmax} \cdot CPI$
$SCI(t)_{ESmin}$	1	(Project) Schedule Cost Index using the ES_{min} metric (at tracking period AT)	$SCI(t)_{ESmin} = SPI(t)_{ESmin} \cdot CPI$
$SCI(t)(e)$	1	(Project) Effective Schedule Cost Index (at tracking period AT)	$SCI(t)(e) = SPI(t)(e) \cdot CPI$
SD_i	Time	Activity i 's (Earliest) Start Date (at tracking period AT)	Critical path calculations (ASAP schedule)
s_i	Time	Activity i 's slack or float . Difference between each activity's earliest and latest Finish or Start.	Critical path calculations
SP	1	Serial-Parallel topological indicator	$SP = (q-1)/(n-1)$
SPI	1	(Project) Schedule Performance Index using original EVM metrics (at tracking period AT)	$SPI = \frac{EV}{PV}$
$SPI(t)$	1	(Project) Schedule Performance Index using the ES metric (at tracking period AT)	$SPI(t) = \frac{ES}{AT}$
$SPI(t)_{ESmax}$	1	(Project) Schedule Performance Index using the ES_{max} metric (at tracking period AT)	$SPI(t)_{ESmax} = ES_{max} / AT$
$SPI(t)_{ESmin}$	1	(Project) Schedule Performance Index using the ES_{min} metric (at tracking period AT)	$SPI(t)_{ESmin} = ES_{min} / AT$
$SPI(t)(e)$	1	(Project) Effective Schedule Performance Index (at tracking period AT)	$SPI(t)(e) = \frac{ES(e)}{AT}$
$SPI(t)_t$	1	(Project) $SPI(t)$ at tracking period t	$SPI(t)_t = \frac{ES_t}{t}$
t	Time	Integer tracking period such that: $PV_i \leq EV < PV_{i+1}$ for ES calculations, $TPD_i \leq TED < TPD_{i+1}$ for ED calc., $PV_i \leq EV(e) < PV_{i+1}$ for $ES(e)$ calc., or just $t=0,1,2 \dots n$ for the other calc.	-
TAD	Time	(Project) Total Actual Duration (EVM's AC counterpart in EDM) (at tracking period AT)	$TAD = \sum_{i \in N} TAD_{i,AT}$
$TAD_{i,AT}$	Time	Activity i 's Actual Duration (at tracking period AT)	-
TED	Time	(Project) Total Earned Duration (EVM's EV counterpart in EDM) (at tracking period AT)	$TED = \sum_{i \in N} TED_{i,AT}$
$TED_{i,AT}$	Time	Activity i 's Earned Duration (at tracking period AT)	-
TED_t	Time	(Project) Total Earned Duration at tracking period t	$TED_t = \sum_{i \in N} TED_{i,t}$
TPD	Time	(Project) Total Planned Duration (EVM's PV counterpart in EDM) (at tracking period AT)	$TPD = \sum_{i \in N} TPD_{i,AT}$
$TPD_{i,AT}$	Time	Activity i 's Planned Duration (at tracking period AT)	-
TPD_t	Time	(Project) Total Planned Duration at tracking period t	$TPD_t = \sum_{i \in N} TPD_{i,t}$

Variable	Unit	Description	Expression
$T_{t,AT}$	1	(Project) Trend of AT at tracking period t	$T_{t,AT} = \gamma(AT_t - AT_{t-1}) + (1-\gamma)T_{t-1,AT}$ with $T_{0,AT} = \frac{PD}{n}$
$T_{t,EDI}$	1	(Project) Trend of EDI at tracking period t	$T_{t,EDI} = \beta \cdot EDI_t + (1-\beta)T_{t-1,EDI}$ with $T_{0,EDI} = 1$
$T_{t,ES}$	1	(Project) Trend of ES at tracking period t	$T_{t,ES} = \gamma(ES_t - ES_{t-1}) + (1-\gamma)T_{t-1,AT}$ with $T_{0,ES} = \frac{PD}{n}$
$T_{t,SPI(t)}$	1	(Project) Trend of $SPI(t)$ at tracking period t	$T_{t,SPI(t)} = \beta \cdot SPI(t)_t + (1-\beta)T_{t-1,SPI(t)}$ with $T_{0,SPI(t)} = 1$
TV	1	(Project) Time Variance (at tracking period AT)	$TV = SV/PV_{rate}$
X_i	1	Activity i 's correlated Normally-distributed random variable whose variability is conditioned by the d_i from equation (2) and the rest varies according to a st. Normal distrib.	See eq. (14) in the paper
β	1	Exponential smoothing constant (assumed here as 0.25 according to Khamooshi & Abdi (2016))	-
γ	1	Exponential smoothing constant (assumed here as 0.05 according to Batselier & Vanhoucke (2017))	-
δ_i	1	Activity i 's duration-cost correlation	See eq. (15) in the paper
μ_i	Log time	Activity i 's average log duration.	See eq. (9) in the paper
μ'_i	Log money	Activity i 's average log cost.	See eq. (12) in the paper
σ_i	Log time	Activity i 's avg. log duration st. deviation.	See eq. (10) in the paper
σ'_i	Log money	Activity i 's average log cost st. deviation.	See eq. (13) in the paper
ρ_{AT}	1	Spearman's rank correlation coefficient at tracking period AT .	See eq. (5) in the paper
τ_{AT}	1	Kendall's rank correlation coefficient at tracking period AT .	See eq. (6) in the paper

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