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This paper must be cited as:

Salvador, F.; De La Morena, J.; Martínez López, J.; Jaramillo-Císcar, D. (2017). Assessment of compressibility effects on internal nozzle flow in diesel injectors at very high injection pressures. Energy Conversion and Management. 132:221-230. doi:10.1016/j.enconman.2016.11.032



The final publication is available at http://doi.org/10.1016/j.enconman.2016.11.032

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Additional Information

- 1 Energy Conversion and Management 132 (2017) 221–230
- 2 ASSESMENT OF COMPRESSIBILITY EFFECTS ON INTERNAL NOZZLE

3 FLOW IN DIESEL INJECTORS AT VERY HIGH INJECTION PRESSURES

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14 ABSTRACT

15 Diesel fuel injection systems are being used at higher injection pressure conditions over time because of more stringent emissions requirements. Thus, the importance to properly 16 17 take into account the fluid compressibility on injection CFD simulations is also increasing. In this paper, an investigation of the compressibility effects in nozzle flow 18 19 simulations has been carried out for injection pressures up to 250 MPa. To do so, the fluid properties (including density, viscosity and speed of sound) have been measured in a wide 20 range of boundary conditions. These measurements have allowed to obtain correlations 21 22 for the fluid properties as a function of pressure and temperature. Then, these equations have been incorporated to a CFD solver to take into account the variation of the fluid 23 properties with the pressure changes along the computational domain. The results from 24

these simulations have been compared to experimental mass flow rate and momentumflux results, showing a significant increase in accuracy with respect to an incompressible

27 flow solution.

28

29 **KEYWORDS:** nozzle, modelling, Diesel, dynamic, compressibility, CFD

30 NOMENCLATURE

- *a_f* Fuel speed of sound
- *A*_o Geometrical nozzle outlet area

$$C_d$$
 Discharge coefficient, $C_d = \frac{\dot{m}}{\rho_f \cdot A_o \cdot u_b}$

- *D_i* Geometrical nozzle inlet diameter
- *D*_o Geometrical nozzle outlet diameter

k-factor Nozzle conicity, $k - factor = \frac{D_i[\mu m] - D_o[\mu m]}{10}$

- *m* Mass flow
- *M* Momentum flux,
- *P* Fluid pressure
- P_b Discharge pressure
- *P*_{inj} Injection pressure
- *T* Fluid temperature

u_{eff} Effective outlet nozzle orifice velocity

$$u_b$$
 Theoretical outlet orifice velocity, $u_b = \sqrt{\frac{2 \cdot (P_{inj} - P_b)}{\rho_f}}$

Greek Symbols

$$\Delta P$$
 Pressure drop, $\Delta P = P_{inj} - P_b$

 ρ_f Fuel density

v_f Kinematic viscosity

 μ_f Dynamic viscosity

 μ_0 Dynamic viscosity at 0.1MPa pressure

31

32 1. INTRODUCTION.

In the last decades, diesel engine researchers have focused on minimizing the exhaust emissions maintaining the thermal efficiency advantage compared to gasoline engines. In particular, efforts have been made to achieve a combined reduction of nitrogen oxides and soot particles, which are characteristic of the lean diffusive combustion process existing in such engines [1], [2].

Two main paths have been followed to reduce exhaust emissions in diesel engines. On the one hand, several aftertreatment components, such as Diesel Particulate Filter (DPF), Diesel Oxidation Catalyst (DOC), Selective Catalyst Reduction (SCR) or Lean-NOx Trap (LNT) have been placed at the engine outlet to collect and/or convert the exhaust emissions before reaching the atmosphere [3], [4]. On the other hand, new combustion modes with high levels of Exhaust Gas Recirculation (EGR) and higher rates of premixed combustion have been implemented to reduce the emissions at engine-out [5]–[8]. The
performance of the fuel injection system has been proven as critical for such strategies,
since it controls the atomization and fuel-air mixing processes [9]–[11].

Many authors have tried to study the characteristics of the flow inside the fuel injector, 47 and in particular inside the nozzle orifices. Several studies have made use of transparent 48 geometries for this purpose, but many of them explored simplified geometries [12]–[15] 49 or were significantly limited in the maximum achievable injection pressure [16]–[18]. 50 Thus, Computational Fluid Dynamics (CFD) tools have been developed on the last 51 decades as a tool to get further insight in the relationship between the nozzle geometry, 52 the internal flow characteristics and the hydraulic conditions at the nozzle exit [19]–[22], 53 which are a necessary input for spray combustion models [23]–[26]. 54

55 The fuel physical properties (mainly density and viscosity) have a significant impact on the internal nozzle flow characteristics. Battistoni et al [23] compared the internal flow 56 and near-nozzle spray details for a standard diesel fuel and a soybean methyl ester (SME), 57 showing that the different viscosity among them severely impacts both the outlet mass 58 59 flow rate and the spray features. Similar conclusions about the effect of the fuel properties 60 have already been seen both experimentally and numerically for other kinds of biodiesel [27]–[31] and for winter fuel formulations [32]–[34]. Recently, a few authors [35]–[39] 61 62 have showed that it is important to consider not only the changes in the fuel properties 63 related to the fuel composition, but also those related to the different temperature and pressure conditions along the nozzle geometry, which are traditionally neglected. 64

In the current paper, an effort to understand the impact of compressibility effects on internal nozzle flow simulations at very high injection pressure (up to 250 MPa) has been performed. For this purpose, the fuel used for the study has been widely characterized at

different levels of temperature and pressure, producing the corresponding correlations for 68 the fuel density, viscosity and speed of sound. Then, the hydraulic behavior of the injector 69 has been determined in terms of injection rate and momentum flux for different levels of 70 injection pressure and backpressure. These results have been finally compared to internal 71 flow CFD simulations carried out with two strategies: constant fuel properties 72 (incompressible) and pressure-dependent fuel properties (compressible). This procedure 73 allows to quantify the differences obtained in the main flow parameters when 74 75 compressibility effects are considered compared to the more simple incompressible solution generally seen in the literature [15], [40], [41]. 76

The paper is structured in 5 sections. In section 2, the main experimental methodologies used along the study are described, together with the correlations obtained for the main fuel physical properties. Section 3 details the setup used for the internal flow CFD study, whose main results are depicted in Section 4. Finally, the main conclusions obtained from the work are drawn in Section 5.

82 2. EXPERIMENTAL TOOLS

83 In this section, the main experimental techniques used for the study are briefly described.

84 2.1. Nozzle geometry determination

For the current study, a solenoid-driven diesel injector with a 5-orifices convergent nozzle has been used. In order to perform the internal nozzle flow simulations, it is necessary to have all its geometrical details. To do so, a previously developed and validated silicone molding technique has been employed. The technique is based on the injection of the silicone on a semi-liquid state into the nozzle, once the needle has been removed. After a few hours, the silicone becomes solid and can be extracted, maintaining the internal geometry of the sac and the orifices. The mold is later inspected using a Scanning Electron
Microscope, determining the corresponding nozzle dimensions.

An example of the pictures obtained through this process can be seen in Figure 1, while more details on the experimental technique are available in [42]. Finally, the final geometrical values of the nozzle used for the study can be seen in Table 1. In this table, R_a and R_b are the rounding radii at the orifice inlet in the upper and lower side of the orifice, respectively; D_i , D_o and D_m are the diameters in the inlet, outlet and middle sections of the orifices; and *k*-factor is a parameter related to the nozzle orifice conicity, defined as:

$$k - factor = \frac{D_i[\mu m] - D_o[\mu m]}{10} \tag{1}$$

Since the nozzle orifices are significantly convergent (as it can be seen from its high value
of *k-factor*), low probability of cavitation formation inside the nozzle is expected [43],
[44]. Nevertheless, some cavitation could appear when very high injection pressures are
used. This will be further analyzed in Section 4.

104 **2.2. Fuel properties characterization**

As a first step, the main physical properties of the fuel have been measured under a wide range of pressure and temperature conditions. In particular, a standard European winter diesel fuel has been used. Density measurements were performed on a hydrometer, based on the ASTMD1298 procedure, while a standard viscometer was used to characterize the fuel viscosity. Finally, a custom-made facility was constructed to characterize the speed of sound. This facility was based on a standard common-rail system, onto which a long tube has been installed between the rail and the injector. On that line, two high-speed piezoelectric pressure transducers have been installed at two different positions. Once the injector is commanded and the injection event takes place, a pressure wave is generated inside the system. Knowing the distance between these two transducers, it is possible to characterize the speed of sound by measuring the time lapse that the pressure perturbation takes to travel to one sensor to another. More information about the experimental setup can be seen in [45].

Figure 2 shows the results from the fuel characterization for a range of 0.1-300 MPa in pressure and 300-400 K in temperature, which are representative of the usage of diesel fuel in advanced common rail systems. These data have been correlated as a function of pressure and temperature, finding the following relationships:

$$\rho_f = 826.5 - 1.0217(T - 298) + 1.251 \cdot 10^{-3}(T - 298)^2 + 0.6035(P - 0.1) - 8.27 \cdot 10^{-4}(P - 0.1)^2 + 1.44 \cdot 10^{-3}(P - 0.1)(T - 298)$$
(2)

$$\mu_f = 10^{-3} \,\mu_0 \cdot 10^{\left[\left(-1.48 + 5.86 \mu_0^{0.181} \right) \left(\frac{P - 0.1013}{1000} \right) \right]} \tag{3}$$

$$\mu_0 = 3.2158 \exp[0.0263(T - 298)] \tag{4}$$

$$a_f = 1350.6 - 3.1485(T - 298) + 4.4928(P - 0.1) - 6.96 \cdot 10^{-3}(P - 0.1)^2 + 7.4 \cdot 10^{-3}(P - 0.1)(T - 298)$$
(5)

122 Where ρ_f is the fuel density in kg/m³, μ_f is the fuel dynamic viscosity in Pa·s, μ_0 is the fuel 123 dynamic viscosity at 0.1 MPa of pressure, a_f is the speed of sound of the fuel in m/s, *P* is 124 the fuel pressure in MPa and *T* is the fuel temperature in K.

125

127 **2.3. Injection rate meter**

An IAV injection rate meter has allowed to determine the instantaneous mass flow rate delivered by the injector at different boundary conditions, summarized in Table 2. The technique is based on the Bosch method [46], which relates the instantaneous injected quantity to the pressure increase on a tube placed at the injector outlet. More details on the experimental arrangement and postprocessing procedure can be found in [47].

Figure 3 shows an example of the results obtained for a particular case of 180 MPa injection pressure (P_{inj}), 2 ms of energizing time (ET) and different levels of backpressure (P_b). The curve represents the instantaneous mass flow injected by the combination of the 5 nozzle orifices. As it is usual for the high injection pressure cases, the effect of the backpressure is only appreciable on the steady-state phase of the injection event. During this region, the mass flow rate through the nozzle corresponds to the following expression:

$$\dot{m} = C_d \rho_f A_o u_b = C_d A_o \sqrt{2(P_{inj} - P_b)\rho_f}$$
(6)

140 Where \dot{m} is the mass flow rate through the nozzle, C_d is the discharge coefficient of the 141 nozzle, A_o is the geometrical outlet area of the nozzle orifices and u_b is the theoretical 142 nozzle outlet velocity according to Bernoulli's equation. According to this expression, 143 and as it can be seen in Figure 3, higher backpressure values correspond to lower 144 stationary mass flow rates.

145 **2.4. Momentum flux test rig**

146 A dedicated test rig has allowed to obtain the momentum of the sprays produced by the 147 injector. In this rig, the fuel is injected on chamber filled with an inert pressure gas

(nitrogen in this case). A compound of a piezoelectric pressure transducer and a target is 148 placed perpendicular to one of the orifices of the fuel injector, at a distance of 5 mm. The 149 transducer is properly calibrated so that it can measure the impact force of the spray into 150 151 the target, which is then transmitted to the transducer. More details of the technique can be found in [48]. The experimental matrix for the momentum flux measurements, which 152 is a subset of the one already seen for the injection rate meter, is available in Table 3. In 153 154 this case, the maximum backpressure was limited to 7 MPa due to structural limitations of the test rig. 155

Figure 4 shows a schematic of the momentum flux experimental arrangement, together with an example of the results again for the $P_{inj}=180$ MPa case. The results seen in the figure are an average of the data coming from the 5 nozzle orifices.

159

160 **3. NUMERICAL SETUP**

Internal nozzle flow simulations have been carried out using a single-phase isothermal
flow solver in ANSYS ® Fluent ® v.17 [49]. Regarding the turbulence model, ReNormalization Group (RNG) k-ε model has been selected based on previous internal flow
simulation experiences [41], [50]. The geometry has been simplified to a 72° sector-mesh,
corresponding to a single nozzle orifice, in order to minimize the computational effort.
The mean orifice dimensions included in Table 2 have been used for this purpose.

Figure 5 shows the computational domain with a detail of the mesh structure in the orifice.
Constant pressure boundary condition is selected for the Inlet and Outlet boundary
conditions, with values equal to the experimental data at the fuel injector inlet and outlet

during the injection rate experimental campaign. Non-slip boundary condition is used forthe nozzle and needle walls.

172 Figure 6 shows the results for a mesh sensitivity study and the comparison between first and second order numerical schemes. This has been performed for an injection pressure 173 of 130 MPa and a backpressure of 7 MPa. The fuel properties (density and viscosity) have 174 175 been considered constant along the whole computational domain (incompressible 176 solution). From Figure 6, it can be observed that second order schemes reach the mesh independence for a relatively small number of cells (#208000), while first order numerical 177 schemes do not show mesh convergence for significantly higher number of cells 178 (#272000). Thus, in order to minimize the computational effort of the simulations, second 179 180 order schemes with the 208000 cells configuration have been selected for the study. This configuration leads to an overestimation in the experimental mass flow rate of 181 182 approximately 5.5%.

Using the previously determined mesh characteristics, all cases presented in Table 2 have 183 been run on a single processor Intel (R) Core (TM) i5-4460 CPU @ 3.20 GHz. The 184 simulations have been run on a steady-state solver, using two main convergence criteria: 185 first, all the residuals must be below 5.10-5; additionally, the average velocity at the 186 nozzle orifice outlet must reach stationary conditions with 1% tolerance. The simulations 187 are initialized with injection pressure and zero velocity in the internal fluid domain. Doing 188 189 so, and for the particular case of an injection pressure of 130 MPa and a backpressure of 190 5 MPa, the incompressible solver reaches convergence after 1778 iterations, leading to a total CPU time of 2421.7 seconds. For the same conditions, the compressible approach 191 192 takes 1860 iterations and 3059.9 seconds to converge, which represents an increase of the

computational effort of approximately 26%. Similar results on a relative basis areobtained for other operating conditions."

195

196 4. INTERNAL FLOW SIMULATION RESULTS

197 In the current section, internal nozzle flow simulation results will be analyzed comparing 198 two different strategies. First, the fuel properties are considered constant for the whole computational domain. For this purpose, density and viscosity are calculated at the 199 200 backpressure condition. Then, the equations described in Section 2 for the density, viscosity and speed of sound of the fuel are introduced into the solver by means of user-201 202 defined functions, in order to account for the fuel compressibility. For both cases, the 203 flow is considered isothermal with a temperature level of 298 K, which is the value existing at the fuel injector inlet during the experimental injection rate and momentum 204 205 flux measurements.

206 Figure 7 shows an example of the density and viscosity fields inside the nozzle for the 207 compressible configuration. As a consequence of the pressure evolution inside the nozzle, which will be later analyzed in Figure 8, the compressible solver estimates a variation of 208 around 100 kg/m³ in density and of around $8 \cdot 10^{-2}$ kg/m·s in dynamic viscosity along the 209 computational domain. These variations have a double impact: on the one hand, the 210 211 variations in the fuel properties are expected to induce significant changes in the nozzle outlet velocity and mass flow rate compared to the incompressible solution, as it will 212 analyzed in the next paragraphs; on the other hand, the variations of viscosity affect the 213 214 local Reynolds number, with consequences in the turbulent flow characteristics.

Figure 8 shows the comparison of pressure and velocity fields for the compressible and 215 incompressible solvers for the same condition analyzed in Figure 7. One of the first things 216 that can be highlighted is that even for this very high injection pressure, the minimum 217 218 computed pressure values inside the nozzle orifices (around 0.5 MPa) are always higher than the fuel saturation pressure. This means that this particular geometry would not 219 produce any cavitation thanks to the combination of high conicity and relatively high 220 rounding radii. Another significant difference is seen in the velocity fields. In the 221 222 compressible solution, higher fuel viscosity values are observed compared to the incompressible approach, where the viscosity is calculated at backpressure conditions. 223 For this reason, higher viscous dissipation appears, leading to lower velocities. This can 224 be easily perceived looking at the maximum velocity along the computational domain, 225 which is around 58 m/s lower for the compressible case. Additionally, both pressure and 226 227 velocity contours show smoother transitions along the computational domain when 228 including the flow compressibility effects.

The impact of the variation of the properties inside the nozzle over the hydraulic behavior 229 of the nozzle can be clearly observed in Figure 9. This figure compares the experimental 230 mass flow at the nozzle outlet with the simulation results obtained with and without the 231 compressibility equations enabled. In the case of the experimental results, the data 232 corresponds to a time average of the injection rate during its steady-state phase, where 233 the mass flow is not affected by the needle position, as it was introduced in Section 2. In 234 these results, the simulations tend to overestimate the mass flow for all conditions. At 235 236 relatively low injection pressures (30 MPa), the solution given by the compressible and incompressible approaches are relatively similar, since the range of variation of the fluid 237 properties is moderate. However, it is appreciable that the compressible solution is closer 238

to the experimental values, as it is more capable of representing the flow physics. As the
injection pressure increases, the compressible and incompressible solutions diverge,
reaching a maximum difference of approximately 5% in mass flow at the maximum
injection pressure tested (250 MPa).

Figure 10 shows the evolution of the discharge coefficient against the square root of the 243 244 pressure drop for both compressible and incompressible flow, together with the 245 experimental values. For all of them it can be seen how the discharge coefficient is highly dependent on the pressure drop along the nozzle at low $\Delta P^{1/2}$ conditions, while the 246 dependence is much smaller as the pressure drop increases. This behavior is due to the 247 248 impact of the flow regime on the discharge coefficient. At low injection pressures, flow 249 velocities are moderate and the flow is in transitional conditions between laminar and turbulent, for which the discharge coefficient is highly sensitive to the Reynolds number. 250 251 As the injection pressure increase, so does the velocity, the flow regime becomes fully 252 turbulent and the discharge coefficient is independent on the Reynolds number. Similar behavior has been repeatedly found in the literature for different orifice geometries [51]-253 254 [53]

Regarding the effect of compressibility, at low injection pressures both approaches clearly overestimate the discharge coefficient, although the compressible solution gives better results. The relatively high difference between model an experiments at these conditions may be due to uncertainties in aspects such as the nozzle geometry or the turbulence model. As the injection pressure increases, the importance of the flow compressibility ramps up, the compressible and incompressible solutions diverge, and it is clearly seen how the compressible flow solver is more capable to reproduce the experimental data,

while the incompressible solver maintains a deviation of approximately 0.08 in the absolute value of the discharge coefficient.

Figure 11 plots the hydraulic performance of the nozzle in terms of its effective outlet 264 velocity, calculated as the ratio between the momentum flux and the mass flow. For the 265 experiments, the time-averaged values at the steady-state phases of the injection rate and 266 267 momentum flux curves are considered. For the CFD calculations, the mass flow and 268 momentum flux values are integrated in the nozzle outlet section. It can be observed that the incompressible solution overestimates again the outlet velocity, while the values 269 obtained using the compressible flow approach are very similar to the experiments for all 270 271 the conditions tested.

272 Finally, Figures 12 and 13 show the mass flow and effective outlet velocity results 273 expressed as the percentage deviation to the experimental data. In both cases, it can be seen how this deviation tends to reduce when increasing the injection pressure. 274 Comparing the two simulation approaches, the compressible flow solution is around 5% 275 276 closer to the experiments in terms of mass flow. This fact points out the importance of an accurate reproduction of the fluid properties when trying to reproduce the hydraulic 277 behavior of a nozzle through simulations. Regarding the effective velocity, the results 278 pass from around 3% of overestimation in the high-pressure range for the incompressible 279 simulation to a 1% underestimation in the case of the compressible solution, while the 280 281 deviations are significantly higher for the constant-properties approach.

282 **5. CONCLUSIONS.**

In the current paper, an investigation of the compressibility effects on diesel nozzleinternal flow simulations has been performed. First, the fluid density, viscosity and speed

of sound have been characterized as a function of pressure and temperature on a wide 285 range of boundary conditions. Correlations of these properties have been estimated and 286 then implemented on ANSYS ® Fluent ® v.17. Later, the hydraulic behavior of a 5-287 288 orifices convergent nozzle has been characterized by means of mass flow rate and momentum flux experimental tests, exploring values of injection pressure up to 250 MPa. 289 From these results, the evolution of the mass flow rate, momentum flux and effective 290 291 outlet velocity at maximum lift conditions have been extracted. Then, these values are 292 compared to steady-state CFD simulations at two conditions:

- Incompressible flow: constant fluid properties.
- Compressible flow: fluid properties locally computed as a function of the flow
 pressure conditions.

The results from the compressible flow simulations show a variation of around 100 kg/m^3 296 in density and of around $8 \cdot 10^{-2}$ kg/m·s in dynamic viscosity along the nozzle geometry. 297 This implies a significant reduction of the uncertainties related to internal nozzle flow 298 299 simulations without significant impact in the computational effort. In particular, the 300 accuracy in the prediction of the mass flow rate improves around 5% when using the 301 compressible flow approach. Other flow characteristics such as the momentum flux and the effective outlet velocity, which are key inputs for spray models, also show a 302 303 significant improvement in accuracy.

304 ACKNOWLEDGEMENTS.

This work was partly sponsored by "*Ministerio de Economía y Competitividad*", of the Spanish Government, in the frame of the Project "*Estudio de la interacción chorro-pared en condiciones realistas de motor*", Reference *TRA2015-67679-c2-1-R*. The authors

308	would	d like also to thank the computer resources, technical expertise and assistance
309	provie	ded by Universidad de Valencia in the use of the supercomputer "Tirant". Mr.
310	Jaram	nillo's Thesis is funded by "Conselleria d'Educació, Cultura i Esports" of Generalitat
311	Valen	aciana in the frame of the program "Programa VALI+D para investigadores en
312	forma	ación, Reference ACIF/2015/040.
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488		combined effect of hydrogrinding process and inclination angle on hydraulic
489		performance of diesel injection nozzles," Energy Convers. Manag., vol. 105, pp.
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Tables

Orifice	Ra [µm]	Rb [µm]	Di [µm]	Dm [µm]	Do [µm]	k-factor [-]	Length [µm]
1	23	13	141	129	123	1.7	703
2	27	23	145	131	127	1.8	704
3	20	24	145	132	126	1.9	707
4	36	20	141	128	122	1.8	726
5	38	28	145	130	123	2.2	737

Mean Values	29±8	22 ±6	143 ±2.3	130 ±1.4	124 ±2.2	1.9 ±0.2	715 ±15
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7 Table 1. Nozzle geometric characteristics

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Injection Pressures [MPa]	Back-Pressures [MPa]								
30	0.5	1	3	5	7	9	11	13	15
80		1	3	5	7	9	11	13	15
130		1	3	5	7	9	11	13	15
180		1	3	5	7	9	11	13	15
250		1	3	5	7	9	11	13	15

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)	Table 2.	Text ma	trix for	mass flow	rate r	neasi	irem	ents.

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Injection Pressures [MPa] Back-Pressures [MPa									
30	0.5	1	3	5	7				
80		1	3	5	7				
130		1	3	5	7				
180		1	3	5	7				
250		1	3	5	7				
Table 3. Text matrix for Momentum flux measurements.									

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Figure captions.

- 508 Figure 1. Nozzle geometry determination.
- 509 Figure 2. Winter diesel properties as a function of pressure and temperature.
- 510 Figure 3. Mass flow rates at P_{inj} = 180 MPa and all back-pressures.
- 511 Figure 4. Momentum flux at P_{inj} = 180 MPa and all back-pressures.
- 512 Figure 5. Details of nozzle mesh.
- 513 Figure 6. Mesh sensitibity study for first and second order schemes.

- 514 Figure 7. Fields of density and viscosity obtained from CFD simulations (compressible 515 approach) for an injection pressure of 250 MPa and backpressure of 5 MPa
- Figure 8: Fields of pressure and velocity for compressible and incompressible solutions. $P_{inj} = 250 \text{ MPa}, P_b = 5 \text{ MPa}.$
- Figure 9. Experimental mass flow results compared to those of CFD calculations forincompressible and compressible approaches.
- 520 Figure 10. Experimental discharge coefficient results compared to those of CFD
- 521 calculations for incompressible and compressible approaches.
- Figure 11. Experimental effective injection velocity results compared to those of CFDcalculations for incompressible and compressible approaches.
- Figure 12. Mass flow deviation among experimental and modelled (incompressible andcompressible approaches)
- Figure 13. Velocity deviation among experimental and modelled (incompressible andcompressible approaches)
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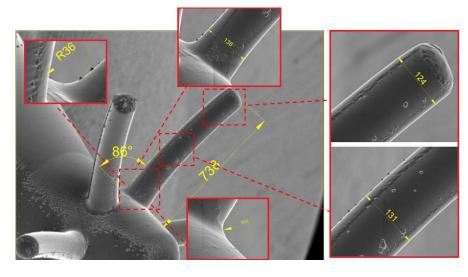


Figure 1. Nozzle geometry determination.

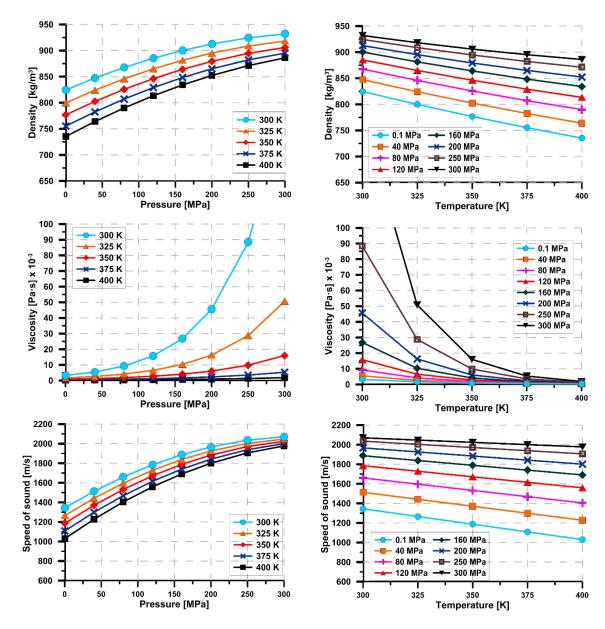




Figure 2. Winter diesel properties as a function of pressure and temperature.

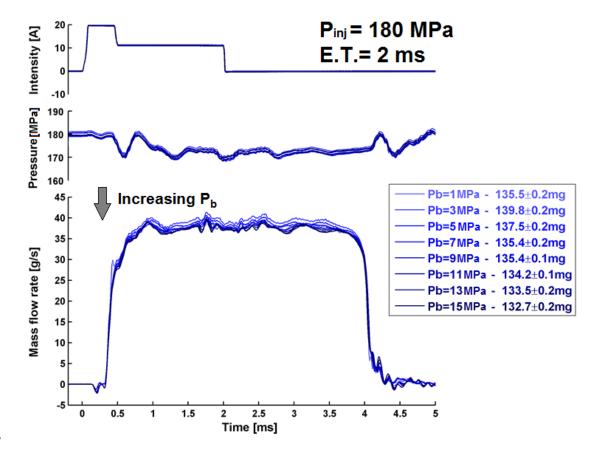




Figure 3. Mass flow rates at P_{inj} = 180 MPa and all back-pressures.

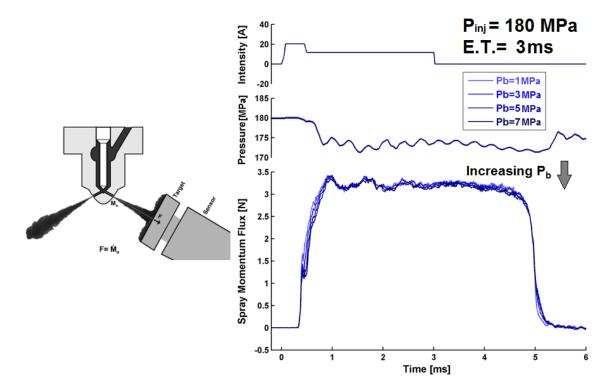
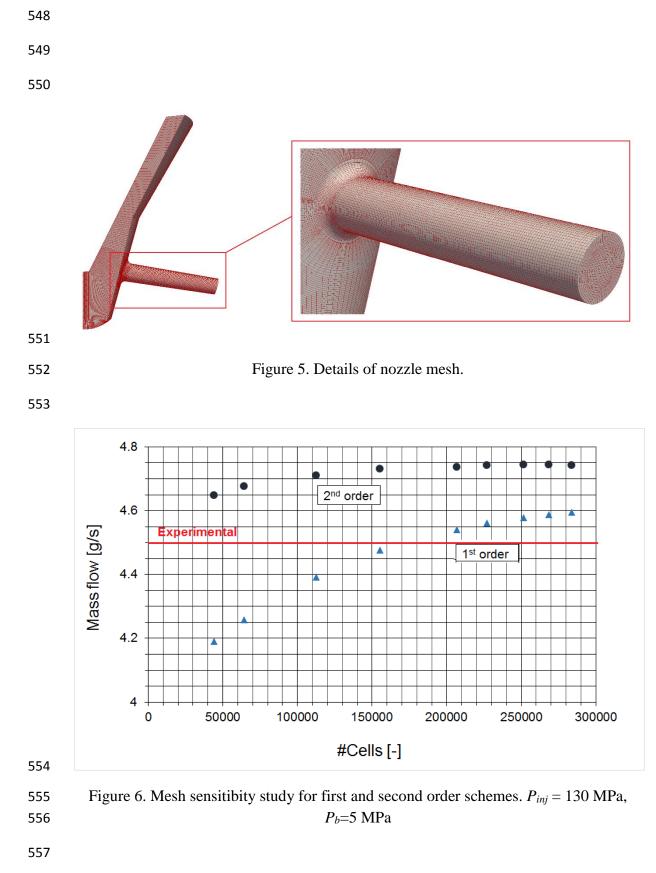






Figure 4. Momentum flux at $P_{\text{inj}} {=} \ 180$ MPa and all back-pressures.



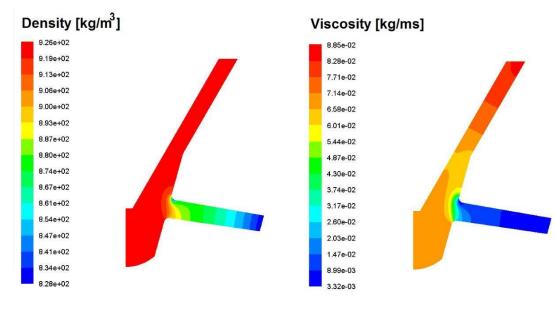
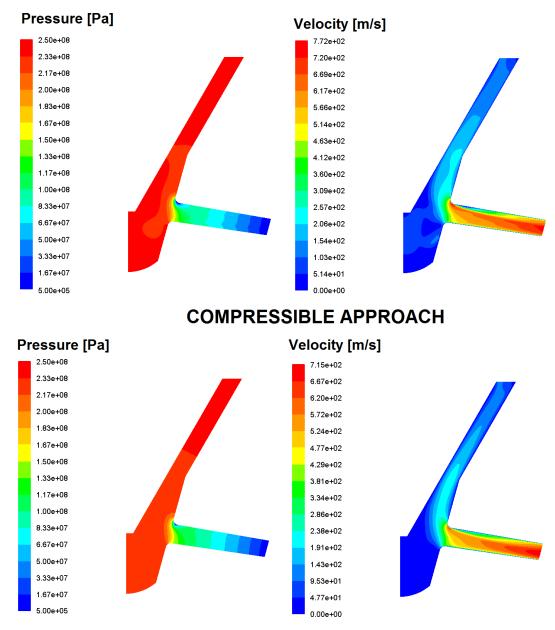
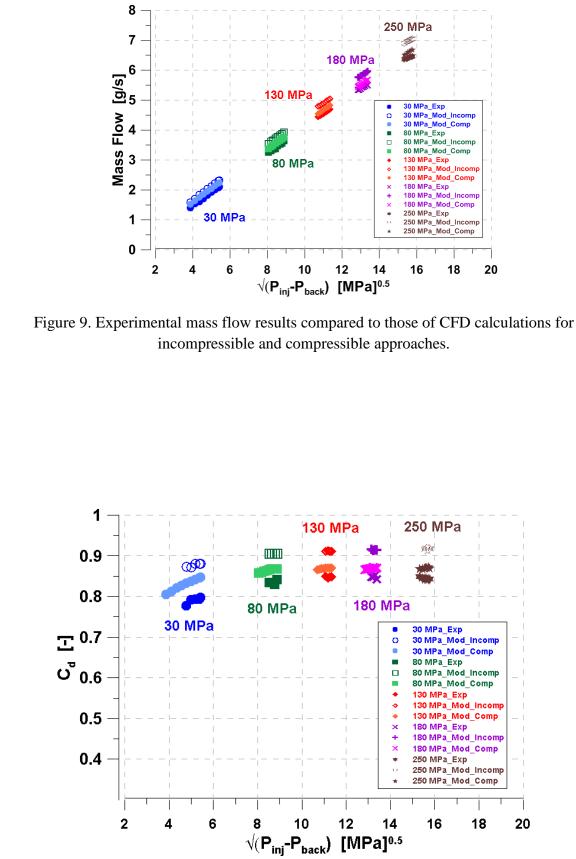


Figure 7. Fields of density and viscosity obtained from CFD simulations (compressible
approach) for an injection pressure of 250 MPa and backpressure of 5 MPa



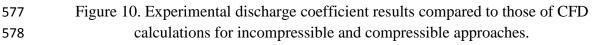
INCOMPRESSIBLE APPROACH

- 565 Figure 8: Fields of pressure and velocity for compressible and incompressible solutions.
- $P_{inj} = 250$ MPa, $P_b = 5$ MPa.









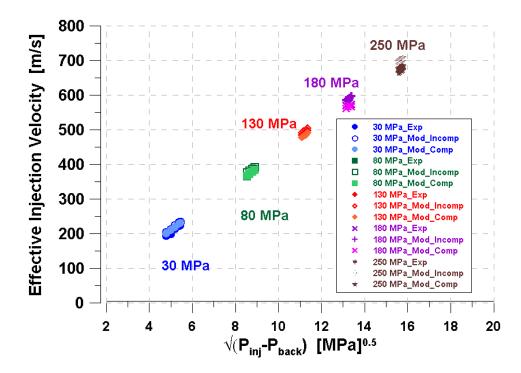


Figure 11. Experimental effective injection velocity results compared to those of CFD
 calculations for incompressible and compressible approaches.

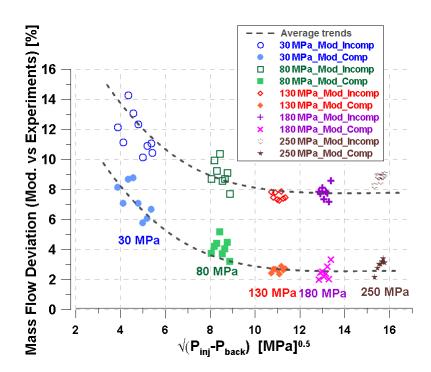


Figure 12. Mass flow deviation among experimental and modelled (incompressible and compressible approaches)

