



Final year project

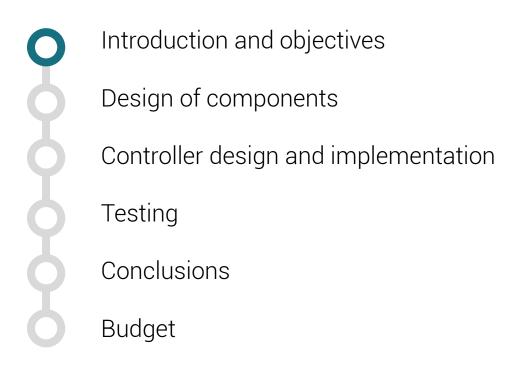
"Control of an electric propulsion system for a light aircraft

Author: Eva Maneus Salvador

Tutor: Ramón Blasco Giménez



Valencia, July 2018



Introduction & objectives

Problems

- Rise of fuel prices
- Increasing concern for pollution
- Industry at risk

Solutions

- Substitute by electric systems (MEA)
- Eliminate the need for fuel (AEA)

- Reducing fuel emissions
- Keeping the performance of the aircraft the same
- · Replacing the propulsion system of an already existing aircraft



Introduction and objectives

Design of components

Controller design and implementation

Testing

Conclusions

Budget

Design of components – Batteries and motor

Motor

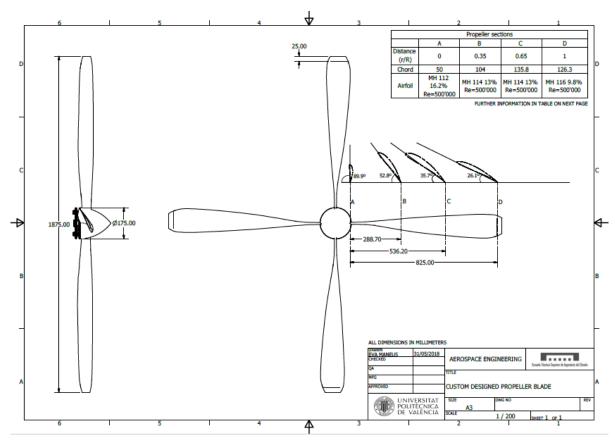
	Inductance,	PM magnetic	Nominal	Max. Angular speed,
Resistance, Rs (Ω)	Ld Lq (H)	flux, λm (Wb)	power (kW)	ωmax (rad/s)
(22)	(11)	(116)	(1447)	(rau/3)
0.0112	7.32 ·10-5	1.732	180	251

Batteries

Battery energy density (Wh/kg)	Batteries weight (kg)	Batteries energy (Wh)
(**************************************	(9/	(1111)
250	300	75000

Design of components - Propeller

N° of blades	Diameter	Chord	
IN OF DIAGES	(m)	Tip (mm)	Root (mm)
4	1.65	50	126.3





Introduction and objectives

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Implementation - Controller

$$u_{d} = R_{s}i_{d} + L_{d}\frac{di_{d}}{dt}$$

$$u_{q} = R_{s}i_{q} + L_{q}\frac{di_{q}}{dt}$$

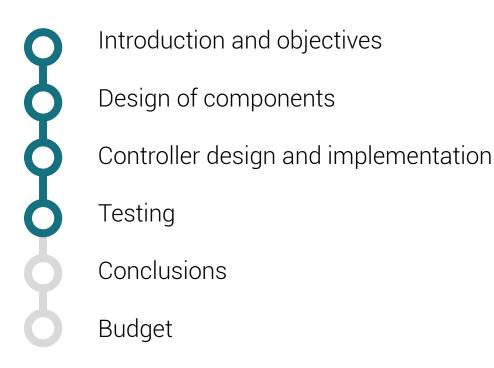
$$I_{d} = \frac{1}{R_{s} + sL_{d}}U_{d}(s)$$

$$I_{q} = \frac{1}{R_{s} + sL_{q}}U_{q}(s)$$

$$T_{m} = \frac{2}{3}p\lambda_{d}i_{q} = \lambda_{m}i_{q}$$

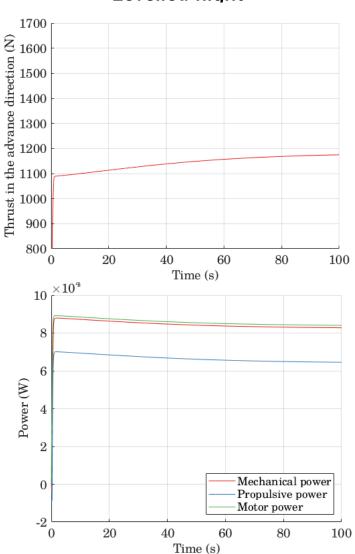
2 PI Controllers

Control	Response time	Settling time	Overshoot
parameter	(us)	(ms)	(%)
Isq	740	3.7	11.5
<u>lsd</u>	730	201	7.86

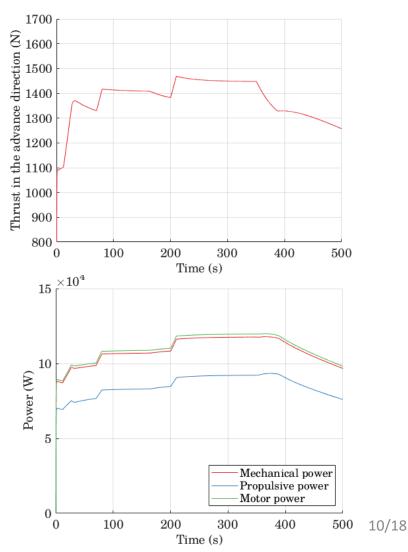


Testing - NORMAL FUNCTIONING



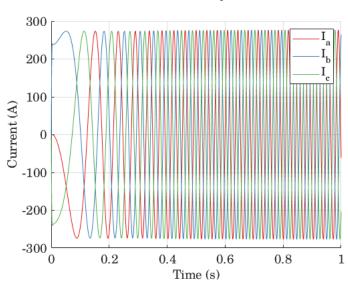


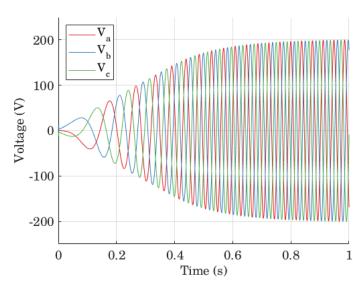
Flight with climbs and descents



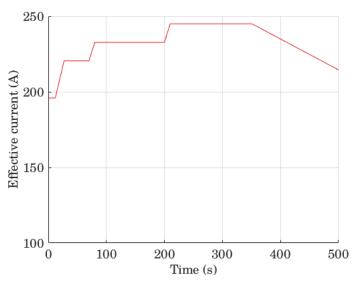
Testing - NORMAL FUNCTIONING

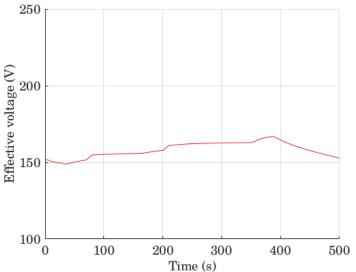
Levelled flight





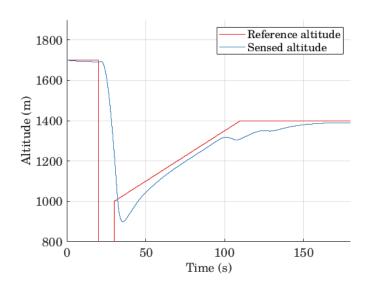
Flight with climbs and descents





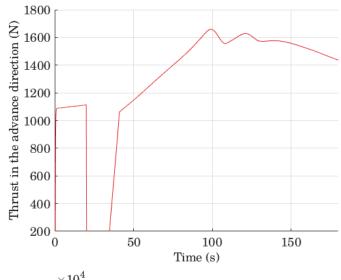
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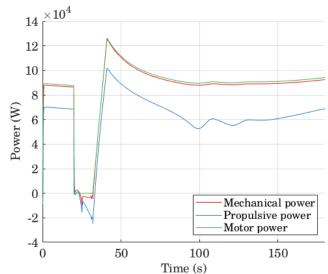
Testing - MOTOR FAILURE RECOVERY





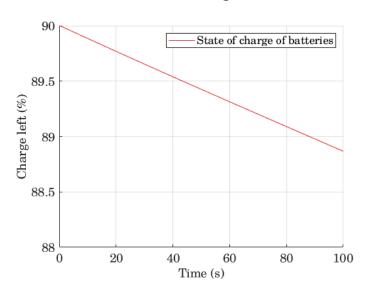
- Still does not reach maximum power
- Can recover





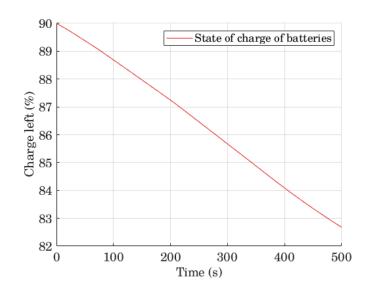
Testing - ESTIMATED AUTONOMY

Levelled flight

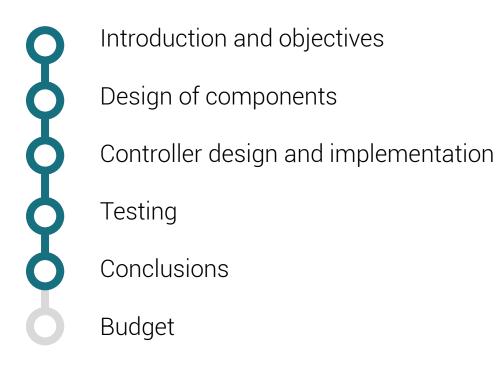


- Linear discharge
- Estimated: 106 minutes

Flight with climbs and descents



- Approximately linear
- Estimated: 80 minutes
- Lower autonomy than fuel counterparts

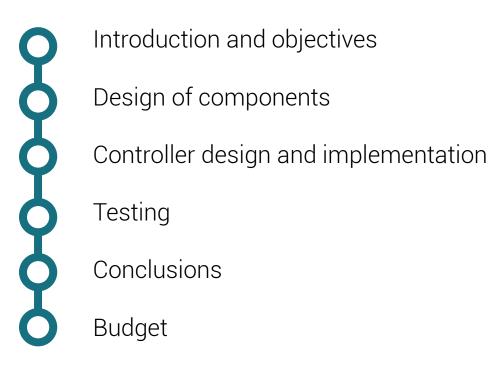


Conclusions

Lower autonomy

Lower cost per hour of flight

- Plausible for certain functions and missions. E.g.:
 - Pilot training
 - Airport surveillance



Budget

Concept	Amount (€)
Group 1	6658.90
Group 2	292.50
TOTAL	6951.40
General expenses (15%)	1042.71
Industrial profit (6%)	417.08
TOTAL	8411.19
VAT (21%)	1766.35
TOTAL	10177.54

Final year project

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Thank you for your attention



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