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Additional Information

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**Application of Multivariate Image Analysis for on-line Monitoring of a
Freeze-Drying Process for pharmaceutical products in vials**

Abstract

A new Process Analytical Technology (PAT) has been developed and tested for on-line process monitoring of a vacuum freeze-drying process. The sensor uses an infrared camera to obtain thermal images of the ongoing process and multivariate image analysis (MIA) to extract the information. A reference model was built and different kind of anomalous events were simulated to test the capacity of the system to promptly identify them. Two different data structures and two different algorithms for the imputation of the missing information have been tested and compared. Results show that the MIA-based PAT system is able to efficiently detect on-line undesired events occurring during the vacuum freeze-drying process.

Keywords: *multivariate image analysis; process monitoring; infrared image; batch process.*

24 1. Introduction

25

26 Vacuum freeze drying (VFD) is a highly attractive process for the water removal in thermal
27 sensitive products, mainly pharmaceutical ones, since water is removed at low temperature by
28 sublimation. Monitoring of critical quality attributes of the product, e.g. the residual amount
29 of ice and the product temperature, is required to guarantee a true quality-by-design
30 manufacturing. To achieve this goal, the development of suitable Process Analytical
31 Technologies (PAT), able to monitor/control the key variables of the process without
32 interfering with the process dynamics, is a mandatory step, as stressed also by the Guidance
33 for industry PAT by the American Food and Drug Administration [1].

34 In the past, many approaches to this problem, based on the measurement of different
35 process variables (e.g. product temperature, sublimation rate, heat flux to the product, among
36 the others), were proposed and tested [2], in particular at lab-scale. The measurement of the
37 temperature of the product, possibly in a well-defined position (e.g. the bottom of the vial),
38 was extensively and successfully applied for process monitoring and control [3]. The main
39 drawback, up to this moment, of this approach is that the temperature measurement has to be
40 performed using a thermocouple stuck into the product, and this does not guarantee neither
41 the sterility requirements nor that the sensor is not interfering with the ongoing process.

42 In this work we used an infrared camera, instead of a thermocouple, for temperature
43 measurement. Differently from the system proposed in the literature [4], we placed the
44 camera inside the chamber, thus being able to monitor the vials in several positions, and not
45 only on the top shelf of the freeze-dryer. Moreover, by this way it is possible to track vial
46 temperature along several axial positions, and not only at the top. **The spatial position of the**
47 **vials inside the drying chamber has been proved to have a dramatic effect on the variability of**

48 the product inside the single batch [5]; any monitoring algorithm, in order to be successful,
49 has to account for this source of variability. In this work this aspect has been deeply
50 investigated. Obviously, this system is able to monitor directly the temperature of the glass
51 wall, and not that of the product, but several studies appeared in the literature evidenced that
52 the temperature of the product is very close to that of the glass wall [6].

53 Thermal images include a lot of useless (i.e. everything that is outside the vial)
54 information and, also the one directly related with the process, i.e. the temperature, is highly
55 noisy, redundant and correlated. The first problem is a matter of gray-scale image
56 segmentation, whereas the second is a frequent problem when dealing with real industrial
57 data. Latent variables based multivariate statistical techniques can easily deal with these
58 kinds of problems. In this framework, Kourti [7] discussed the primary role of multivariate
59 statistical techniques in the development of PAT for the pharmaceutical industry.

60 Multivariate Image Analysis (MIA) is the application of multivariate statistics
61 methods to the extraction of information from images, both spectral [8], that is directly
62 related to the intensity of each pixel, and textural, i.e. linked to the spatial distribution of
63 intensity gradient [9]. Prats-Montalbán et al. [10] published a complete review of MIA
64 techniques and possible applications to problems of image segmentation, monitoring and
65 defect detection, classification and prediction. Application to hyperspectral images was also
66 discussed. Two different possible approaches to MIA were discussed: a global image
67 approach and a pixel level one. The latter treats the spectral information in each pixel as a
68 sample of the whole image, while, global image MIA is used when a set of features
69 describing certain characteristics of the image are extracted and used for classification and/or
70 prediction purposes. In this work, a global image approach was used.

71 The idea underlying the development of a latent variable multivariate monitoring

72 system is that only a few underlying events are driving the process, and all the measurements
73 we obtain are just a different sight on this underlying driving force. Multivariate Statistical
74 Process Control (MSPC) allows us to obtain a model of the process by projecting the
75 information into a low dimensional space defined by latent variables and, in this reduced
76 space, to build control charts able to detect any deviation from the normal operating
77 conditions [11]. Both principal component analysis (PCA) [12] and projection to latent
78 structures (PLS) [13] have been widely studied and applied for this purpose, being also able
79 to successfully deal with the highly auto-correlated data typical of batch processes [14-16]
80 such as VFD intrinsically is. Multivariate control charts for batch process monitoring were
81 proposed by Nomikos and MacGregor [17], while Kourti [18] presented a more general
82 discussion of MSPC of batch processes. Ramaker et al. [19] discussed the advantage of
83 conjugating these techniques with process specific information in a so called *gray model*. Van
84 Sprang et al. [20] presented a comparative evaluation of five different algorithms to the
85 problem of on-line batch process MSPC. Rato et al. [21][22] recently presented a systematic
86 methodology to compare batch process monitoring methods and compared different
87 approaches in terms of detection strength and speed.

88 In more recent years many successful applications of MSPC to real industrial
89 problems were published; a definitely not exhaustive list of them includes industrial polymer
90 batch process [23,24], a continuous recovery process [25], batch production of PVC [26],
91 fed-batch fermentation [27], autobody assembly [28] and continuous slurry stripping [29]. A
92 complete discussion of multivariate image analysis in the process industries was published by
93 Duchesne, Liu and MacGregor [30], including different examples of image analysis
94 application to MSPC and real-time process control and optimization [31].

95 This paper is thus focused on the design of a new Process Analytical Technology

96 (PAT) for on-line process monitoring in a VFD process. The sensor uses an infrared camera
97 to obtain thermal images and multivariate image analysis (MIA) to extract the information
98 after automatic detection and segmentation of the region corresponding to the product in
99 every vial. This information allows detecting on-line undesired events eventually occurring in
100 the batch.

101 The paper is organized in six sections: section 2 introduces the experimental work and
102 some useful nomenclature, section 3 deals with image preprocessing and feature extraction,
103 section 4 presents the MSPC scheme and the different approaches to two of the **major** issues
104 related to batch process MSPC (data unfolding and missing data estimation) tested, section 5
105 presents the main results, and section 6 the general conclusions of this work.

106

107

108 **2. Experimental study and nomenclature**

109

110 Drying experiments were carried out using a lab scale equipment LyoBeta 25TM freeze-dryer
111 (Telstar, Spain). In all tests ten vials (ISO 8362-1 10R) were placed at 30 cm from the
112 camera, and a new image was acquired every five minutes for 50h corresponding to almost
113 600 image acquisitions. The actual elapsed time from the beginning of the process was used
114 to report the results of continuous variables “sampled” by the sensor, while the progressive
115 number of the image acquisition was preferred to refer to the results of the calculation
116 performed by the algorithm on the single images.

117 The sensor, together with the infrared camera (FLIR A35), includes a HDTV **rgb**
118 **(upper or lower case letters)** camera. In this work, only the thermal images were used and will
119 be discussed. The data are stored into a microprocessor that can be accessed via wi-fi and

120 monitored in real time through a graphical user interface. A case in plastic material was
121 designed (IMC Services s.r.l., (upper or lower case letters) Italy) to resist and protect the
122 electronics from the low pressure, low temperature and high moisture level typical of the
123 drying chamber during the freeze-drying process [32].

124 The normal operating conditions (NOC) set was obtained processing 5 ml of a
125 solution 10% b.w. of sucrose (Sigma Aldrich, 99.5%) at -20°C and 20 Pa. Five batches were
126 processed in the same operating conditions, thus obtaining a total of 50 vials. Each vial in the
127 batches was assigned with a number referring to the position on the shelf as Figure 1A shows,
128 progressively increasing with the number of the batches. Batch 6 was intended to be another
129 NOC batch but, due to the vibrations of the equipment, the vial in position number 7 felt
130 down and was, for this reason, regarded as a fault, while the remaining nine vials were
131 considered successfully dried.

132 The detection ability of the system was evaluated in four additional batches. In batch
133 7 a breakage in the vacuum system have been simulated and, after 5 hours of drying, chamber
134 pressure was raised to 50 Pa. In batch 8 the shelf temperature was set to -10°C while in batch
135 10 a solution 5% b.w. of sucrose was used. Batch 9 aimed to prove the ability of the model to
136 detect faults affecting the single vials and, while shelf temperature and chamber pressure
137 were set to the NOC values, only four vials (corresponding to vials 81, 88, 89 and 90) were
138 filled with a 10% solution. For the remaining six vials the configuration was the following: a
139 piece of glass was inserted into two of them; another one was filled with pure water; one
140 more with the same 5% b.w. solution used for batch 10, and the remaining two with,
141 respectively, 2.5 and 7.5 ml of solution. Batches 11 and 12 are NOC batches included into the
142 test set and used only to assess the monitoring performance of the algorithm. Given the high
143 amount of time required to obtain a new batch these were assembled randomly by selecting

144 vials from the five batches that constitutes the training set (batches 1 to 5). The only
145 restriction imposed during selection was to preserve the position of the vial on the shelf (e.g.
146 vial 111, first vial in batch 12 was selected between the vials 1, 11, 21, 31 and 41), as it is one
147 of the variables studied in this work. Should we stress that this “simulated” NOC test data set
148 would give overoptimistic results? Table 1 resumes the number of the vials belonging to each
149 batch, the operating conditions tested and whether it was used to train the model or to test it.

150 The ratio between the pressure measurements obtained from a conductive Pirani
151 gauge and a capacitive Baratron manometer was measured on-line in every batch. This ratio
152 is greater than one when the ice is sublimating, while approaches the unitary value at end of
153 the primary drying [33]. For this reason it has been used to determine when the drying was
154 completed and as a comparison for the features extracted (see section 3) from the thermal
155 images.

156

157

158 3. Image segmentation and features acquisition

159

160 The thermal images are 256x320 pixels. The camera is equipped with a 63°x50° lens which
161 leads to a slight optical distortion, known as barrel effect. This second order deviation from
162 the ideal rectilinear projection can be compensated by remapping the pixels according to the
163 following equation:

164

$$165 \quad r_{new} = r_{old} + f \cdot r_{old}^2 \quad (1)$$

166

167 where r is the distance from the center of the image of a generical pixel and f a correction

168 factor (negative in this kind of optical aberration) depending on the distance between the
169 camera and the object [34]. Since in all our tests the same distance was used, this factor is
170 approximately constant and equal to -1.5.

171 After optical correction, the Hough transform [35] was used to detect the position of
172 the vials in the images, as shown in Figure 1B. Being known the diameter of the vials bottom
173 and the length of the line detected by the Hough transform we could infer the width of a
174 single pixel and, thus, as we know also the height of the vial, the height of the region to be
175 segmented, Figure 1C.

176 The whole portion of the image corresponding to the product into every vial was
177 segmented and, to study the evolution over time of the temperature distribution, the values of
178 mean, standard deviation (std), skewness and kurtosis of the temperature in this region were
179 calculated from the measured values. The results were collected into a three-dimensional data
180 structure using two approaches. In the first approach, in the following referred as vial-wise or
181 *VW*, each vial has been considered as a single observation, thus $\underline{\mathbf{X}}_1$ is an $I \times J \times K$ data
182 structure where I is the number of vials (fifty considering 10 vials in each one of the batches
183 included in the training set), J is the number of variables measured (mean, std, skewness and
184 kurtosis), and K is the number of time instants (six hundred). In the second approach, referred
185 as batch-wise or *BW*, also the position on the shelf was included among the modeled
186 variables, thus $\underline{\mathbf{X}}_2$ is a $B \times J^* \times K$ data structure, where B is the number of batches (i.e. **five in**
187 **the training set**), K is again the number of time instants while the variables (J^*) are forty,
188 corresponding to mean, std, skewness and kurtosis for each one of the ten positions that a vial
189 could occupy on the shelf.

190

191

192 4. Batch process monitoring

193

194 In both approaches the data structures were unfolded putting all the features extracted for a
195 single observation beside each other in order of time acquisition. This kind of unfolding
196 preserves the information on the single observation, beside capturing the cross-correlation
197 and the auto-correlation along time [16]. The final matrix obtained for the *BW* approach
198 $\mathbf{X}_2(B \times J^*K)$ has ten times more columns and ten times less rows of $\mathbf{X}_1(I \times JK)$, the unfolded
199 matrix obtained with the *VW* approach. After mean centering and scaling the unfolded data
200 sets \mathbf{X}_1 and \mathbf{X}_2 , a PCA model with, respectively, A_1 and A_2 principal components was built
201 using only the batches of the training set, that is, the 50 successfully dried vials included in
202 batches 1 to 5. The general structure of a PCA model is the following:

203

$$204 \quad \mathbf{X} = \mathbf{T} \cdot \mathbf{P}' + \mathbf{E} \quad (2)$$

205

206 where \mathbf{T} is the $I \times A_1$ (or $B \times A_2$) *score* matrix, \mathbf{P} is the $A_1 \times JK$ (or $A_2 \times J^*K$) *loading* matrix and
207 \mathbf{E} is the residual matrix, having the same dimension of the original matrix \mathbf{X} .

208 Only the batches included into the training set were used to build up the PCA model;
209 batches 6 to 12 were used for validation purposes [36]. Once the latent variable subspace is
210 known, unusual behaviors can be detected using two multivariate control charts built on the
211 following two statistics: Hotelling T^2 (T^2) and the squared prediction error (*SPE*), defined by
212 Equations 3 and 4, respectively. For each observation:

213

$$214 \quad T^2 = \sum_{a=1}^A \frac{t_a^2}{\lambda_a} \quad (3)$$

215
$$SPE = \sum_{c=1}^{KJ} e_c^2 \quad (4)$$

216

217 where t_a is the a -th score, λ_a its corresponding variance and e_c is the error obtained after
 218 predicting the measurement of variable c for a certain observation.

219 In on-line monitoring the SPE is computed only on the information measured at
 220 instant k , and for this reason it is called *instant SPE (SPEI)*:

221

222
$$SPEI = \sum_{c=1+(k-1)J}^{JK} e_c^2 \quad (5)$$

223

224 where JK becomes $J*K$ in the batch-wise approach. Nomikos and MacGregor [17] proposed
 225 to use the errors on a moving window of five instant measurements to compute the upper
 226 control limit (UCL) for this statistic. First guess UCLs for these charts were computed both
 227 empirically, that is taking the 99.5 % percentile of the actual values of both statistics obtained
 228 from the training set, and using their theoretical approximations, following the approach of
 229 Nomikos and MacGregor [17].

230 The percentage of time instants that a single statistic overtakes the UCL in NOC
 231 batches, is called Overall type I (OTI) risk, and should be close to the imposed significance
 232 level (ISL = 0.5%):

233

234
$$OTI = 100 \times \frac{Nf}{I_{NOC} \times K} \% \quad (6)$$

235

236 where Nf is the number of time instants that a single statistic overtakes the UCL for the

237 overall training set [38]. Notice that the number of vials I should be replaced with B , the
238 number of batches in the training set, in the BW approach.

239 Due to the limited number of batches available, a *one-batch-out cross-validation*
240 approach was used. It consists in removing in turn each batch (in case of the VW approach, all
241 the ten vials obtained in the same batch) from the training data set, build a PCA model using
242 the remaining training batches (vials), measure the actual OTI for the deleted batch (vials),
243 measure the average OTI after all iterations, modify, if needed, the UCLs by multiplying this
244 by a coefficient greater or lower than 1, and repeat the procedure, until the desired OTI is
245 achieved [37]. To evaluate the actual performance of the algorithm, the UCLs have been
246 manually retuned, i.e. the original ones (both theoretical or empiric) were multiplied by a
247 positive factor greater or lower than 1. To what extent this is already stated in the highlighted
248 text in yellow??

249 The main issue when dealing with on-line batch multivariate SPC is that at time k
250 ($k < K$) the future part of the trajectory of each variable j (or j^*) is missing and has to be
251 “filled in” [17]. Arteaga and Ferrer showed that among the different scores estimation
252 methods for future multivariate incomplete observations from an existing PCA model, the
253 most statistical efficient ones are those that estimate the scores for the new incomplete
254 observation as the prediction from a regression model: the so-called regression-based method.
255 Out of these methods, two are recommended: the *Trimmed Score Regression (TSR)* method
256 and the *Known Data Regression (KDR)* [39], [40]. These have been tested and compared in
257 this work.

258 Given a reference matrix of observations \mathbf{X} and its PCA decomposition $\mathbf{X} = \mathbf{T} \cdot \mathbf{P}' + \mathbf{E}$,
259 when a new partially unknown observation \mathbf{z} is available at time k , it can be written as $\mathbf{z}^T = [$
260 $\mathbf{z}^{*T} \mathbf{z}^{\#T}]$, where \mathbf{z}^* includes the first Jk (or J^*k) known values of \mathbf{z} and $\mathbf{z}^{\#}$ contains all the

261 values still unknown. This partition induces a partition also into $\mathbf{P}^T = [\mathbf{P}^{*T} \mathbf{P}^{\#T}]$ and $\mathbf{X} = [\mathbf{X}^*$
 262 $\mathbf{X}^{\#}]$, see Figure 2. Ferrer and Arteaga proved that $\mathbf{z}^{\#}$ can be estimated by the general formula:

263

$$264 \quad \hat{\mathbf{z}}^{\#} = \mathbf{S}^{\#\#} \times \mathbf{L} \times \left(\mathbf{L}^T \times \mathbf{S}^{**} \times \mathbf{L} \right)^{-1} \times \mathbf{L}^T \times \mathbf{z}^* \quad (7)$$

265

266 where \mathbf{L} is key matrix, different for each method of imputation used,,equal to the identity
 267 matrix \mathbf{I} ($K-k \times K-k$) for the *KDR* method, and to the partial loading matrix \mathbf{P}^* ($A \times K-k$) when
 268 the *TSR* method is used. Given the full covariance matrix \mathbf{S} obtained from the know data set
 269 \mathbf{X} , $\mathbf{S}^{\#\#}$ and \mathbf{S}^{**} are the partition induced by the separation in \mathbf{z} [39]:

270

$$271 \quad \mathbf{S} = \frac{\mathbf{X}^T \mathbf{X}}{n-1} = \frac{1}{n-1} \begin{pmatrix} \mathbf{X}^{*T} \mathbf{X}^* & \mathbf{X}^{*T} \mathbf{X}^{\#} \\ \mathbf{X}^{\#T} \mathbf{X}^* & \mathbf{X}^{\#T} \mathbf{X}^{\#} \end{pmatrix} = \frac{1}{n-1} \begin{pmatrix} \mathbf{S}^{**} & \mathbf{S}^{\#\#} \\ \mathbf{S}^{\#\#} & \mathbf{S}^{\#\#} \end{pmatrix} \quad (8)$$

272

273 The two regression methods were compared in terms of accuracy of the score estimation,
 274 accuracy of the prediction of the future observation and, indeed, the fault detection ability
 275 following the procedure used by Garcia-Muñoz et al. [41]. Three fundamental properties of a
 276 good predicted score matrix were checked: *orthogonality*, *coherence* and *stability*. The score
 277 predicted for each principal component must be orthogonal, thus the covariance matrix
 278 should be diagonal with the terms on the diagonal, in order to be coherent, arranged in a
 279 decreasing order. *Stability* means that the estimation of the score must be constant in time and
 280 equal to the true value, i.e. the one obtained at the end of the process when all the variables
 281 are known, also at the beginning of the batch when most of the matrix is missing. The future
 282 prediction sum of squares (*FPRESS*) and the future prediction mean square error (*FPMSE*),
 283 Equations 10 and 11, introduced by Garcia-Muñoz et al. [41] were used as a measurement of

284 the quality of the forecast of the unknow part of the trajectory of variable j , in observation i
 285 made at time instant k :

286

$$287 \quad FPRESS_k^{ij} = \hat{\mathbf{a}} \left(e_k^{ij} \Big|_l \right)^2 \quad (9)$$

$$288 \quad FPMSE_k^{ij} = \frac{\hat{\mathbf{a}} \frac{1}{l} \left(e_k^{ij} \Big|_l \right)^2}{\hat{\mathbf{a}} \frac{1}{l}} \quad (10)$$

289 **Quizá habría que indicar que FPRESS se calcula sumando los FPRESS^j para cada variable j .**

290 where $e_k^{ij} \Big|_l$ is the error made for each observation i at time instant k when forecasting the
 291 future part of the unknown trajectory of variable j , that is, the values corresponding to the
 292 data to be acquired from $k+1$ to K or, equivalently, for l from 1 to $K-k$. $FPRESS$ is the
 293 equivalent of a SPE calculated on the predicted part of the observation and represents a
 294 measure of global forecast accuracy. In the $FPMSE$ the error at each instant of time is
 295 weighted by the inverse of the distance to the current time sample giving back a measure of
 296 the local forecast accuracy at specific time instant k .

297 Finally, after the PCA model was created and the control limits tuned, **the monitoring**
 298 **performances of both T^2 and $SPEI$ control charts were compared by projecting the**
 299 **observations of the test set onto the reference model. At every time step, only the information**
 300 **known up to that time instant was used, the missing part of the observation was forecasted,**
 301 **with either the KDR or the TSR algorithm, thus simulating an on-line acquisition system. The**
 302 **occurrence of false positives and false negatives were investigated, together with the amount**
 303 **of time needed to perform the calculation on the whole data set of images.**

304

305 5. Results

306

307 Figure 3 shows the Pirani-Baratron pressure ratio trajectory (Figure 3a) compared with the 10
308 trajectories, one for each vial, described by the four variables: mean, std, skewness and
309 kurtosis of the temperature of the pixels corresponding to the product into the vials (Figure
310 3b, 3c, 3d and 3e, respectively) measured during the drying of one of the reference batches.
311 Average temperature shows a change of slope around 9 hours after the onset of the primary
312 drying stage, and an asymptotic behavior up to the thermal equilibrium. The standard
313 deviation (std), after a sudden decrease, grows up until a maximum reached at almost 9
314 hours; then, it slowly decreases again until reaching an almost constant value at 36 hours.
315 Both skewness and kurtosis show a maximum, followed by a local minimum around 9 hours.
316 An almost constant value is kept from 36 hours to the end. The local maxima (or minima, as
317 well as the change of slope in the mean temperature) seems to correspond to the first slope
318 change of the Pirani/Baratron pressure ratio. The constant values at the end indicates that the
319 thermal equilibrium has been reached, i.e. there is no more sublimation, thus the primary
320 drying is over. Significant differences in the thermal trajectories obtained in different tests
321 may reveal an abnormal heat transfer, that is an anomalous drying kinetic and a lower product
322 quality. The features extracted from the thermal images, although based on simple first order
323 statistics, contain some relevant information about the process required to perform a process
324 monitoring. Multivariate statistical techniques are, nevertheless, mandatory to deal with such
325 amount of noisy and redundant data.

326 In the *VW* approach , the reference model was created extracting 10 PC corresponding
327 to 93.6% of variance explained. In the *BW* approach, two or more principal components, give
328 back basically the same results. Thus, the reference model was built extracting two principal

329 components. Regarding the UCL for T^2 , there is a remarkable difference between the
330 theoretical and the empirical values, being the former always lower than the latter. The UCL
331 for *SPEI* computed with the theoretical distribution and the one obtained taking the percentile
332 of 99.5% are always very similar. After tuning the control limits, the obtained OTIs for the
333 *VW* approach with *TSR* and *KDR* were, respectively, 0.47% and 0.48% for *SPEI*, and 0.48%
334 and 0% for T^2 ; in the case of a *BW* data approach we obtained 0.47% and 0.47% for *SPEI*,
335 and 0.43% and 0% for T^2 . It was impossible to achieve a higher OTI in the case of T^2
336 simulated with *KDR* because the scores are straight and as the limits were relaxed the error
337 soon exceeded the ISL.

338

339 *5.1 Missing information algorithms comparison*

340 Figure 4 shows the evolution along time of the prediction of the score of the first principal
341 component for both *TSR* and *KDR* algorithms and both data unfolding approaches for the
342 training data set: 50 vials for the *VW* approach corresponding to 5 batches for the *BW*
343 approach. In both cases the scores predicted with the *KDR* algorithm are more stable during
344 the process and, except for the first few images of the *VW* approach, they are perfectly
345 constant and equal to the true values (i.e. the values obtained at the end of the batch). The
346 score predicted with the *TSR* algorithm asymptotically moves toward the true values, but
347 without completely reaching them. In both cases the coherence of the score covariance matrix
348 was respected, that is the variance explained by the scores of the first component is greater
349 than that of the second component and so on, but the full orthogonality of the scores was
350 obtained only applying the *KDR*. A diagonal matrix was obtained from the first instant of
351 time in case of a *BW* approach and after the first 15 images in the *VW* approach.

352 After the scores were computed, an estimation of the original data matrix \mathbf{X} could be

353 obtained by multiplying the score matrix and the transpose loading matrix; subtraction of this
354 estimation from the original data matrix gives back the forecast error of the future (unknown)
355 part of the trajectory of all the variables in observation i made at each time instant k . From the
356 final $K-k$ columns, the values of $FPRESS$ and $FPMSE$, shown in Figure 5 and 6, were
357 obtained. As expected, being a global estimation of the prediction error, $FPRESS$ always
358 decreases with time, while $FPMSE$, that accounts for the local forecast accuracy, could
359 increase, decrease or, as in this case, keep an almost constant (except for generalized
360 increment towards the end) value. To ease the comparison among the different algorithms, a
361 darker line with symbols, representing the mean value of the trajectories, has been reported.
362 In Figure 5, corresponding to VW approach, the mean $FPRESS$ shows a maximum of 26 at k
363 $= 3$ for TSR , while the maximum for KDR is 135 and is located at the fifteenth data
364 acquisition. This five-time difference is kept through all the process and the mean value for
365 TSR also goes faster to zero. A slighter difference can be noticed also in the $FPMSE$, with the
366 TSR always behaving moderately better. Same conclusions can be stated from the analysis of
367 Figure 6, corresponding to BW approach. In this case $FPRESS$ is one order of magnitude
368 greater than in the VW approach while $FPMSE$ is basically constant.

369 KDR seems to give back a more stationary prediction of the scores, while the TSR
370 algorithm better forecasts the original value of the observations. The larger the number of
371 columns included in the unfolded data set, the higher the prediction errors are.

372

373 5.2 Classification performance - VW approach

374 Once a PCA model of the process has been fitted using the observations included in the NOC
375 batches and the UCL for both $SPEI$ and T^2 have been tuned in order to have an OTI closed to
376 the imposed ISL of 0.5%, we can evaluate the ability of this model to discriminate a fault

377 from a successful drying. The classification performance of this monitoring system has been
378 evaluated by projecting the whole test set on the obtained model. **At each time step, only the**
379 **measurements available up to that instant were used while missing part of the observations**
380 **was forecasted with the algorithms just discussed, thus simulating a real on-line monitoring**
381 **system.** Tuned empirical limits performed slightly better than the theoretical ones and have
382 been used. This could be due to the fact that taking the percentile of the actual distribution of
383 the statistics helps to better follow the instantaneous variation of the distribution itself and
384 better describe the little misbehavior that could occur.

385 The control chart for *SPEI* is almost the same in both cases while the T^2 control charts are
386 quite different especially at the beginning. Using the *trimmed score regression* algorithm,
387 while tuning UCLs, the control charts for *SPEI* detected 8 false positives vials in the training
388 set (8, 9, 15, 16, 19, 31, 40 and 50). Comparable results have been obtained with the *known*
389 *data regression* method; *SPEI* detected 7 false positives (vials 1, 6, 9, 15, 41, 50, 54) in the
390 training data set. Looking at the vials that appeared as false positives in *SPEI* (they are 1, 6, 8,
391 9, 15, 16, 40, 41, 50 and 54) we can notice a certain periodicity in the results. Position 1 and
392 10 in every batch corresponds to the external vials, directly radiated by the chamber walls. In
393 the first two batches a thermocouple was located inside the vials in position 5 and 6, see
394 Figure 1. This slight difference into the data structure of vials 6, 15, 16 might be due to the
395 influence of the thermocouple on the drying kinetics.

396 These observations mildly overtake the control limits on a limited number of time instants.
397 If we accept these spurious errors as part of the unavoidable statistical error rate, that is, we
398 assume that the phenomena responsible for these instantaneous faults cannot jeopardize the
399 quality of the resulting product, the fault detection performance could be further optimized.
400 This new relaxation of the control limits was achieved by considering faults only the vials

401 whose *SPEI* crossed the control limits in more than 5% of the time instants. In this way all
402 the false positives in *SPEI* were properly classified as successful tests.

403 The validation of the obtained model was performed by projecting all the vials of the test
404 set onto the obtained model step by step simulating a real-time acquisition. Figure 8
405 compares the control charts obtained with the different algorithms for three vials:

- 406 - number 105, a NOC vial, always below the UCL;
- 407 - number 51, a vial expected to be in control but reported as a fault in the *SPEI* control
408 charts;
- 409 - number 75, dried at a higher shelf temperature and lies over the control limits in all cases
410 almost all the time.

411 Vial 57, as well as all the vials of the anomalous batches 7, 8 and 10 were detected as
412 faults. In batch 9 six vials were tampered and all of them have been correctly
413 discriminated. The T^2 control chart reported nine false negatives and two false positives
414 (vials 52 and 56). Only one of the four vials of batch 9 dried with the original 10% sucrose
415 solution (vial 81) has been correctly found to be a successful drying test. Vials 88 and 89
416 and 90 have been highlighted as faults by the T^2 control chart. **This results are from TSR?**

417 Using the *KDR* algorithm four false positives were highlighted into batch 9 together
418 with vials number 51, 52, 56, 58, 60. The T^2 control charts detected vials 51 to 60 (the whole
419 batch number 6) and 81, 88 and 90 as false positives but no false negatives.

420

421 The anomalous behavior of vials 51, 60, 81 and 90 appears to prove what has been
422 stated about the effect of the radiation from the surrounding. The appearance of vials 56
423 could be due to either the effect of the thermocouple used also in this batch, or to a greater
424 amount of radiation from the surrounding due to the absence of vial 57 after it fell down. A

425 possible explanation of the anomalous behavior of some vials in position 8 and 9 the
426 presence of the cold led, required for the illumination of the rgb camera field of view, right in
427 front of them.

428 In general, we could state that the *trimmed score regression* algorithm gives back a
429 better *SPEI* control chart, probably because of the lower error in the estimation of the
430 variables, while the *known data regression* algorithm gave back better T^2 control charts,
431 which could be a direct consequence of the better score estimate we discussed. The *KDR*
432 requires 13 times the computational time required for a simulation using the *TSR*.

433

434 *5.3 Classification performance - BW approach*

435 Since we segmented and extracted features from each one of the different vials in the images,
436 the most natural way to treat the data was the vial-wise approach. The idea to organize the
437 data including the potential effect of the vial position on the shelf was conceived when we
438 noticed the periodicity in the results just discussed in the previous subsection. There is also a
439 matter of variables and matrix dimension, i.e. in the *BW* approach we have only 5 batches,
440 but for each image we obtain forty new columns and the resulting matrix is ten times wider
441 than the *VW* one. The computational time required was 28 times greater when *TSR* is used
442 and lasted almost 10 days (instead of a few minutes) with the *KDR*. In this last case (use of
443 the *KDR* algorithm for a matrix organized taking the single batch as an observation) the time
444 required for the analysis of a single image is greater than the 5 minutes required for each data
445 acquisition, thus jeopardizing the possibility of a real time application of the algorithm. After
446 matching the desired OTI, both *TSR* and *KDR* presented three false positives (batches 3, 4
447 and 5) in the *SPEI* control chart; the three batches of the training set that had no
448 thermocouples inside the central vials. Again, a 5% threshold was set to correctly

449 discriminate the false positives in the *SPEI*, although just raising the control limits would
450 have fit the purpose.

451 As for the *VW* approach, we tested the behavior of the monitoring scheme by
452 projecting all the batches of the test set on the plane defined by the two principal components.
453 Also in this case tuned empirical limits performed better and were preferred.

454 Figure 8 shows the control charts of both *SPEI* and T^2 for three of the seven batches
455 that constitute the test set. Batch 12 was always perfectly classified by both algorithms, batch
456 8 was always clearly signaled as an outlier, and batch 10 was detected only by the T^2 control
457 charts.

458 Neither false positive nor false negative were detected with both the *TSR* and the *KDR*
459 by the *SPEI* control charts. No false positive were detected in the T^2 control charts when
460 using either the *TSR* or the *KDR* algorithm. In both cases only batches 6 and 8 were detected
461 as faults. Even after the limits in the T^2 control chart were retuned, it was impossible to set
462 apart the faulted batch 7, 9 and 10 from the NOC data set.

463 These three batches have a common characteristic: they all simulated faults mainly
464 concerning the mass transfer. In the VFD process mass and heat transfer are intimately
465 coupled that is, any deviation in the mass transfer affects also the evolution of the
466 temperature profiles in the products, but it will always be an indirect and weaker effect.
467 Being a weaker effect, also the breakage into the correlation structure of the data will be less
468 pronounced. Moreover, the glass of the vials is almost opaque to infrared radiation
469 (emissivity 0.9) thus, the temperature we measure is that of the vial wall. The two values
470 were proved to be quite similar, but it might partially mask some slight variation in the
471 thermal history of the product. The effects on the heat transfer are strong enough to be read
472 by the *SPEI* chart, but not to raise an alarm into the T^2 chart. On the other side, in batch 6 a

473 vial felt down, and the camera measured the temperature of the front door of the dryer, which
474 is warmer than a normal vial and almost constant during the whole process. This single vial
475 misbehavior was strong enough to completely compromise the data structure. In batch 8 the
476 whole shelf was set at a higher temperature. Thus, also the glass of the vial, which is always
477 in contact with the shelf, is directly heated and both the average temperature as well as the
478 whole temperature distribution change. This direct effect is strong enough to be detected also
479 by the less responsive of the control charts.

480 This lower detection ability of the T^2 control charts in batch processes monitoring has
481 already been reported in the literature and is basically due to the strong auto-correlation in the
482 data [38].

483 As the position of the vial on the batch is, in this approach, part of the model, any
484 harmful effect of the position should be highlighted into the contribution plot. In Figure 9 we
485 reported the contribution plots of batch 6 (a), 8 (b) and 11 (c), respectively, for *SPEI* when
486 *TSR* is used, after 6.7 hours of drying. Batch 11 is the reference, a good batch correctly
487 discriminated (note the small value of the contributions). In case of batch 6 the bars
488 corresponding to the variables in position 7 (variables 25 to 28) are three orders of magnitude
489 greater than the others as well as those of batch 11 (I can't see it!), denoting that something in
490 that vial is going wrong. In batch 8 all the forty variables are higher than expected,
491 betokening an unconventional processing.

492

493

494 **6. Conclusions**

495

496 In this work a PAT for MIA based real time monitoring of vacuum freeze-drying has been

497 developed and tested. The sensor uses an infrared camera to get thermal images of the
498 ongoing process. These images are segmented, after optical aberration correction, and global
499 features of these regions are extracted and used to detected unusual behavior in the new
500 observations.

501 Two different approaches of data unfolding and missing data estimation have been
502 tested and compared, with the aim to obtain the best combination for addressing the problem
503 at hand. The *TSR* algorithm appears to better forecast the missing values and this gives back a
504 slightly more responsive *SPEI* control chart. On the other side, the *KDR* algorithm better
505 estimates the scores of the future observation that ensures better, although non-optimal,
506 performances of the T^2 control chart. In any case the nature of batch data makes the T^2
507 statistics not reliable. The main drawback of the *known data regression* algorithm is the time
508 required for the data analysis, basically due to the need to invert the partial covariance matrix
509 of the training data set (S^{**}), whose dimensions increase in time and is normally very ill-
510 conditioned. For matrix with a great number of columns, the long time required jeopardizes
511 the possibility to apply this algorithm on-line.

512 Both modeling approaches guarantee a fine fault detection. In a *BW* approach,
513 detection of a fault related to a single vial is deputed to the analysis of the contribution plots,
514 and thus less immediate. Using the single vials as an observation, the algorithm is more prone
515 to type II (false negative) errors since the effects related to the spatial position of the vial on
516 the shelf are not included in the model and could mask a deviation of the same amplitude in
517 the control charts; although we did not face this kind of problem. Given the lower number of
518 columns, the computational time is dramatically lower in this second case.

519 This PAT could be used to assess whether the variation of freeze-drying process is
520 only due to common causes, that is the process is in statistical control, or some special cause

521 might affect the product quality. Since this information is available on-line it might strongly
522 reduce the failure rate of the process, the waste production, the laboratory tests to be
523 performed at the end of the batch, and the time required from the end of the process to the
524 release of the batch. Anyway, **before considering any industrial application, the algorithm**
525 **developed should be, indeed, validated on larger industrial data sets.**

526 The performance of this algorithm could be further improved including in the data set
527 other variables available and currently measured during the process, especially those directly
528 related with the mass transfer inside the chamber (e.g. chamber pressure, vapor flow, etc.).
529 Future works will aim to prove the possibility to apply other multivariate techniques and the
530 infrared imaging technology for process optimization and control.

531

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