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Additional Information

Analysis of the effect of out-of-phase biaxial fatigue loads on crack paths in cruciform specimens using XFEM

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Abstract

In the present research work, a numerical crack growth analysis using linear elastic fracture mechanics is carried out paying attention to the crack paths that grow in the central part of cruciform specimens under biaxial fatigue loads. The crack propagation in this type of specimens has been studied using the extended finite element method (XFEM). The objective is to analyse the effect of different phase angles under biaxial fatigue loads and to assess the different orientation criteria for nonproportional loading, benefiting from the advantages of XFEM. The crack path and the stress intensity factor range of a crack either aligned or inclined to the load directions have been investigated using different crack orientation criteria. Symmetrical branching is predicted for an initial crack inclined at 45° with phase angle of loading equal to 90° and 180°. The numerical results are in good agreement with the experimental observations found in the literature, although the study reveals important differences in the crack path predictions depending on the orientation criteria.

<u>Keywords</u>

XFEM; cruciform specimen; biaxial fatigue loading; crack paths

1. Introduction

Multiaxial stresses can be found in many engineering structures, for example in the automotive or aeronautical industry. Furthermore, fatigue has been identified as responsible of a large amount of structural failures [1]. The biaxial stress state is one of the most studied cases since it is found on the surface of many mechanical components, where crack initiation usually takes place [2]. Thus, the scope of this study has been limited to a biaxial stress state under pure mode I, pure mode II and mixed mode (I+II) of fracture mechanics. During last decades, the development of new fatigue testing machines has allowed to investigate different biaxial loading paths (in-phase, out-of-phase, different frequencies, variable amplitude, etc.) in different engineering materials [3–7]. Tubular [8], solid cylindrical [9] or cruciform specimens [7] are the most common specimens that have been analyzed in the literature [10].

Under proportional fatigue loading, a crack may propagate either co-planar or at a certain deviation angle, mode I or mode II controlled (either perpendicular to the maximum normal stress or governed by the maximum shear stress) depending on the material and type of loading [11]. Due to the proportionality of loads, directions of maximum normal and shear stresses are kept constant with time, and therefore the crack growth direction can be easily ascertained.

Under non-proportional mixed mode I+II, a crack can either grow co-planar (mode I or mode II controlled), or propagate at a certain deviation angle or branch in different cracks [4,12]. Co-planar crack growth has been reported for cracked cruciform specimens under equibiaxial and in-phase loading in several works found in the literature [3,13–17]. In addition, symmetric crack branching (crack bifurcation) from an initial crack 45° inclined to the loading axis has been reported in cracked cruciform specimens under out-of-phase loading conditions [3–5,18]. Furthermore, it has been shown that nonsingular terms have no significant influence on crack deflection in cruciform specimens. However, non-singular terms, as the T-stress, are good predictors of crack stability [6].

The objective of the present work is to analyse numerically the effect of different phase angle of loading and initial crack inclinations on the predicted crack path under biaxial fatigue loading, benefiting from the advantages offered by XFEM simulations. With this aim, different criteria for nonproportional loading found in the literature are compared. Finally, the effect of the displacement ratio and phase angle of loading on the crack orientation is assessed for the first crack growth step.

2. Materials and methods

2.1. Cruciform specimen and initial crack geometry

A symmetrical cruciform specimen is employed for the biaxial study, as is shown in Fig. 1. The specimen geometry is in accordance to the international program NESC [19,20]. A centred initial crack either aligned or inclined to the load directions is located at the centre of the specimen. The inclination angle values examined are $\beta=0^{\circ}$, 15°, 30° and 45°, and the initial crack length (2*a*) is 36mm.

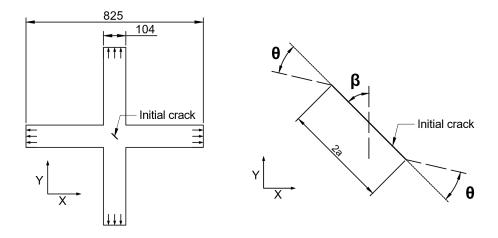


Figure 1: Sketch of the cruciform specimen problem with a centred crack and definition of initial inclination angle (β) and local angle of propagation (θ).

2.2. Loading

Loads are controlled by prescribed displacements U_x and U_y applied to each of the specimen arms. In all loading cases studied, the maximum displacement applied to both arms is kept constant and equal to 0.076mm. In addition, the same displacement ratio between the minimum and maximum displacements (U_{min} and U_{max}) prescribed in a cycle (Eq. 1) and frequency are set for both arms. Displacement loads are defined according to Eqs. (2) and (3), being δ_{xy} the phase shift angle, *T* the time period, U_m the mean displacement and U_a the amplitude displacement:

$$R_{dx} = R_{dy} = \frac{U_{min}}{U_{max}} \tag{1}$$

$$U_x = U_m + U_a \cos\left(\frac{2\pi t}{T}\right) \tag{2}$$

$$U_y = U_m + U_a \cos\left(\frac{2\pi t}{T} + \delta_{xy}\right) \tag{3}$$

Numerical crack paths are obtained with a phase angle of 0°, 90° and 180° and a positive displacement ratio R_d of 0.1 in order to minimize crack closure effects. The loading cases considered are shown in Fig. 2. When δ_{xy} is 0°, loads are in-phase, and the loading path is a straight line with slope equal to 1. Thus, the biaxiality ratio keeps constant during the cycle and the case is clearly proportional.

When δ_{xy} is 90°, loads are out-of-phase, and the loading path is a circle with centre at (Um, Um). When δ_{xy} is 180°, loads are again out-of-phase and the crack path is a straight line with a slope of -1.

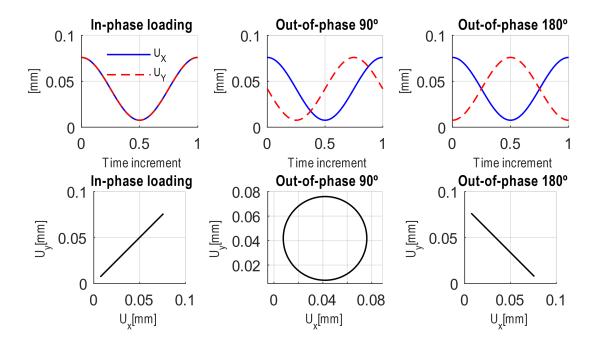


Figure 2: In-phase and out-of-phase 90° and 180° loading paths applied with $R_d=0.1$ and $U_{max}=0.076$ mm.

2.3. Numerical model

An Abaqus implementation of the extended finite element method (XFEM) [21] is employed to model crack propagation. Thus, the mathematical discontinuity introduced by means of XFEM enables the crack growth simulation without the necessity of remeshing. Inertial effects are not taken into account, and a quasi-static analysis is performed. A small scale yielding condition is assumed at crack tip. The material behaviour is taken as elastic, with E=206 GPa and v=0.3, under a plane strain condition. The mesh element size is 0.5 mm at the specimen centre.

The crack is successively propagated as follows. First, stress intensity factors (SIFs) are calculated using the domain independent interaction integral for each crack tip (further details can be found in [21]). Then, a fatigue crack propagation criterion is applied, and the crack is extended 1.25 mm in the predicted direction. The mesh and crack extension sizes have been analyzed previously in order to optimize the computational cost and accuracy of the results.

2.4. Fatigue crack propagation

In two-dimensional linear-elastic fracture mechanics and under mixed loading conditions that vary with time, the stress state governed by K_{I} and K_{II} corresponding to the singular term at crack tip in polar coordinates (r, θ) is given by [22]:

$$\sigma_{\theta\theta}(t,\theta) = \frac{K_{\mathrm{I}}(t)}{\sqrt{2\pi r}} \left[\frac{3}{4} \cos\left(\frac{\theta}{2}\right) + \frac{1}{4} \cos\left(\frac{3\theta}{2}\right) \right] + \frac{K_{\mathrm{II}}(t)}{\sqrt{2\pi r}} \left[\frac{-3}{4} \sin\left(\frac{\theta}{2}\right) - \frac{3}{4} \sin\left(\frac{3\theta}{2}\right) \right]$$

$$\tau_{r\theta}(t,\theta) = \frac{K_{\mathrm{I}}(t)}{\sqrt{2\pi r}} \left[\frac{1}{4} \sin\left(\frac{\theta}{2}\right) + \frac{1}{4} \sin\left(\frac{3\theta}{2}\right) \right] + \frac{K_{\mathrm{II}}(t)}{\sqrt{2\pi r}} \left[\frac{1}{4} \cos\left(\frac{\theta}{2}\right) + \frac{3}{4} \cos\left(\frac{3\theta}{2}\right) \right]$$
(4)

The trigonometric functions in Eq. (4) can be found in any basic book of fracture mechanics, e.g. [23]. After multiplying Eq. (4) by $\sqrt{(2\pi r)}$, the stress field expressions are modified in such a way that the influence of *r* is cancelled:

$$k_{\mathrm{II}}^{*}(t,\theta) = \sigma_{\theta\theta}(t,\theta)\sqrt{2\pi} = K_{\mathrm{I}}(t)\left[\frac{3}{4}\cos\left(\frac{\theta}{2}\right) + \frac{1}{4}\cos\left(\frac{3\theta}{2}\right)\right] + K_{\mathrm{II}}(t)\left[\frac{-3}{4}\sin\left(\frac{\theta}{2}\right) - \frac{3}{4}\sin\left(\frac{3\theta}{2}\right)\right]$$

$$k_{\mathrm{II}}^{*}(t,\theta) = \tau_{r\theta}(t,\theta)\sqrt{2\pi} = K_{\mathrm{I}}(t)\left[\frac{1}{4}\sin\left(\frac{\theta}{2}\right) + \frac{1}{4}\sin\left(\frac{3\theta}{2}\right)\right] + K_{\mathrm{II}}(t)\left[\frac{1}{4}\cos\left(\frac{\theta}{2}\right) + \frac{3}{4}\cos\left(\frac{3\theta}{2}\right)\right]$$
(5)

Since Eqs. (5) are dimensionally equivalent to stress intensity factors, in Eqs. (5) we define the virtual stress intensity factors k_{I}^{*} , k_{II}^{*} to assess the prospective angle θ for crack kinking (see Fig. 3). This assessment is performed via several criteria (reviewed below) that are based on k_{I}^{*} or k_{II}^{*} computed for different values of *t* and θ .

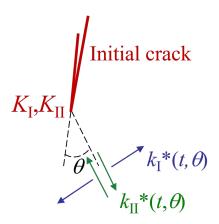


Figure 3: Sketch of the stress intensity factors associated with a virtual crack emanating from the initial crack.

Conceptually, some authors link k_{I}^{*} , k_{II}^{*} to a virtual infinitesimally-branched

crack emanating from the original crack with an angle θ [24]. It must be noted that negative values of k_{I}^{*} have no physical meaning since a negative k_{I}^{*} means that the normal stress field is compressive and the hypothetical crack faces overlap. Therefore, it should not be considered in the crack propagation. In this way, negative k_{I}^{*} are set to zero.

In general, under proportional loading, a crack kinks in a direction where the tensile normal stress field (mode I stress intensity factor k_I^*) is maximum. Furthermore, this direction coincides with the direction of k_{II}^* equal to zero, in accordance with the criterion of local symmetry [25], and with the direction of maximum Δk_I^* . Several criteria can be found in the literature following these observations such as the maximum tangential stress criterion [26], the maximum strain energy density criterion [27] and the maximum energy release rate [28].

Many authors have demonstrated that predicted angles given by the aforementioned criteria are very similar. It should be mentioned that these criteria can be modified in order to account for the effect of non-singular terms [29]. On the other hand, it has been verified that a crack can also propagate co-planar or mode II controlled at high mixed-mode loadings under certain circumstances [30]. However, this is not the general case. Therefore, we will assume that propagation is mode I controlled to simplify the study. Other types of propagation are out of the scope of this work.

Under nonproportional loading, the ratio of the stress intensity factor $K_{\rm I}/K_{\rm II}$ is not kept constant during the cycle as in proportional loading. Thus, it can be generally said that the direction of maximum $k_{\rm I}^*$ at different instants of a loading cycle ($k_{\rm I,max}^*$) is not kept constant during the cycle. Under these conditions, Hourlier [31] examined three potential directions of crack orientation: the direction corresponding to the absolute $k_{\rm I,max}^*$ (max($k_{\rm I}^*$)), the direction where $\Delta k_{\rm I}^*$ is maximum (max($\Delta k_{\rm I}^*$)) and the direction where the crack growth rate is maximum. In addition, Dubourg and Lamacq [32] proposed the direction where the effective range of the circumferential stress is maximum along the cycle. The criterion was applied to fretting fatigue problems showing a good agreement. On the other hand, an extension of the criterion of local symmetry for nonproportional loading, min(Δk_{II}^*), was proposed by Giner et al. [33], where the crack orientation is the direction for which the shear stress range at the crack tip is minimized, min(Δr) [34]. Lastly, Highsmith [35] observed that direction of crack orientation usually falls between the max(k_I^*) and max(Δk_I^*) criteria. In this way, Highsmith employed a crack driving force, Eq. (6), combining the influence of both parameters following the work by Hourlier et al. [31] and Walker [36]. In this way, the mean stress influence is introduced into the crack orientation criterion for materials that show this dependence. In Eq. (6), the parameter *w* weighs k_{Lmax}^* and Δk_I^* , thus defining which one dominates the direction of orientation. The crack orientation angle is the one for which the crack driving force is maximized:

$$\overline{\Delta k_l^{w^*}(\theta)} = k_{l,max}^{*}{}^{1-w}(\theta) \,\Delta k_{l,max}^{*}{}^{w}(\theta) \tag{6}$$

3. <u>Results</u>

The results are divided into five sections. The first three sections present the numerical crack path results for a phase angle of 0°, 90° and 180°. In each section, the numerical crack path is obtained for four different central crack inclinations (0°, 15°, 30° and 45°) while keeping constant the rest of parameters. Finally, the fourth and fifth sections address the influence of the displacement ratio and the first crack kink, respectively, for an initial centred crack inclined at 45°.

3.1. In-phase

When the loads are in phase, K_{II} remains zero during the loading cycle for any crack

inclination, and the crack grows coplanar to the initial crack as is shown in Fig. 4. Thus, crack behaviour is a pure mode I. As is shown in Fig. 5, the prospective directions θ predicted by the min(Δk_{II}^*), max(k_I^*) and max(Δk_I^*) criterion do not vary with time during the loading cycle due to the proportionality of loads. This direction is $\theta=0^\circ$ (defined as in Fig. 1), which is in line with experimental observations found in the literature for the case of $\beta=0^\circ$ and 45° [3,14,17].

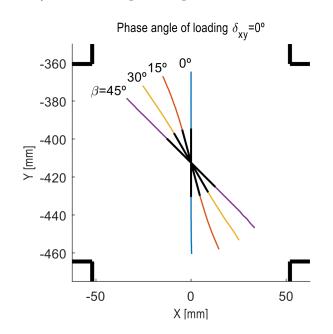


Figure 4: Numerical crack paths after 25 propagations for the four initial inclinations $\beta=0^{\circ}$, 15°, 30° and 45° with phase angle of loading 0° (initial crack in black) using the max(Δk_1^*) criterion.

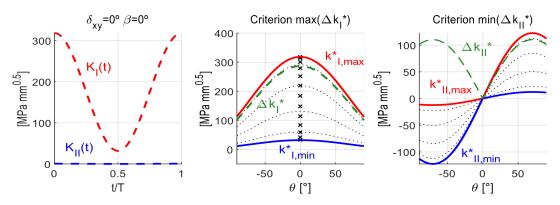


Figure 5: SIFs, $k_1^*(t,\theta)$ and $k_{II}^*(t,\theta)$ during a loading cycle for the initial centred crack for the case $\beta = 0^\circ$ and $\delta_{xy} = 0^\circ$.

3.2. Out-of-phase 180°

When the phase angle of loading is 180°, three crack behaviours are found depending on the initial crack inclination β . When the crack is aligned with the loading directions $(\beta=0^{\circ})$, K_{II} remains zero during the loading cycle. Therefore, the crack behaviour is a pure mode I and there is not crack kink. Furthermore, predicted crack paths agree with the experimental evidence found by Lee and Taylor [17].

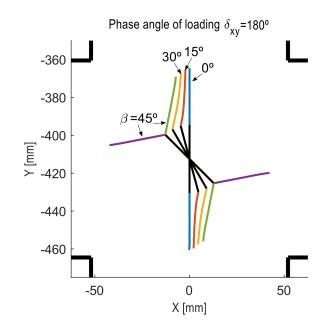


Figure 6: Numerical crack paths after 25 propagations for the four inclinations β with phase angle of loading 180° (initial crack in black) using the max(Δk_1^*) criterion.

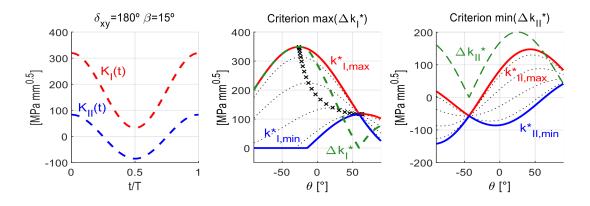


Figure 7: SIFs, $k_{I}^{*}(t,\theta)$ and $k_{II}^{*}(t,\theta)$ during a loading cycle for the initial centred crack for the case $\beta=15^{\circ}$ and $\delta_{xy}=180^{\circ}$.

When β is either 15° or 30°, the loading case is clearly non-proportional and mixed-mode (see Fig. 7 and 8). As is seen in Fig.7 and 8, the direction where k_1^* achieves its maximum (cross markers in subfigure for max(Δk_1^*) criterion) changes during the loading cycle. The predicted orientation by max(k_1^*) coincides with the direction of $\max(\Delta k_{I}^{*})$ for β equal to 15° and 30°. However, it is observed in Fig. 7 that $\min(\Delta k_{II}^{*})$ is zero and the predicted direction does not coincide with the direction predicted by the $\max(\Delta k_{I}^{*})$ criterion for both cases (see Fig. 7 and 8).

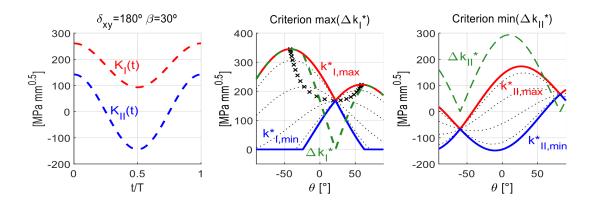


Figure 8: SIFs, $k_1^*(t,\theta)$ and $k_1^*(t,\theta)$ along a cycle for the initial centred crack for the case $\beta=30^\circ$ and $\delta_{xy}=180^\circ$.

When β is 45°, the loading case is again mixed-mode and non-proportional. However, in this case $K_{\rm I}$ does not vary during the loading cycle while $K_{\rm II}$ changes. As is shown in Fig. 9, there are two directions ($\theta=\pm50^{\circ}$) where $k_{\rm I}^*$ and $\Delta k_{\rm I}^*$ achieve their absolute maximum. Furthermore, min($\Delta k_{\rm II}^*$) is zero and its predicted direction ($\theta=\pm70.5^{\circ}$) does not coincide with the max($\Delta k_{\rm I}^*$) predicted direction. Therefore, the crack is expected to branch symmetrically into two cracks with respect to the initial crack.

This result was first observed by Qian et al. [4] and recently by Neerukatti et al. [5]. Qian et al. [4] observed experimentally that the crack initially bifurcates symmetrically into two cracks at 50°-60°. Within 1 mm, the crack bifurcates to 70° and finally propagates along the direction of axes. We point out that Lee and Taylor [17] only observed kinking of the crack into one of the branches. However, this fact may be consequence of misalignment of the specimen or local effects such as the microstructure at that region.

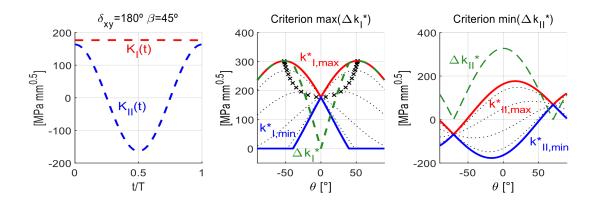


Figure 9: SIFs, $k_1^*(t,\theta)$ and $k_1^*(t,\theta)$ along a cycle for the initial centred crack for the case $\beta = 45^\circ$ and $\delta_{xy} = 180^\circ$.

3.3. Out-of-phase 90°

When the phase angle of loading is 90°, the crack path predicted is very close to the predicted crack path with phase angle of loading equal to 180°. Nevertheless, the predicted kink angles are smaller in this case. Mall and Perell [3] found experimentally less kinking in symmetrical bifurcated cracks under 90° phase angle of loading than in 180° phase angle of loading. As can be seen in Fig. 10, the crack path is straight for the initial crack aligned with the load axis, and symmetric branching is predicted for an initial crack with an inclination of 45°.

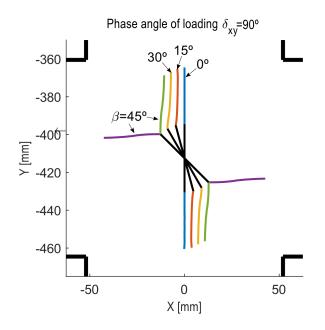


Figure 10: Numerical crack paths after 25 propagations for the four inclinations β with phase angle of loading 90° (initial crack in black) using the max(Δk_1^*) criterion.

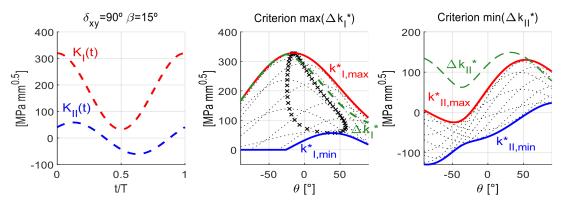


Figure 11: SIFs, $k_1^*(t,\theta)$ and $k_1^*(t,\theta)$ during a loading cycle for the initial centred crack for the case $\beta=15^\circ$ and $\delta_{xy}=90^\circ$.

The differences found between 180° and 90° phase angles of loading are in the k_1^* and k_{II}^* curves along a cycle. As is shown in Fig. 11, relative $k_{I,max}^*$ values during a cycle (cross markers in subfigures for max(Δk_1^*) criterion) follow a loop shape. Furthermore, in comparison with the same inclination case of phase angle of loading equal to 180°, the angle predicted by min(Δk_{II}^*) (θ =-36.5°) is less sharp (for δ_{xy} =180° it was θ =-43.5°), and it does not coincide with the angle predicted by max(Δk_I^*) (θ =-26.25°).

These facts are more pronounced when the initial inclination is 45° as is shown in Fig. 12. As in the case of 180° phase angle of loading, symmetric branching is predicted on both crack tips when β =45°. Mall and Perell [3] observed experimentally the same fact for an initial crack inclined 45° with phase angle of loading equal to 90°. However, Neerukatti et al. [5] observed the initial crack kinking only in one branch although the major crack tried to split unsuccessfully to secondary cracks.

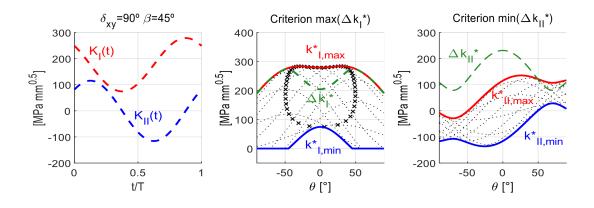


Figure 12: SIFs, $k_1^*(t,\theta)$ and $k_{II}^*(t,\theta)$ during a loading cycle for the initial centred crack for the case β =45° and δ_{xy} =90°.

Fig. 13 displays the predicted crack paths at one of the crack tips (the behaviour at the other crack tip is symmetric) for the different orientation criteria: $\max(k_1^*)$, $\min(\Delta k_{II}^*)$, $\max(\Delta k_1^*)$ and $\max(\Delta k_1^{w*})$ (*w*=0.3 and 0.7) for the case β =45° and δ_{xy} =90°. It is evident that significant differences can be found between the predicted crack paths. It is shown that the crack predicted by the criterion $\max(k_1^*)$ is a straight line. The crack paths predicted by $\min(\Delta k_{II}^*)$ and $\max(\Delta k_1^*)$ are different from the beginning, but the crack path predicted by $\max(\Delta k_1^*)$ gets close to the crack path predicted by $\min(\Delta k_{II}^*)$ as the crack grows. In addition, it is observed that the approach proposed by Highsmith [35] can be employed to fit the predicted crack in cases for which the experimental crack lies between the results obtained by $\max(\Delta k_1^*)$ and $\max(k_1^*)$ criterion.

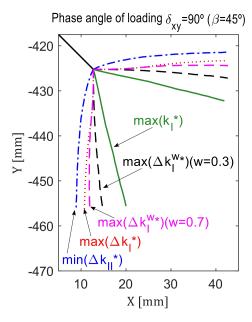


Figure 13: Numerical crack paths after 25 propagations for β =45° and δ_{xy} =90° predicted by the orientation criteria max(k_{I}^{*}), min(Δk_{II}^{*}), max(Δk_{I}^{w*}) (w=0.3 and 0.7) and max(Δk_{I}^{*}). Initial inclined crack: solid black line.

Figure 14 shows the predicted crack paths at one of the crack tips (predicted crack paths for the other crack tip are symmetric) with $\max(k_{\rm I}^*)$, $\min(\Delta k_{\rm II}^*)$ and $\max(\Delta k_{\rm I}^*)$ for β =45° and δ_{xy} =180°. Again, significant differences can be observed between the predicted crack paths. The differences are similar to those found for the δ_{xy} =90° case. The crack path predicted by $\max(k_{\rm I}^*)$ is again a straight line. In addition, the predicted bifurcation angle is greater for the $\min(\Delta k_{\rm II}^*)$ criterion than for the angle predicted by $\max(\Delta k_{\rm I}^*)$. Experimental crack paths observed in [3–5] with phase angle of loading equal to 180° are similar to the predictions obtained with $\min(\Delta k_{\rm II}^*)$ and $\max(\Delta k_{\rm I}^*)$. The shape of the experimental crack is closer to the predictions obtained by the $\min(\Delta k_{\rm II}^*)$ criterion. Further investigations by varying specimen dimensions and loads are necessary to confirm this point.

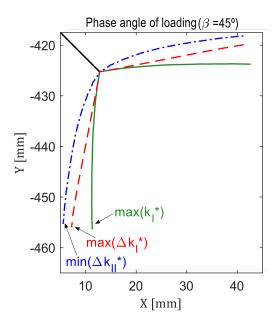


Figure 14: Numerical crack path after 25 propagations for β =45° and δ_{xy} =180° predicted by the orientation criteria $\max(k_{I}^{*}), \min(\Delta k_{II}^{*})$ and $\max(\Delta k_{I}^{*})$. Initial inclined crack: solid black line.

Mall and Perel [3] observed crack bifurcation from an initial crack inclined 45° under phase angle of loading equal to 180° and 90° and co-planar growth under equibiaxial in-phase loading. Fig. 15 shows a picture of the experimental crack paths described above, published in [3]. In qualitative terms, it is observed a good correlation with the predicted crack paths shown in Fig. 13 and 14 with the criterion of min(Δk_{II}^*) and max(Δk_{I}^*). However, it must be noted that the geometry and material may relevantly influence the crack path. It cannot be concluded which criterion has a better agreement with the experimental evidence.

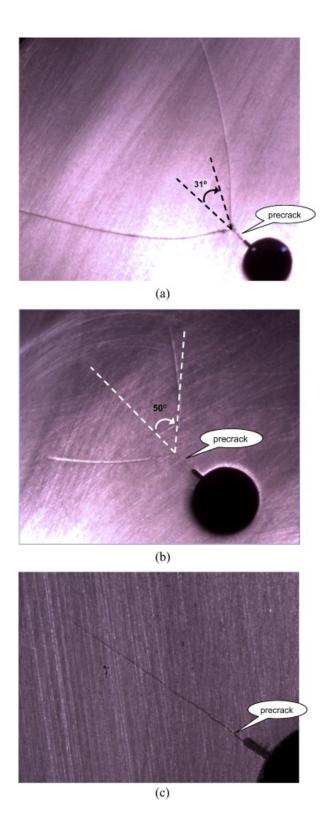


Figure 15: Experimental evidence found by Mall and Perel [3] (reproduced with permission of Elsevier) for cracks originating from a precrack inclined 45° with the loading axes with phase difference (a) 90°, (b) 180° and (c) 0°.

On the other hand, Qian et al. [4] showed that the shear stress range in mode II stress intensity factor is almost zero after the bifurcation of the crack in 4 branches when

the phase angle of loading is 180°. Fig. 16 shows the mode I and mode II stress intensity factor ranges (ΔK_I and ΔK_{II}) along the crack path predicted by the orientation criteria max(k_I^*), min(Δk_{II}^*) and max(Δk_I^*) for the case β =45° and δ_{xy} =180°. As can be seen, ΔK_{II} achieves a value close to zero after few propagations for the path predicted by the min(Δk_{II}^*) criterion. This condition takes longer to be achieved by the max(Δk_I^*) criterion, whereas it is not achieved by the max(k_I^*) criterion. This again suggests that the min(Δk_{II}^*) captures in a better way the mechanical behaviour governing crack orientation, as was commented by Giner et al. in [33], for the analogous min($\Delta \tau$) criterion.

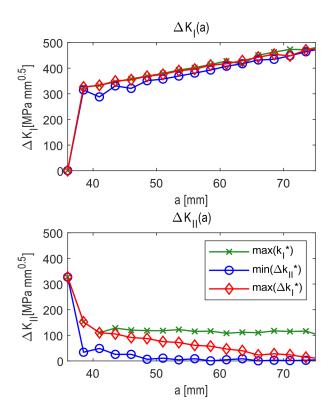


Figure 16: Mode I stress intensity factor range (top) and mode II stress intensity factor range (bottom) vs. crack length for β =45° and δ_{xy} =180° predicted by the orientation criteria max(k_1 *), min(Δk_{II} *) and max(Δk_I *).

3.4. Displacement ratio

In the previous sections, the displacement ratio applied in both axes is kept constant in all the cases ($R_d = 0.1$). In this section, the influence of the displacement ratio of the

displacement-controlled loads applied at both arms on the first crack orientation is assessed numerically. The case analyzed corresponds to an inclination β =45° and two outof-phase loadings: 90° and 180°. The same displacement ratio is applied on both arms. Four different orientation criteria are applied: min(Δk_{II}^*), max(Δk_{I}^*), max(k_{I}^*) and max(Δk_{I}^{w*}). The studied displacement ratio interval ranges from -1 to 0.8.

Figure 17 shows the predicted crack orientation angle against the displacement ratio R_d , showing large differences depending on the orientation criteria. In general, all the applied criteria predict symmetric branching with respect to the initial crack direction, except the max(k_1 *) criterion for the case $\delta_{xy} = 90^\circ$ and displacement ratio higher than 0.4. We point out that Fig. 17 only shows the predicted angle in one of the bifurcated branches. It is important to remark that the criterion min(Δk_{II} *) leads to an angle prediction that is independent of R_d . On the contrary, and for the out-of-phase 90°, the criterion max(k_I *) predicts no kinking when the displacement ratio is above 0.4. However, when the displacement ratio is below 0.4, max(Δk_I *) tends to predict the same direction as the max(k_I *) criterion. In addition, it can be observed that, as the parameter *w* increases, the angle predicted by the max(Δk_I ^w*) criterion is closer to the direction predicted by the max(Δk_I *) criterion.

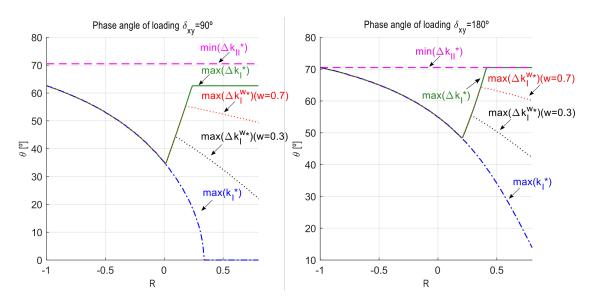


Figure 17: Bifurcation angle predicted at the crack tip of the initial inclined crack (β =45°) versus displacement ratio

applied on both arms when the phase angle of loading is 90° and 180° .

3.5. Phase angle of loading

In this section, we analyze the effect of phase of loading for the case β =45° and $R_d = 0.1$ on both arms. Similar to the previous section, different criteria are applied to predict the crack propagation of a straight initial crack of length 36 mm. Fig. 18 shows the predicted crack orientation angle against the phase angle for the outlined case. The parameter *w* is set to 0.3 for the calculation of the max(Δk_I^{w*}) criterion. As can be seen, all criteria predict that the crack will propagate without kinking for small phase loading angles. In addition, all criteria predict bifurcation above a certain value of phase angle of loading. It is interesting to observe that crack bifurcation is predicted abruptly after a phase angle of loading of about 40° for the criterion of min(Δk_{II}^*), predicting a bifurcation angle of 70.5° that is independent of the phase loading angle.

The bifurcation angles predicted by the rest of criteria increase with the phase angle in a smooth way. Note that the phase angle value that triggers bifurcation is greater than 50° for the rest of criteria. Further experimental tests should be carried out to compare these predictions.

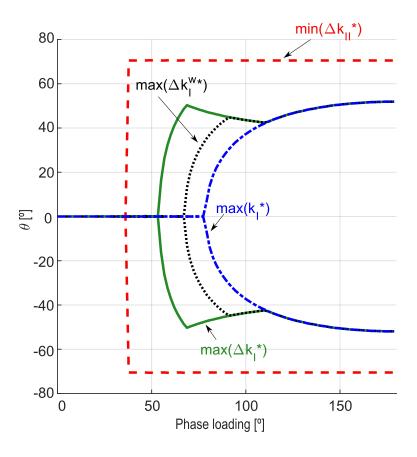


Figure 18: Bifurcation angle predicted at the crack tip of the initial inclined crack (β =45°) versus phase angle of loading applied on both arms with a displacement ratio equal to 0.1.

4. Conclusions

Crack propagation has been numerically analysed for a cruciform specimen under out-ofphase biaxial fatigue loads. The influence of the phase angle of loading and displacement ratio has been assessed using XFEM and applying different criteria found in the literature for non-proportional loading. A parametric study has been carried out thanks to the advantages of XFEM. It enables the study of the effect of out-of-phase fatigue biaxial loads and initial crack inclination on crack paths.

In the case of either initial cracks aligned with a load direction or in-phase loading, cracks do not change the initial orientation. In the cases of 90° and 180° phase loading, an initial crack inclined 45° to the load direction can bifurcate into two cracks growing

symmetrically with respect to the initial crack plane. The numerical results agree with the experimental observations found in the literature. It can be concluded that crack paths predicted using different orientation criteria, such as $\max(\Delta k_{I}^{*})$, $\max(k_{I}^{*})$ and $\min(\Delta k_{II}^{*})$, can be significant different from each other. Further experimental testing should be carried out in order to confirm the numerical predictions discussed in this research.

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